

# Image formation

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370: Intro to Computer Vision

Subhransu Maji

Feb 13 & 18

# Overview

## The pinhole projection model

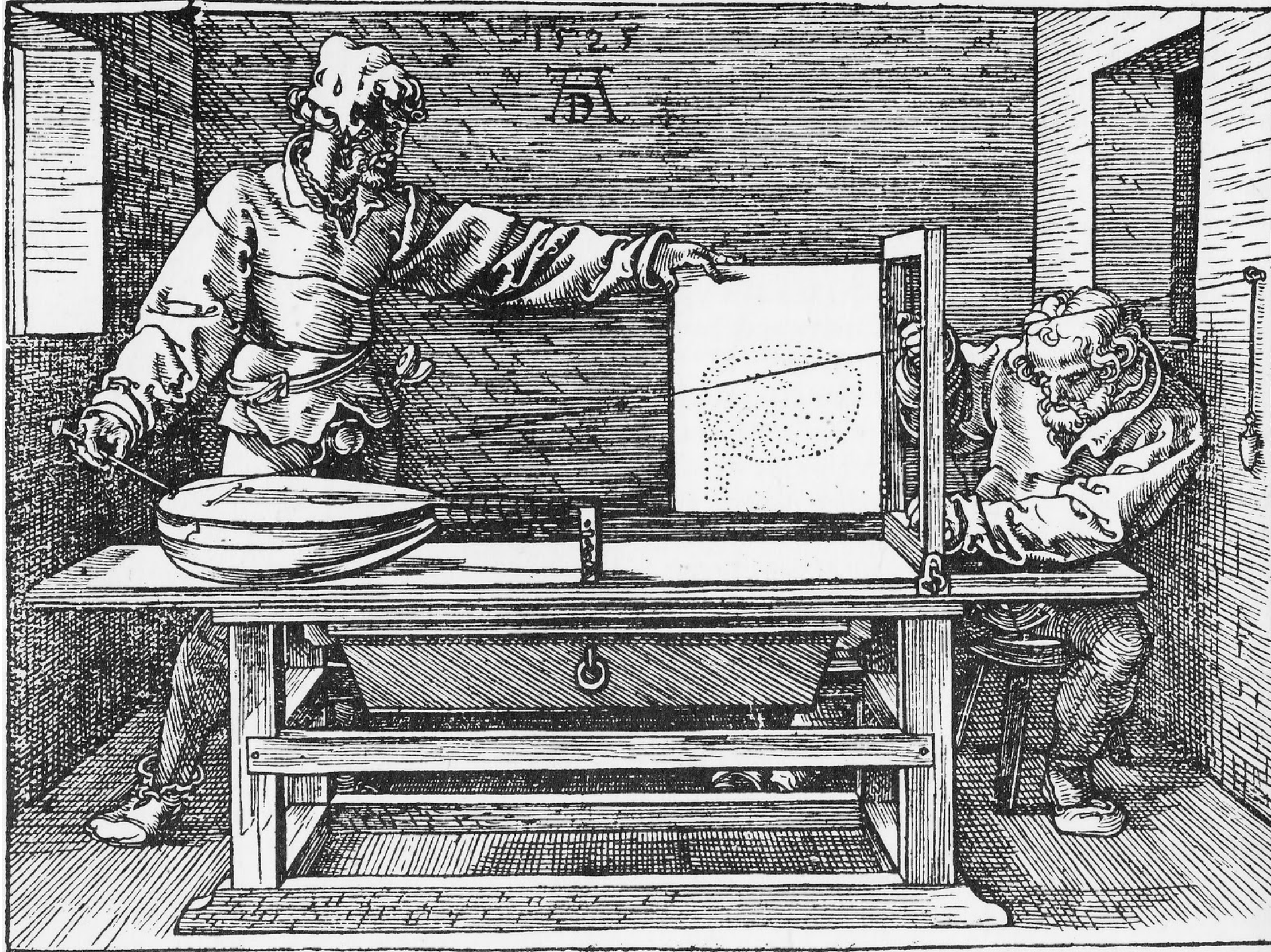
- Qualitative properties

## Cameras with lenses

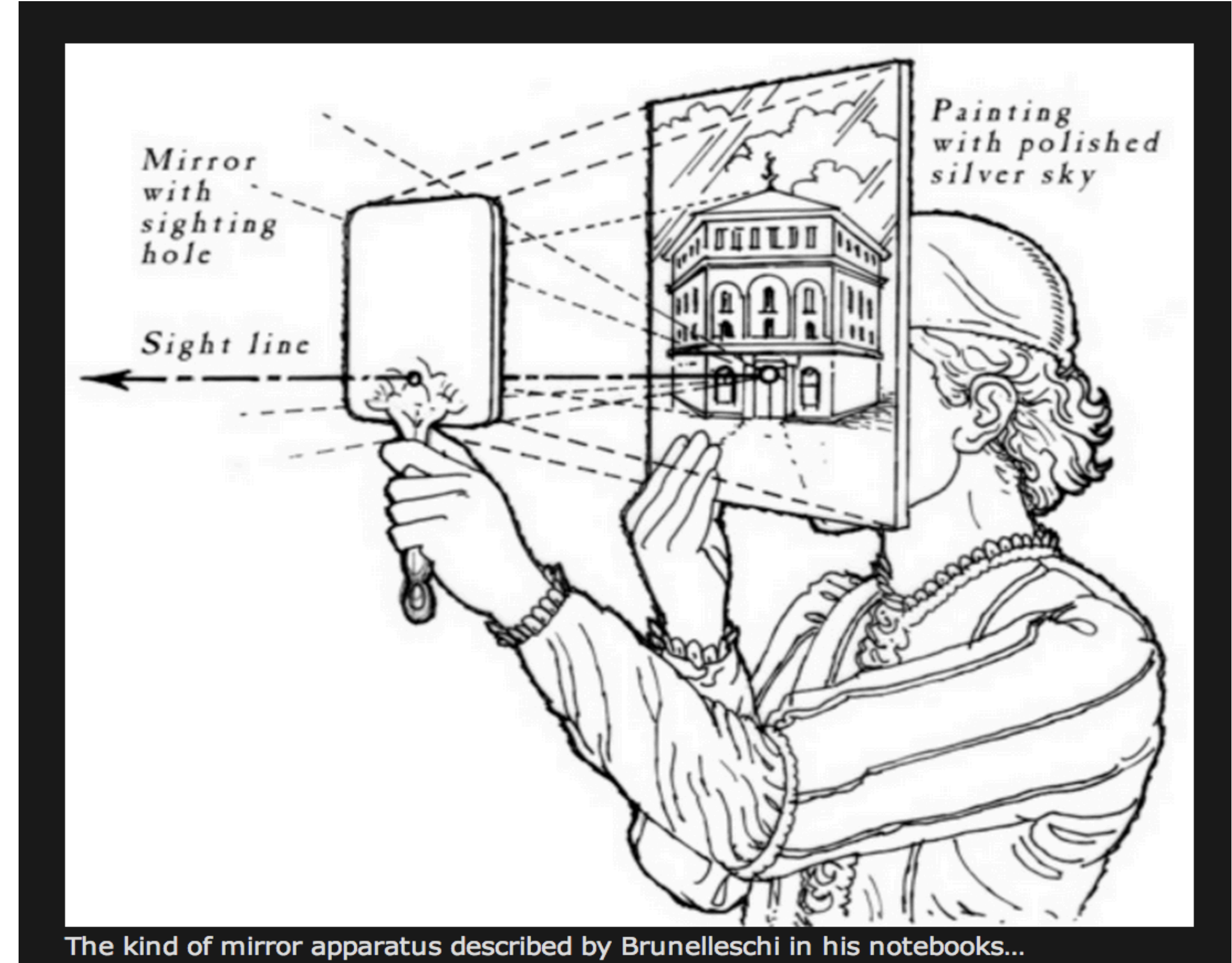
- Depth of focus
- Field of view
- Lens aberrations



# Cameras



Albrecht Dürer early 1500s

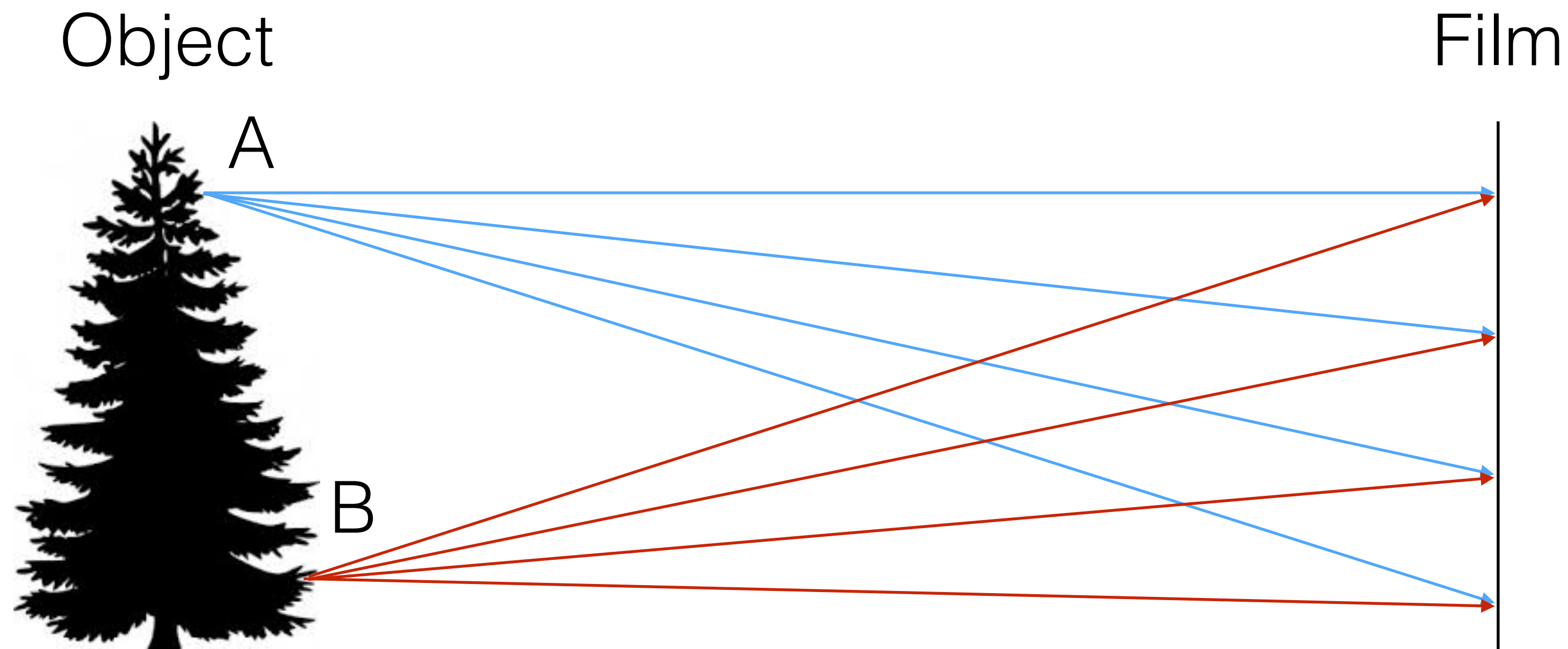


The kind of mirror apparatus described by Brunelleschi in his notebooks...

Brunelleschi, early 1400s



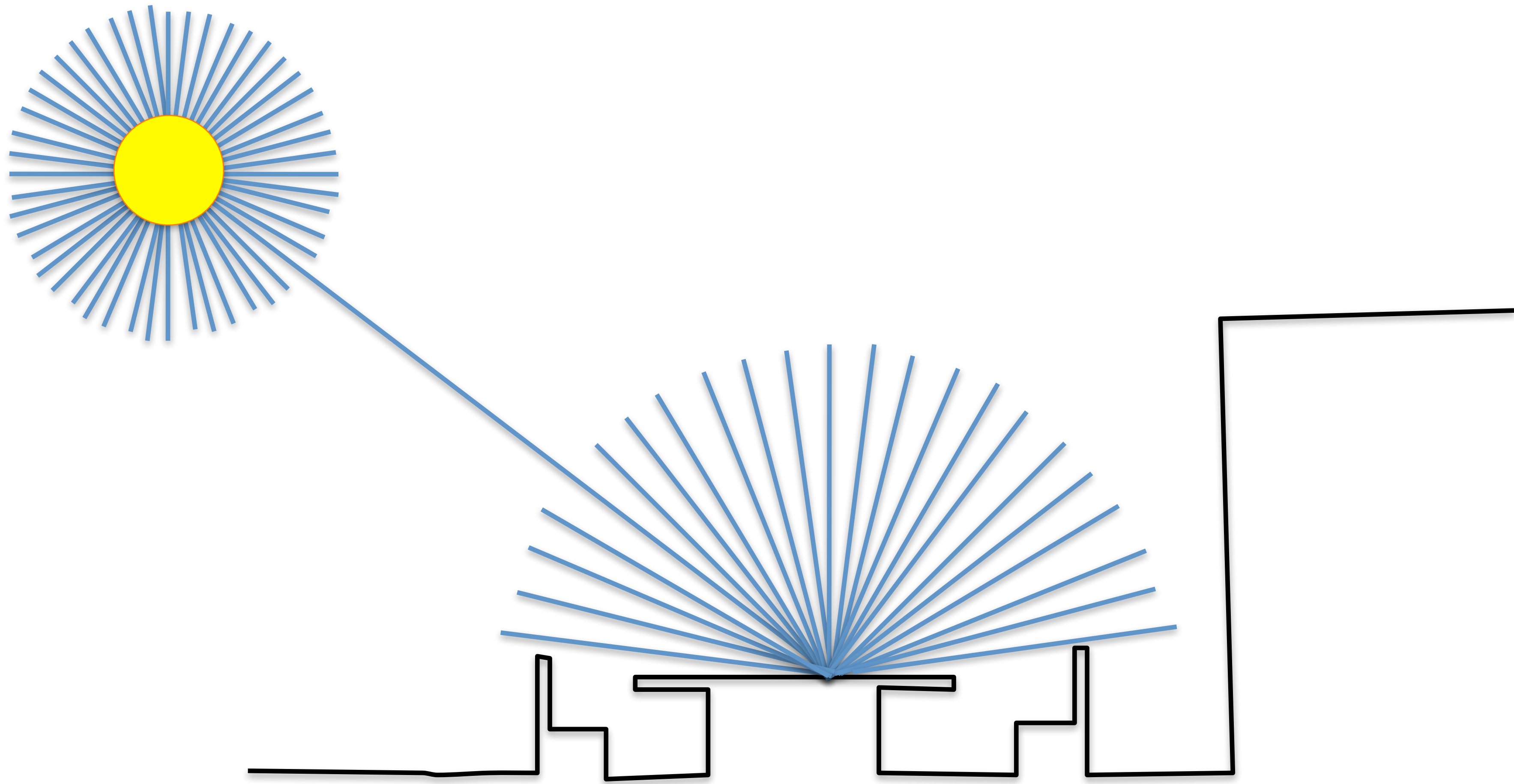
# Lets design a camera



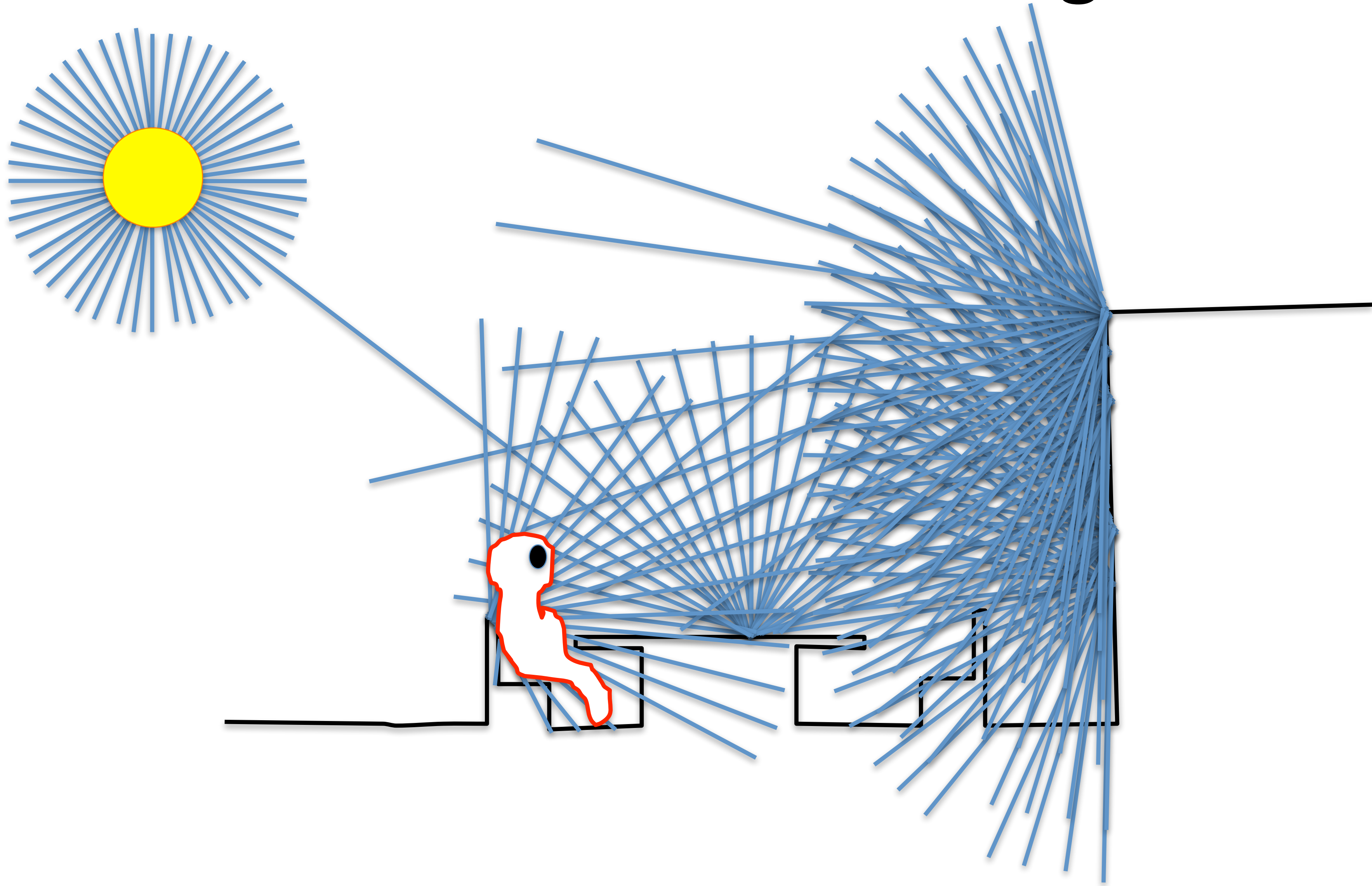
Let's put a film in front of an object

**Question:** What image do we expect on the film?

# The structure of ambient light

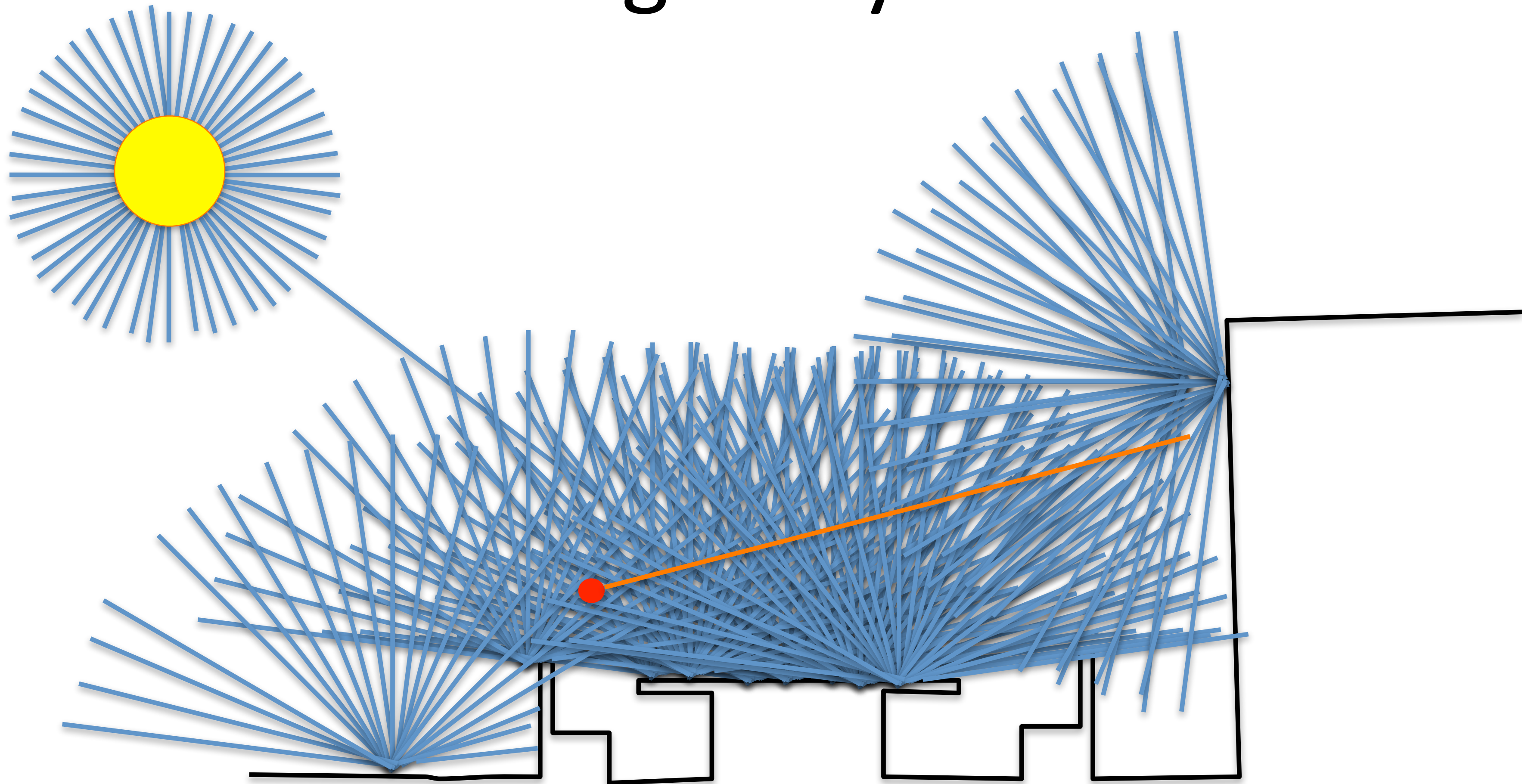


# The structure of ambient light



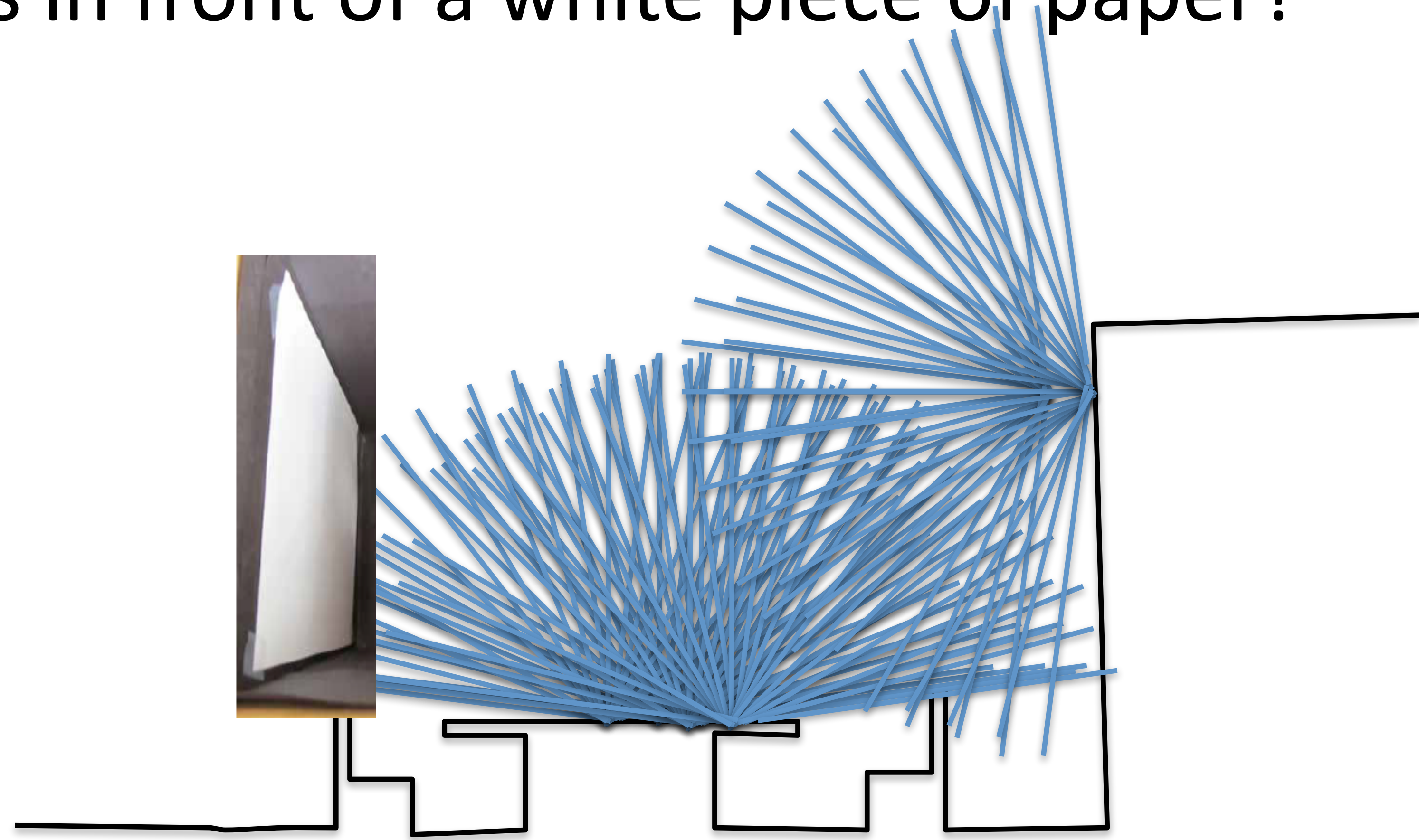


# All light rays



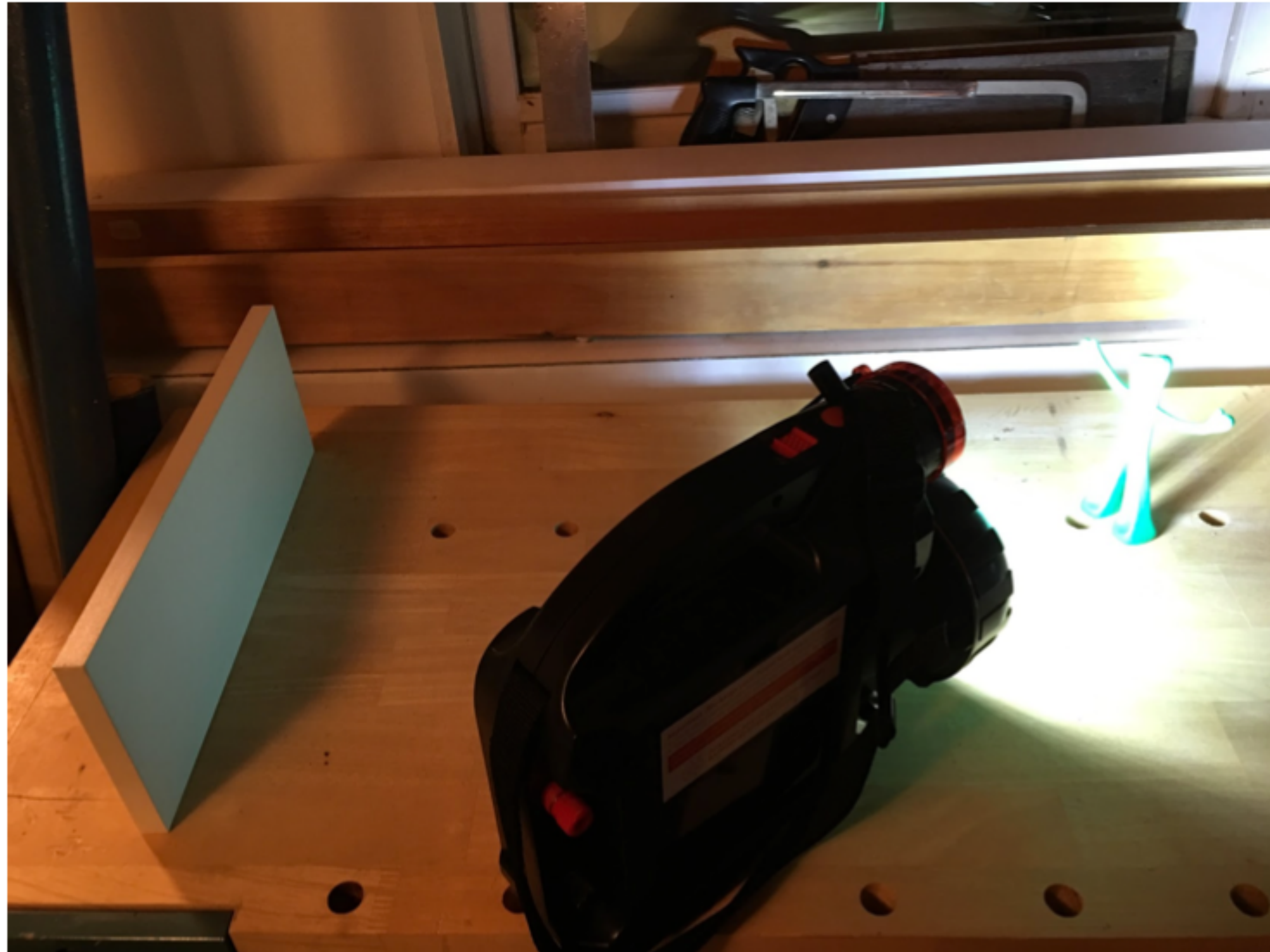


# Why don't we generate an image when an object is in front of a white piece of paper?



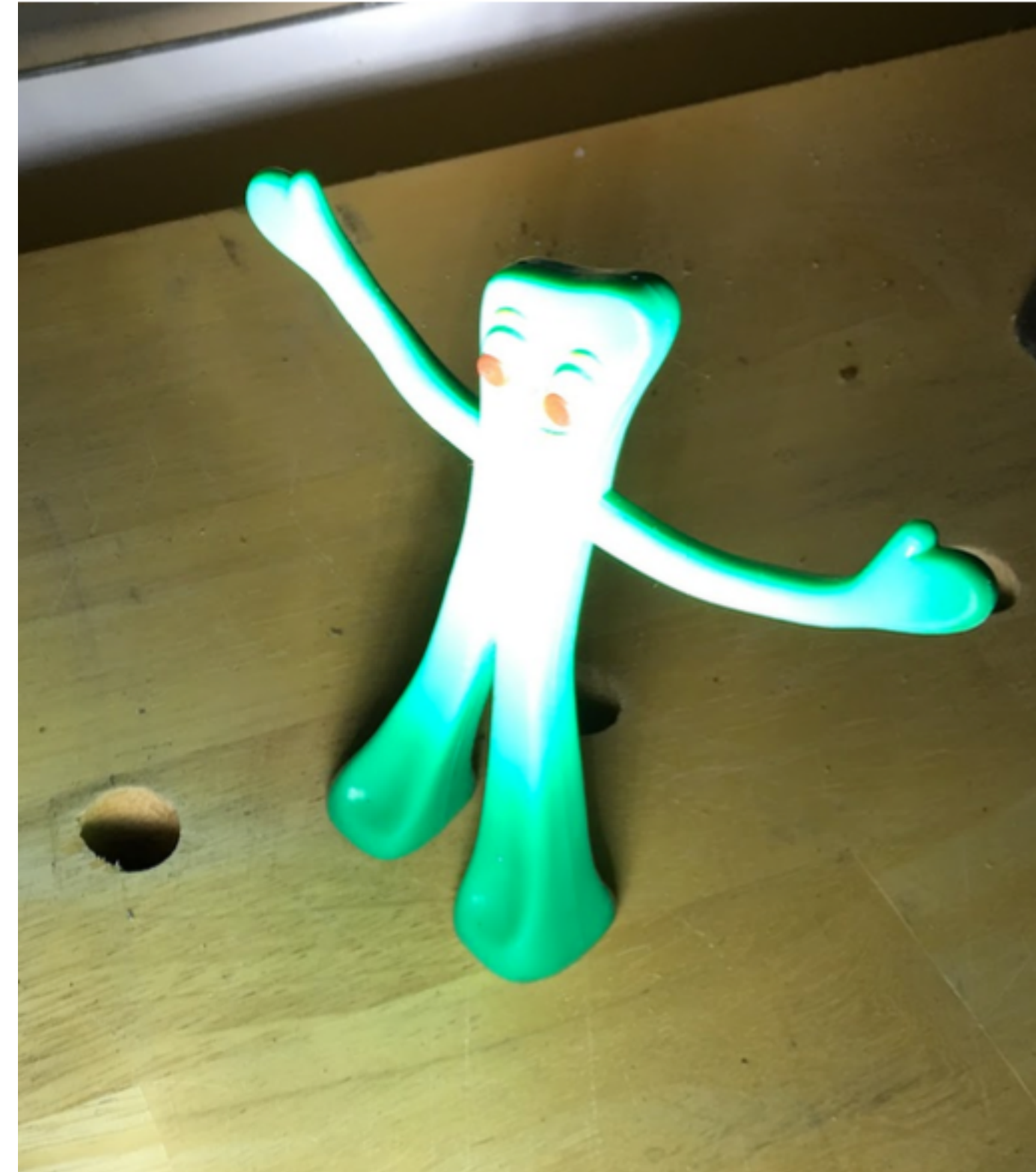
Why is there no picture appearing on the paper?

Let's check, do we get an image?





Let's check, do we get an image? No

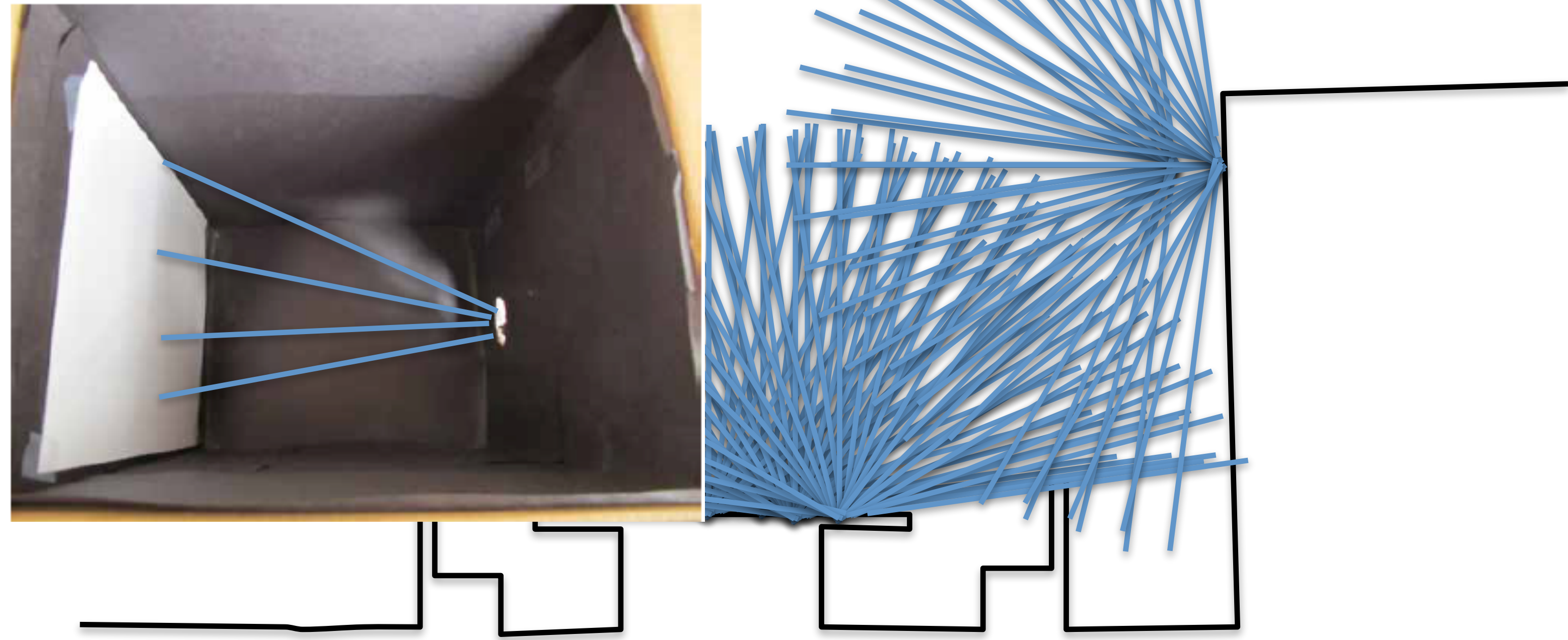




To make an image, we need to have only a subset  
of all the rays strike the sensor or surface

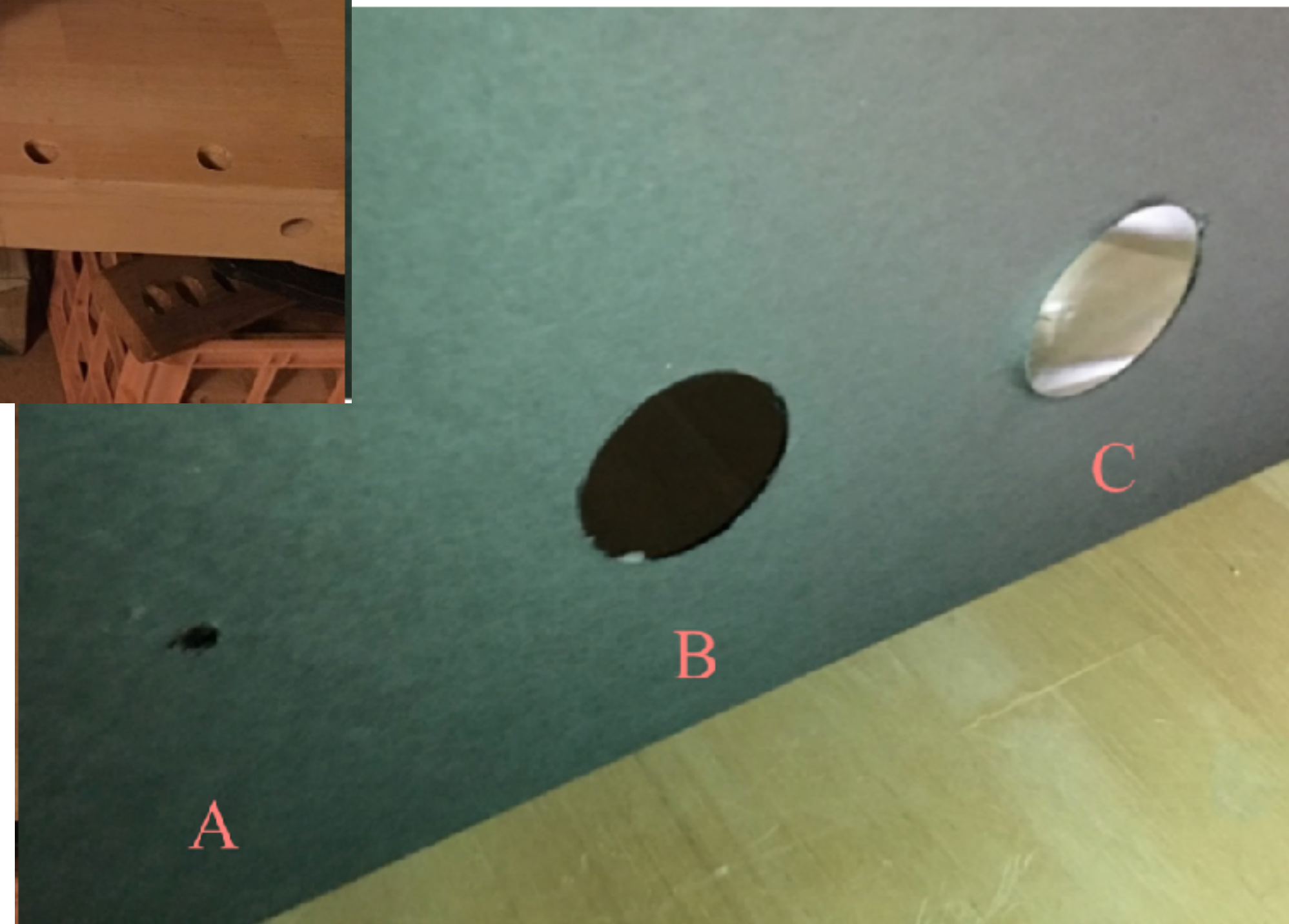
The camera obscura

The pinhole camera





Let's try putting different occluders in between the object and the sensing plane

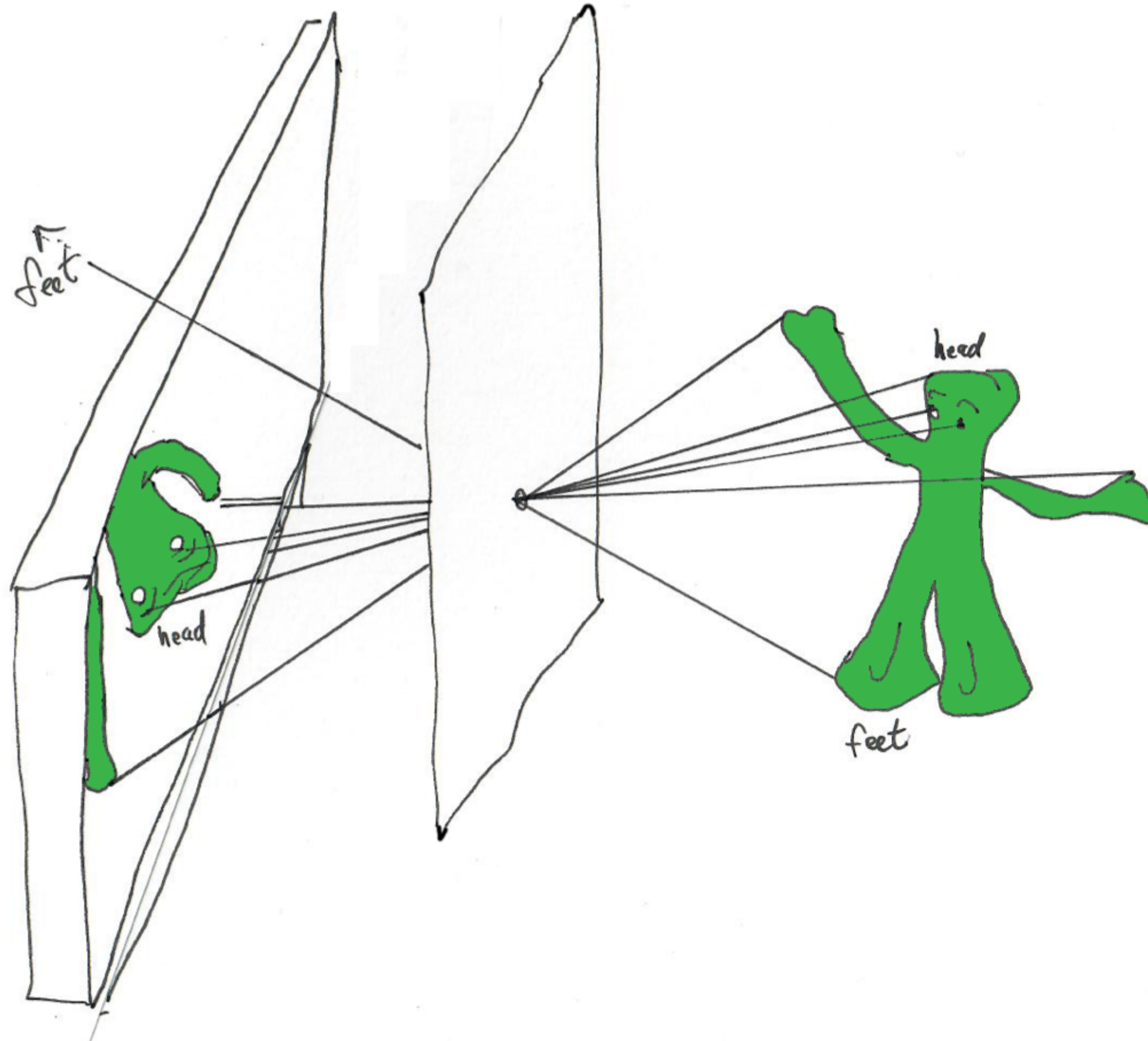




light on wall past pinhole

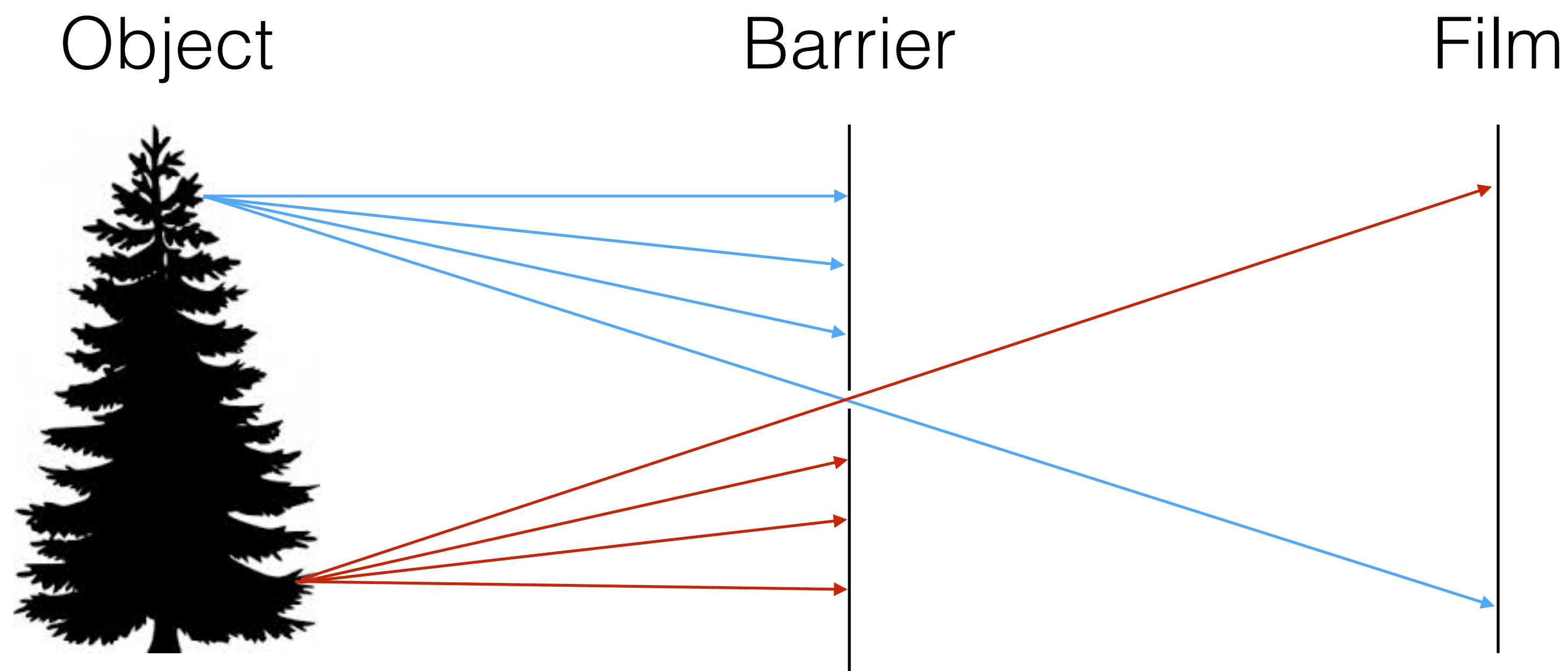


image is inverted



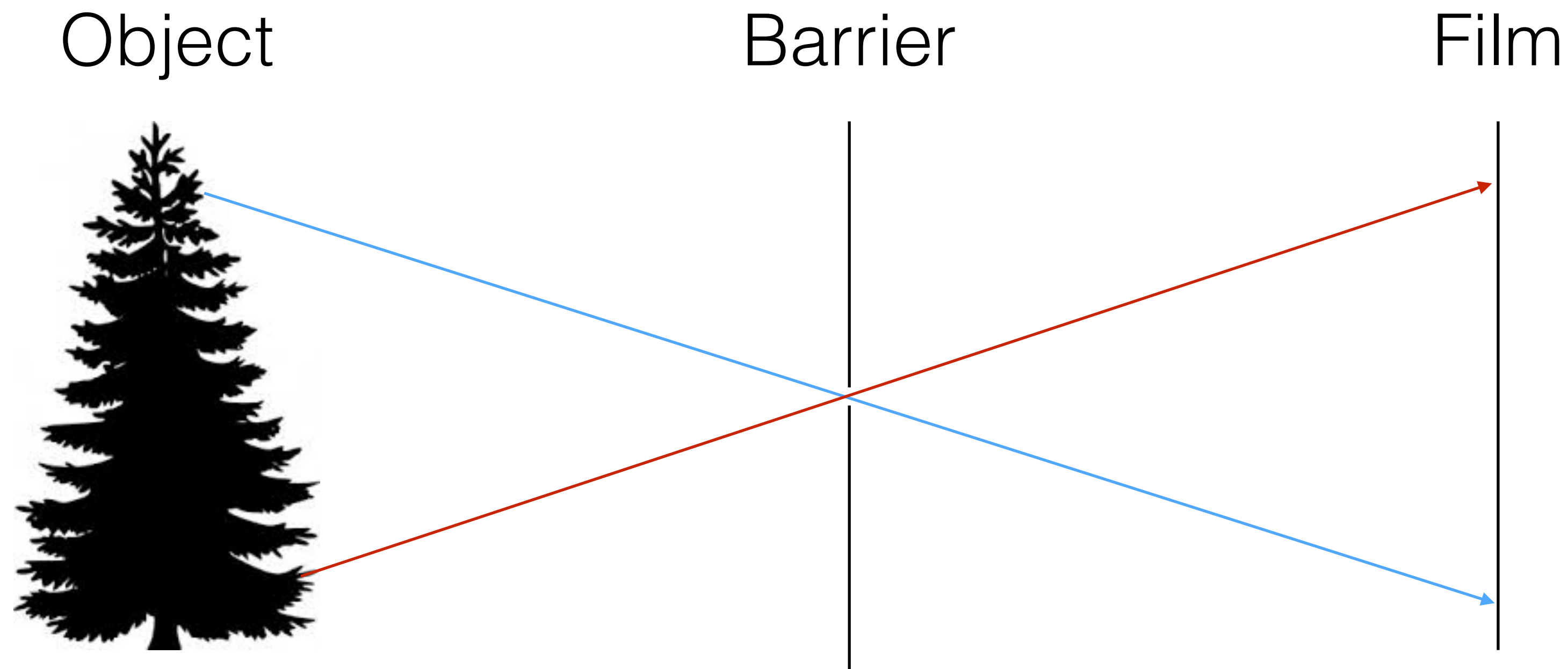


# Pinhole camera



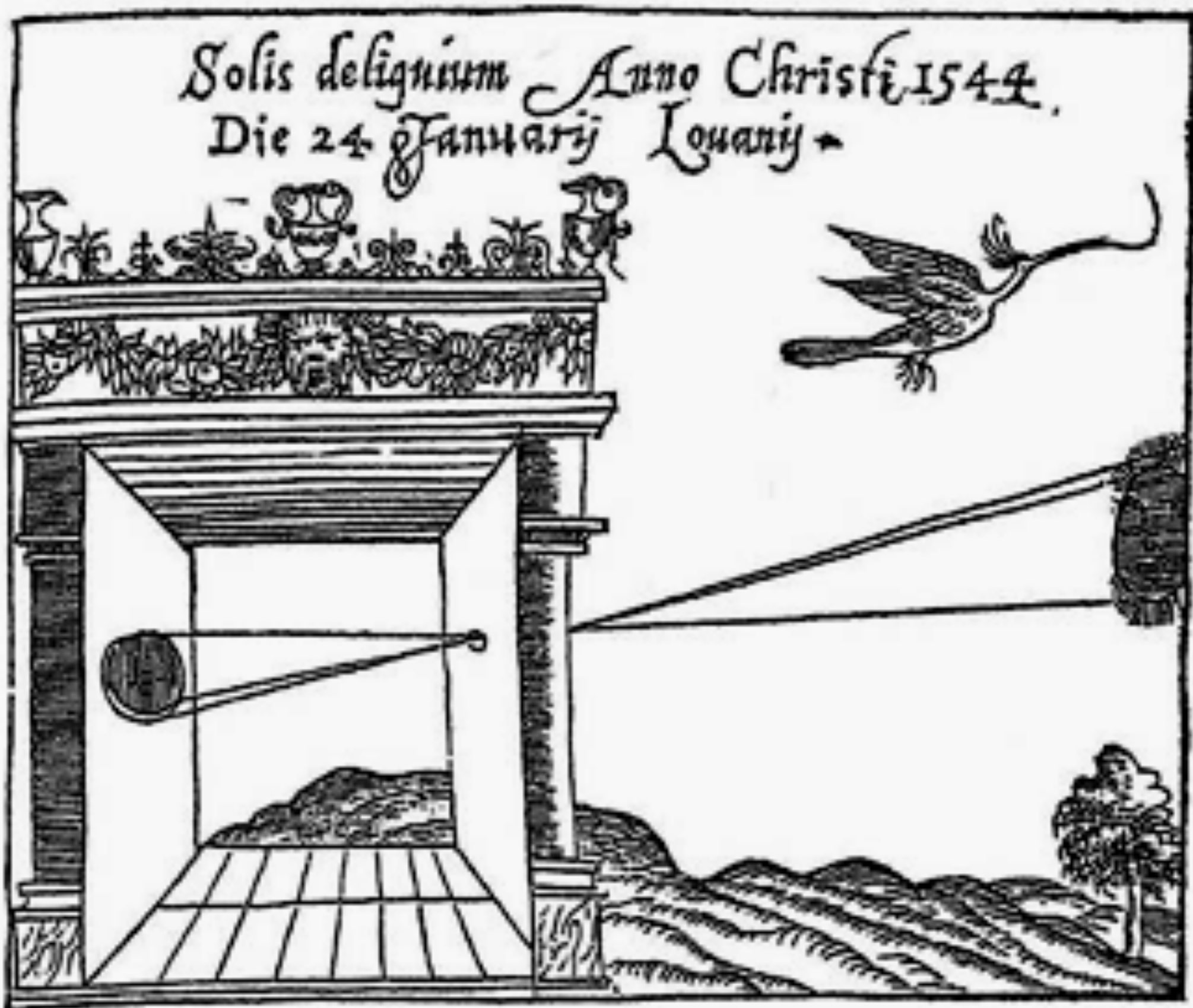
Add a barrier to block of most rays

# Pinhole camera



- Captures pencil of rays - all rays through a single point: aperture, center of projection, focal point, camera center
- The image is formed on the image plane

# Camera obscura



Gemma Frisius, 1558

Basic principle known to Mozi (470-390 BCE),  
Aristotle (384-322 BCE)

Drawing aids for artists: described by Leonardo Da  
Vinci (1452-1519 AD)

“Camera obscura” Latin for “darkened room”



# Pinhole cameras are everywhere



**Tree shadow during a solar eclipse**

photo credit: Nils van der Burg

<http://www.physicstogo.org/index.cfm>



# Accidental pinhole cameras

My hotel room,  
contrast enhanced.



The view from my window



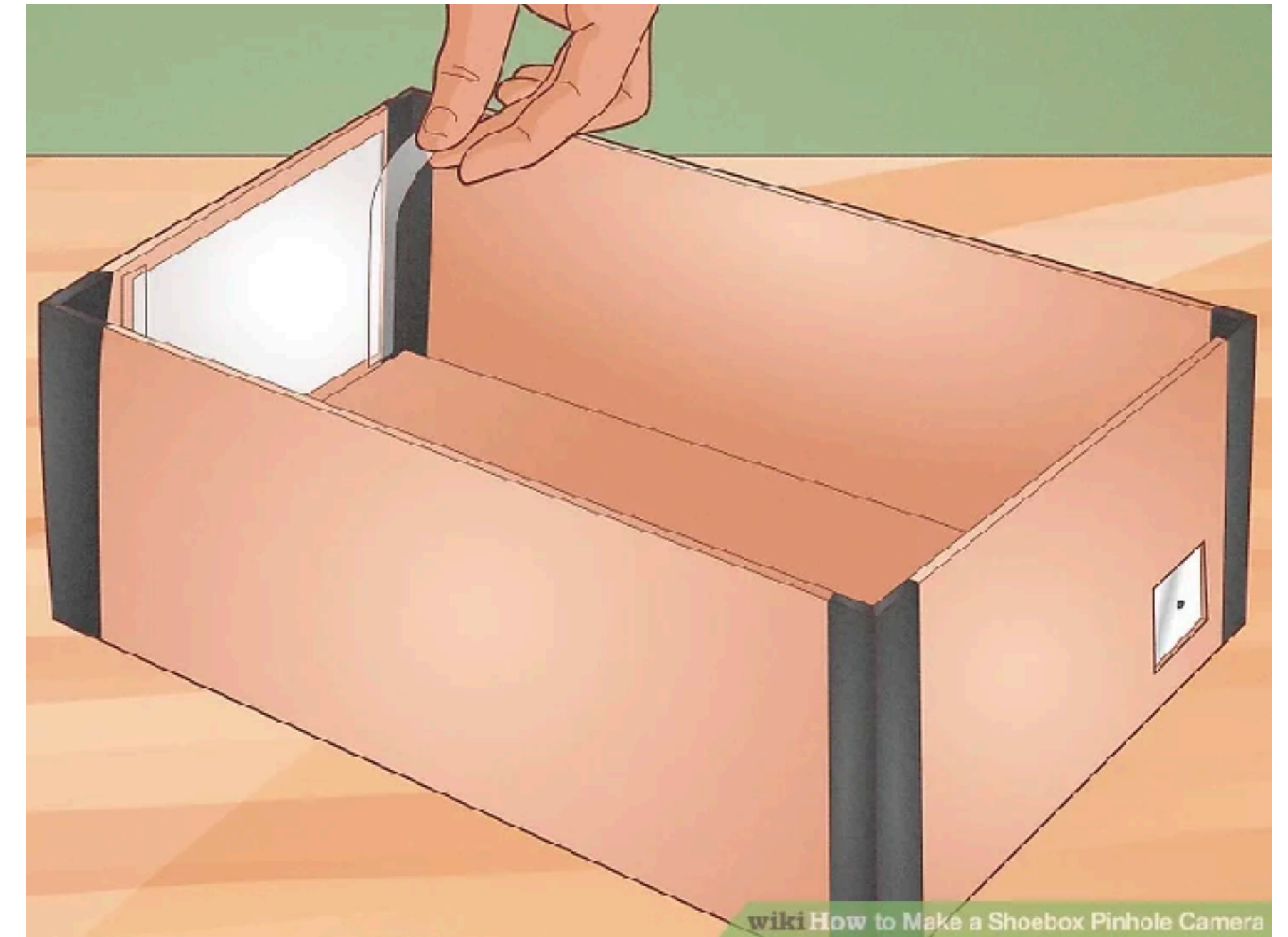
Accidental pinholes produce images that are  
unnoticed or misinterpreted as shadows

A. Torralba and W. Freeman, [Accidental Pinhole and Pinspeck Cameras](#), CVPR 2012

# Home-made pinhole camera



<https://kids.nationalgeographic.com/books/article/pinhole-camera>

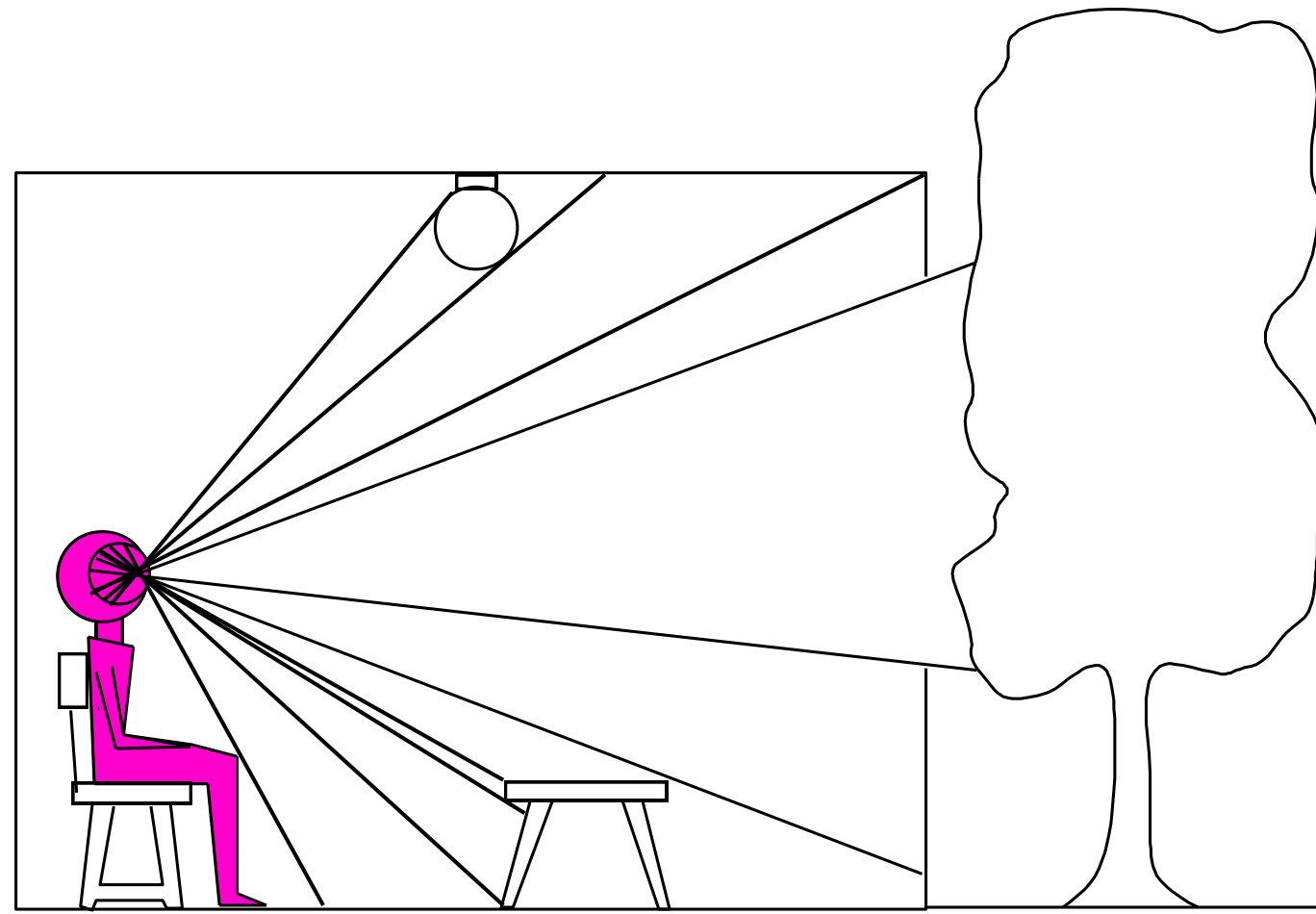


<https://www.wikihow.com/Make-a-Shoebox-Pinhole-Camera>



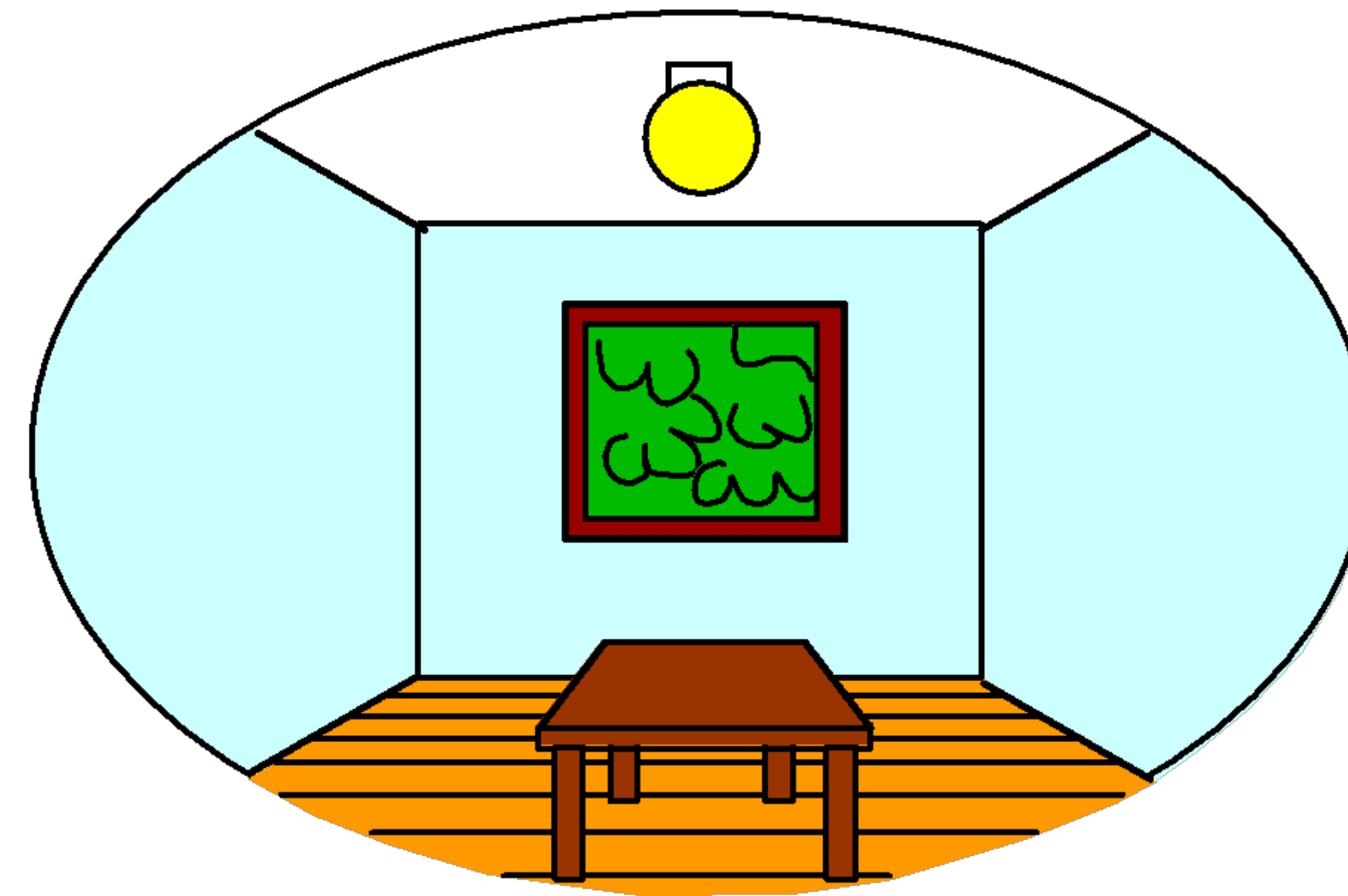
# Dimensionality reduction: 3D to 2D

3D world



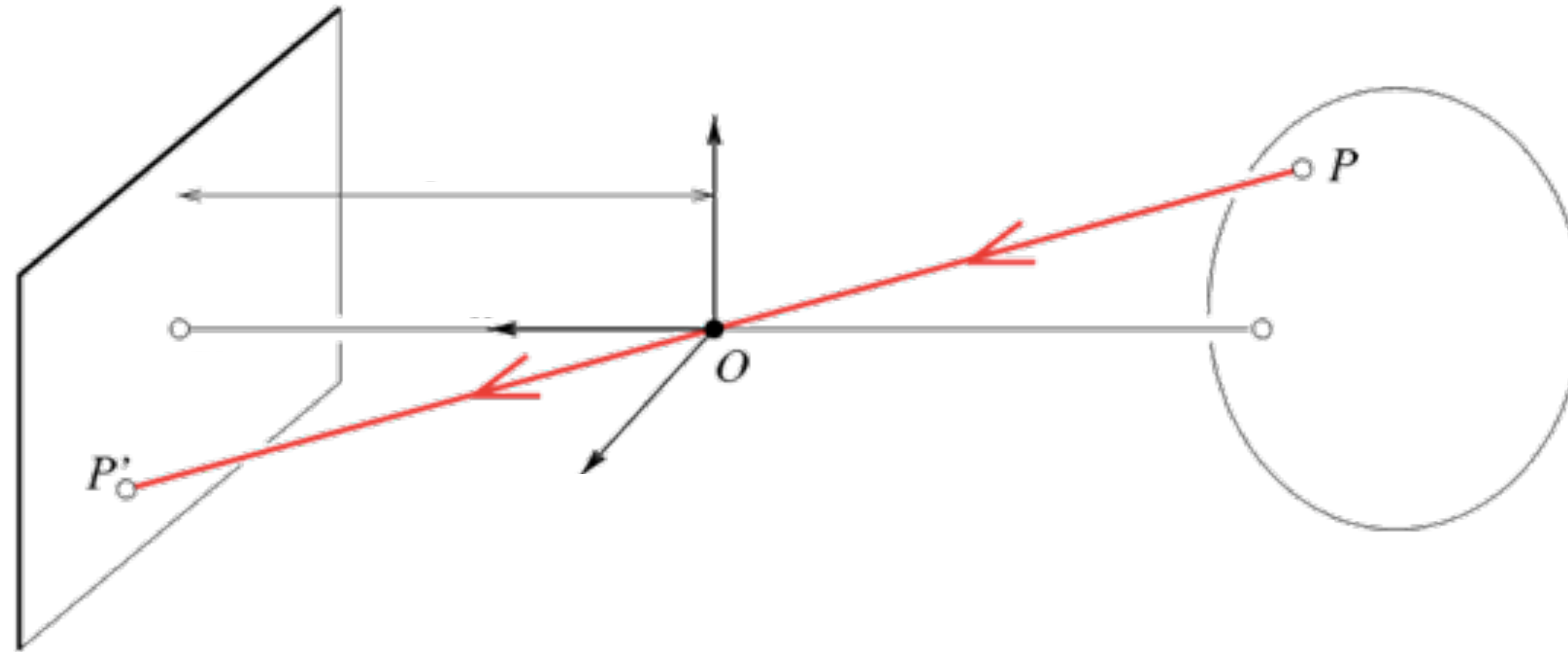
Point of observation

2D image



- **What is preserved?**
  - Straight lines, incidence
- **What is not preserved?**
  - Angles, lengths

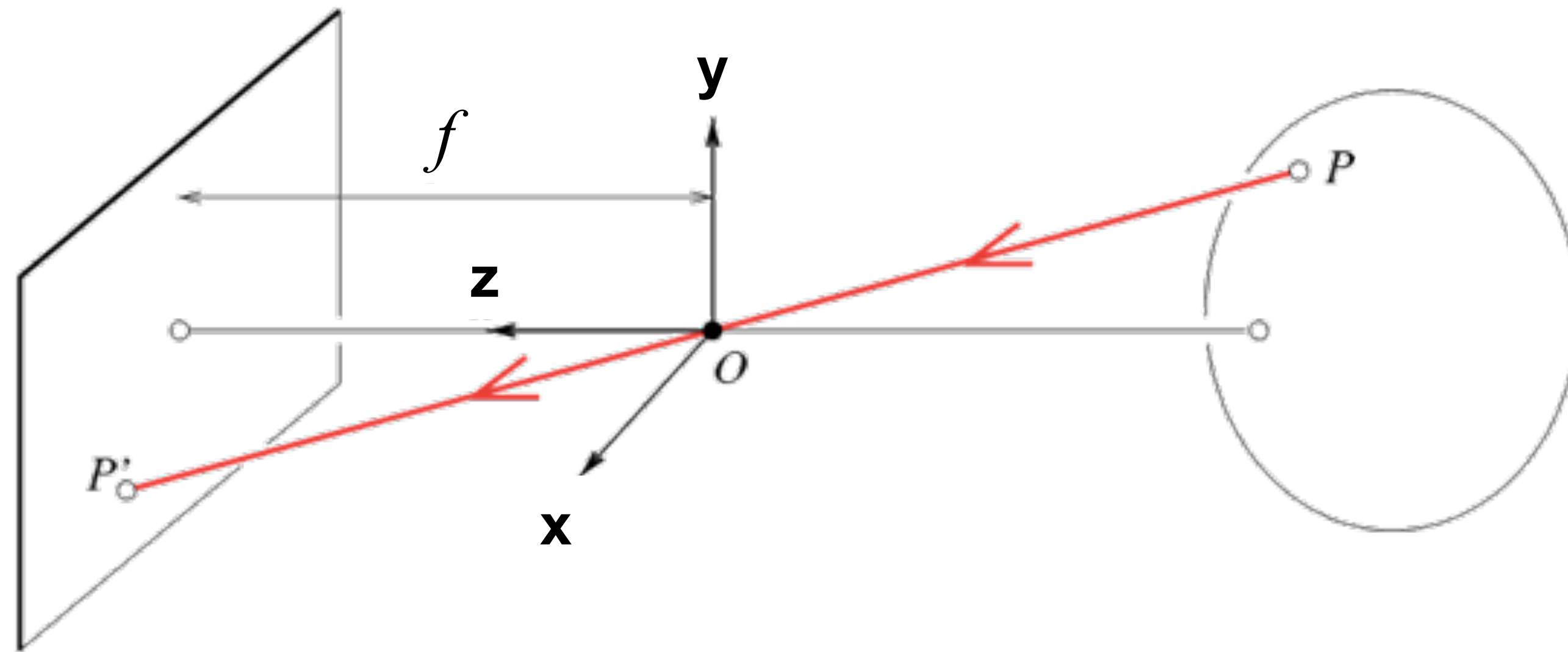
# Modeling projection



To compute the projection  $P'$  of a scene point  $P$ , form a **visual ray** connection  $P$  to the camera center  $O$  and find where it intersects the image plane

- All scene points that lie on this visual ray have the same projection on the image

# Modeling projection



## The coordinate system

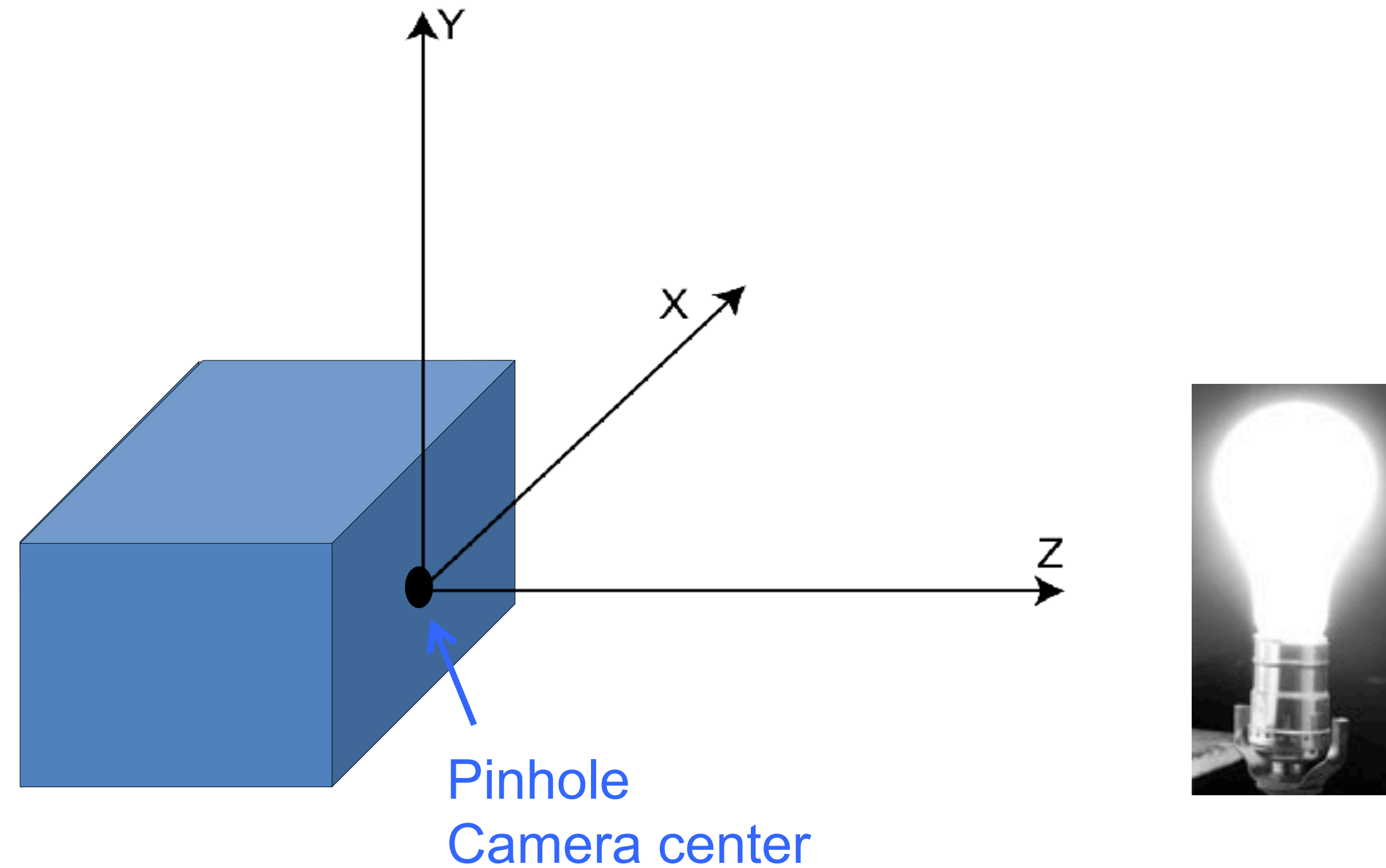
- The optical center ( $\mathbf{O}$ ) is at the origin
- The image plane is parallel to the  $xy$ -plane (perpendicular to the  $z$  axis)

## Projection equations

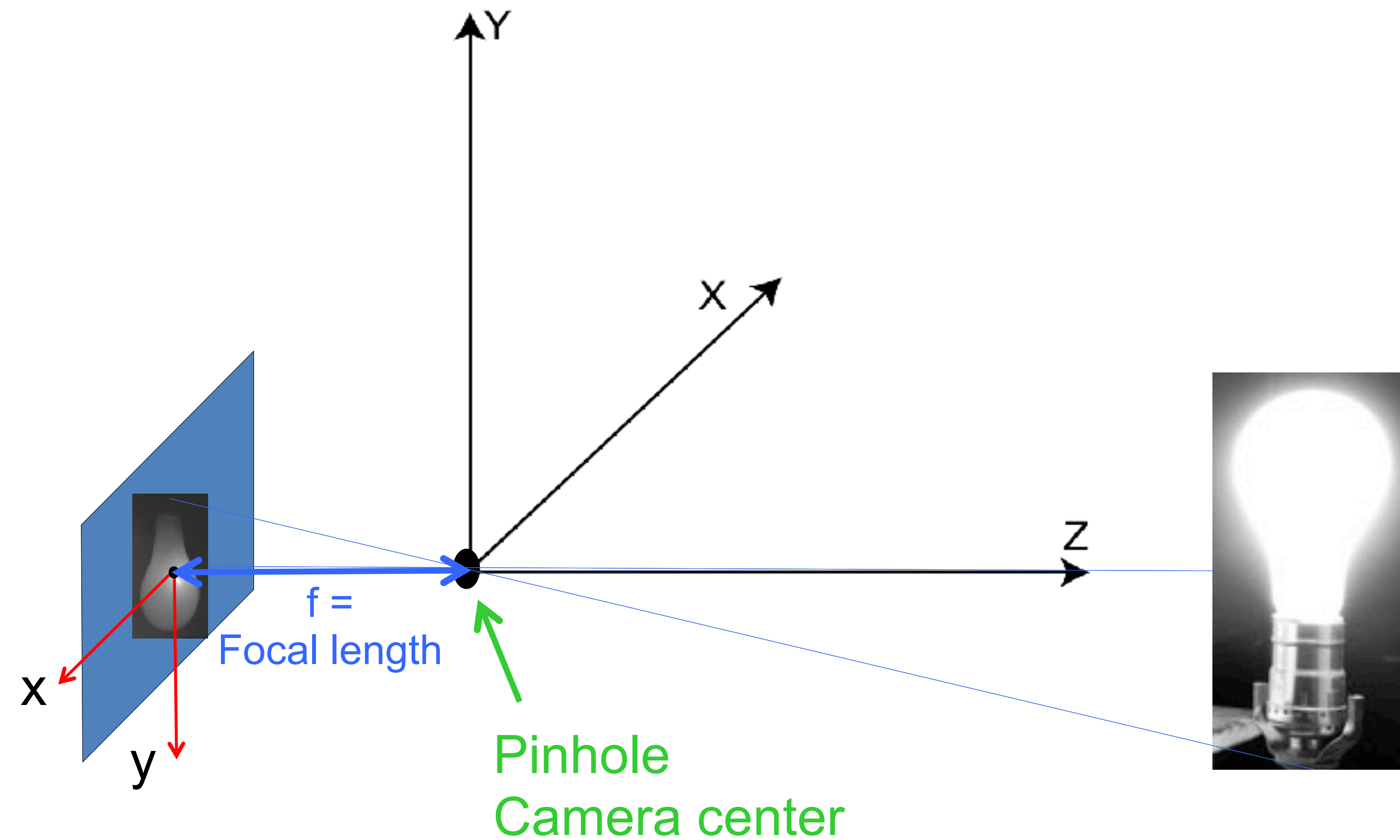
- Derive using similar triangles

$$(x, y, z) \rightarrow \left( -f \frac{x}{z}, -f \frac{y}{z} \right)$$

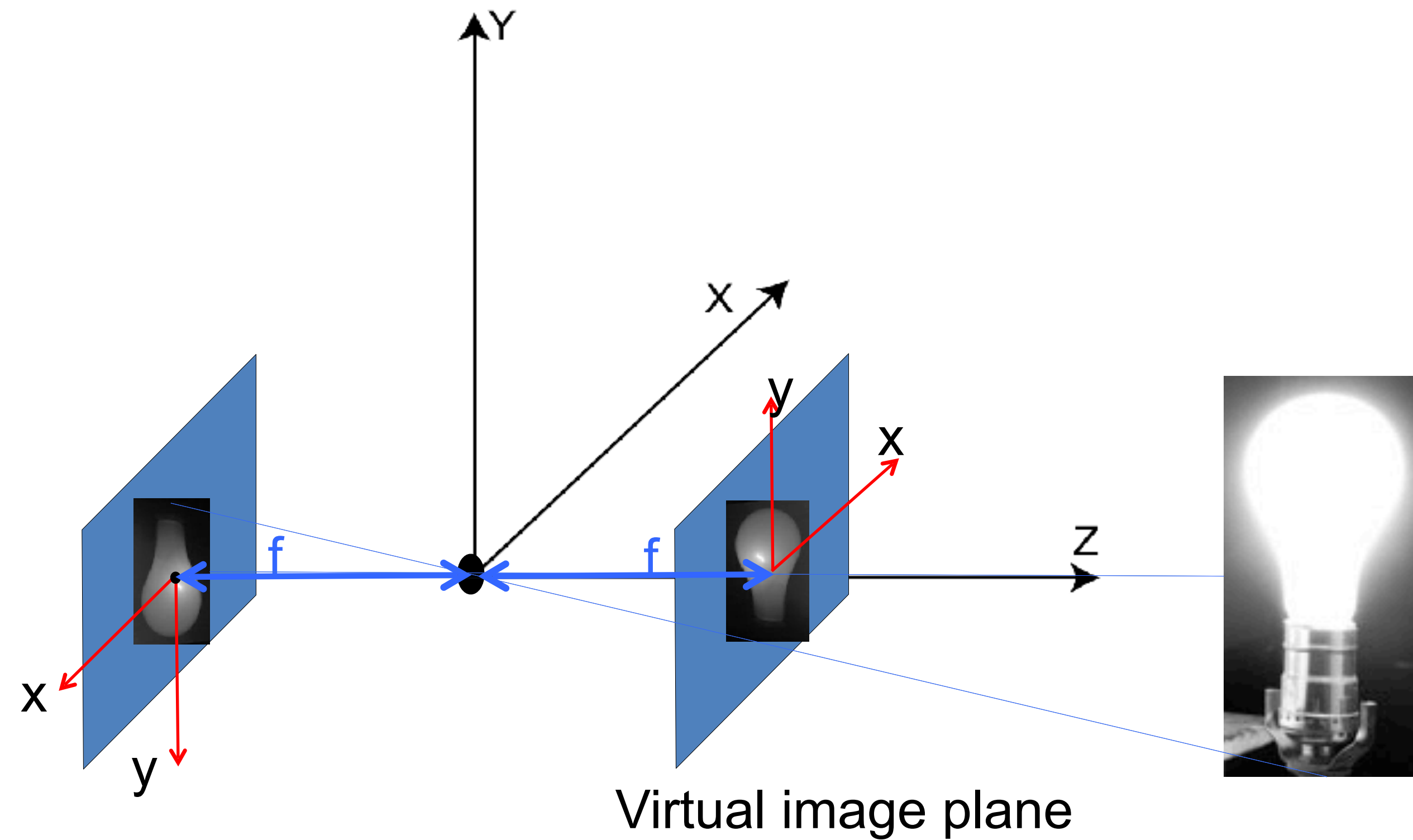
# Real and virtual imaging planes



# Real and virtual imaging planes

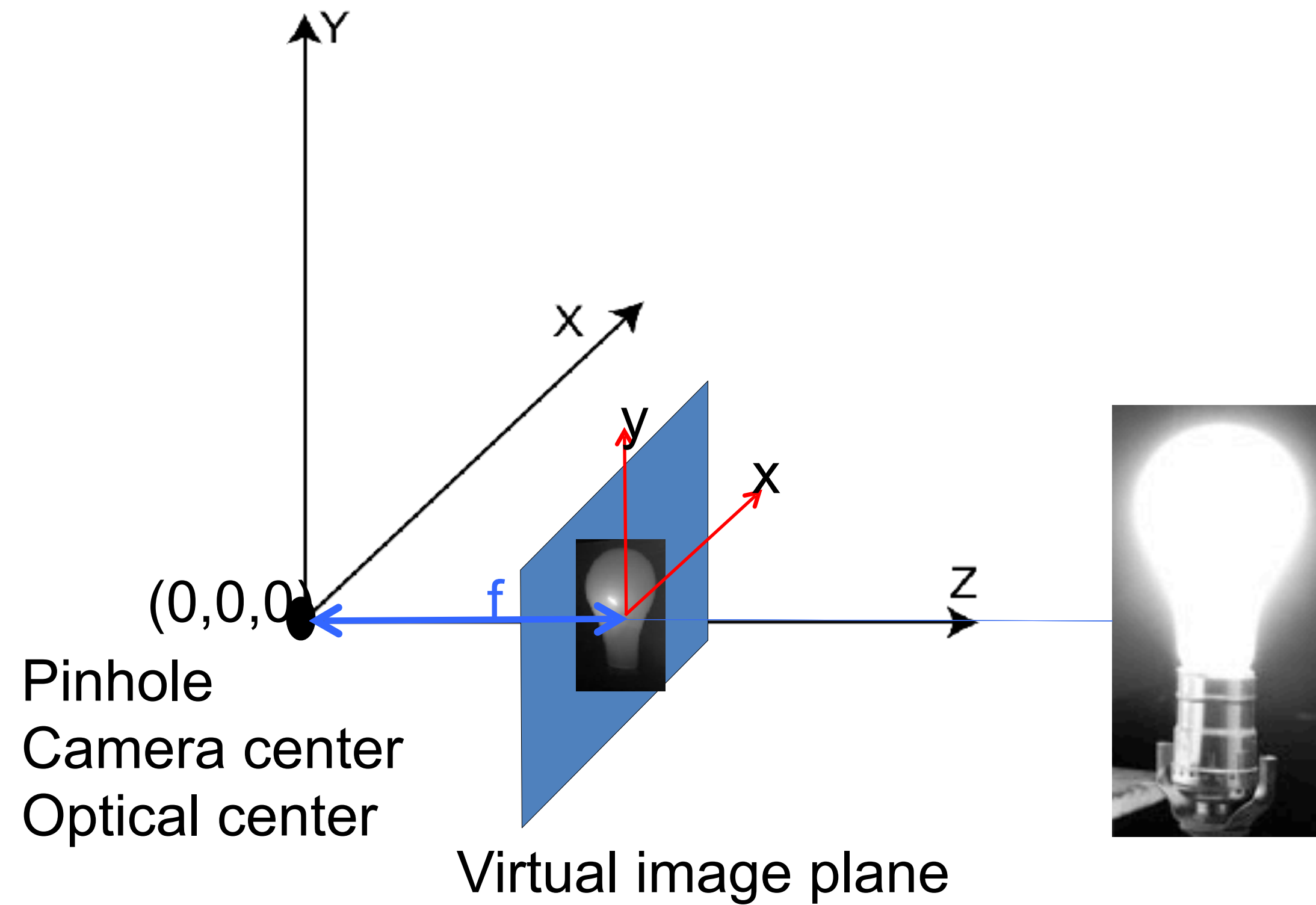


# Real and virtual imaging planes

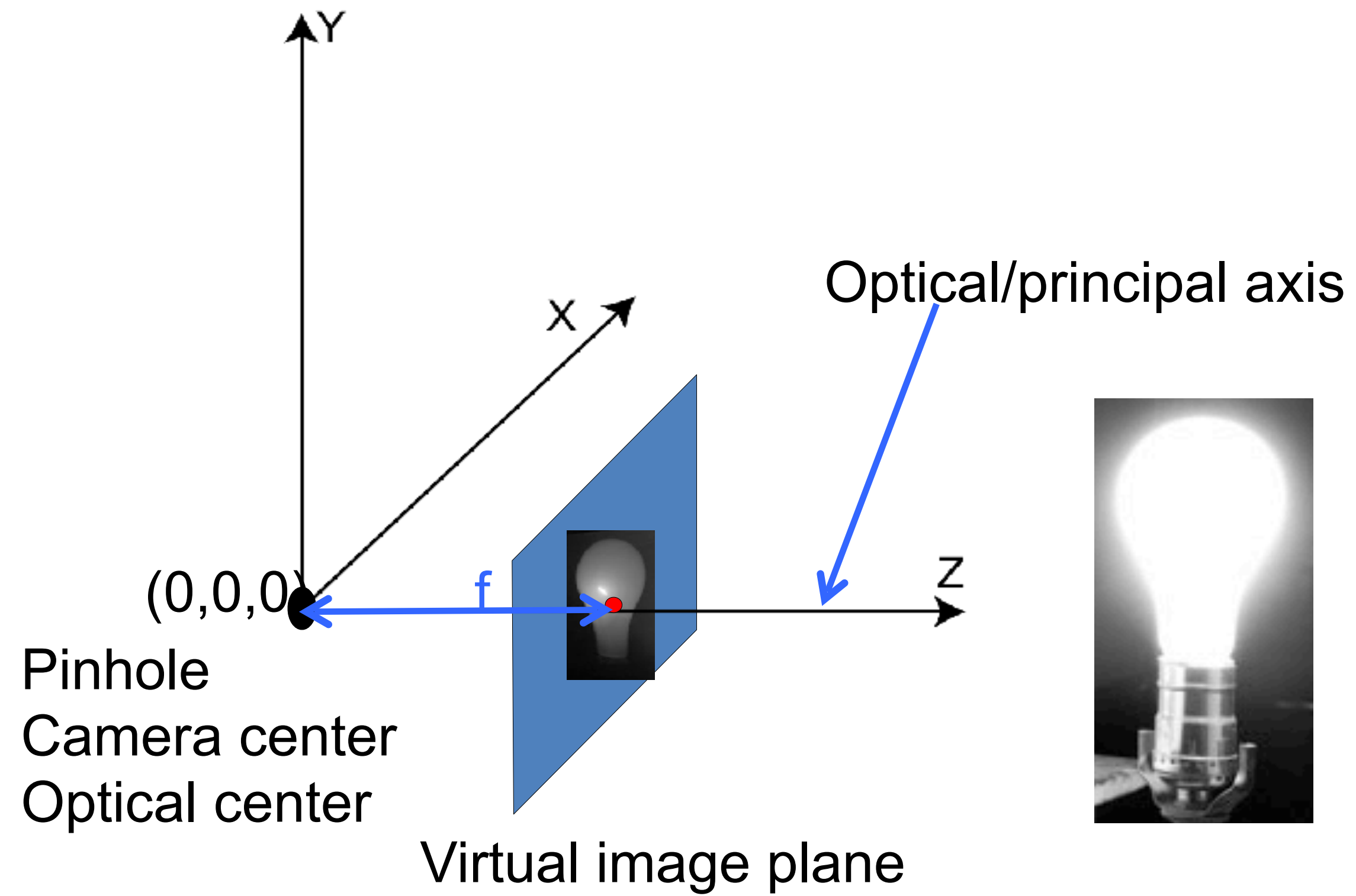




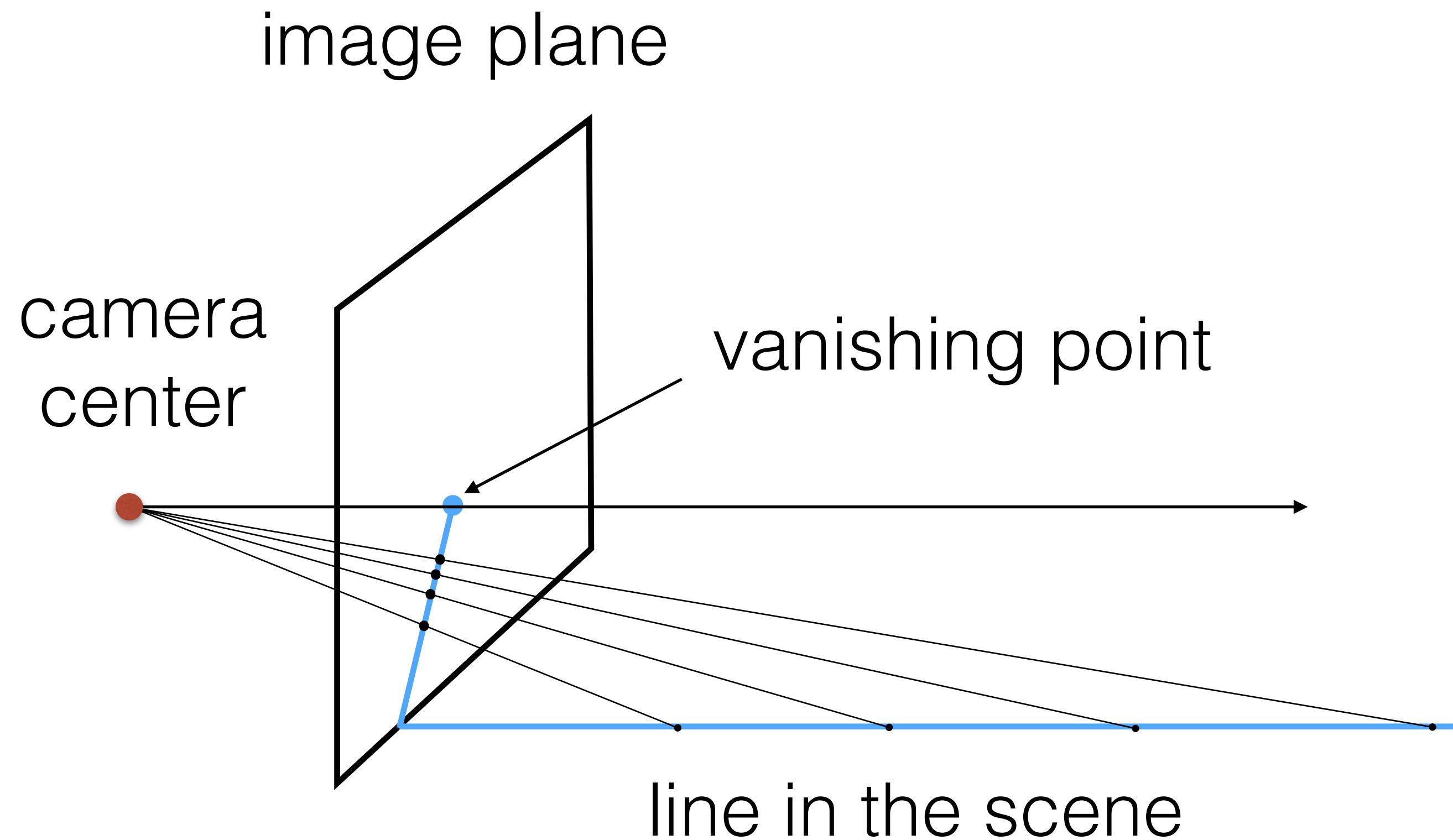
# Real and virtual imaging planes



# Real and virtual imaging planes



# Projection of a line



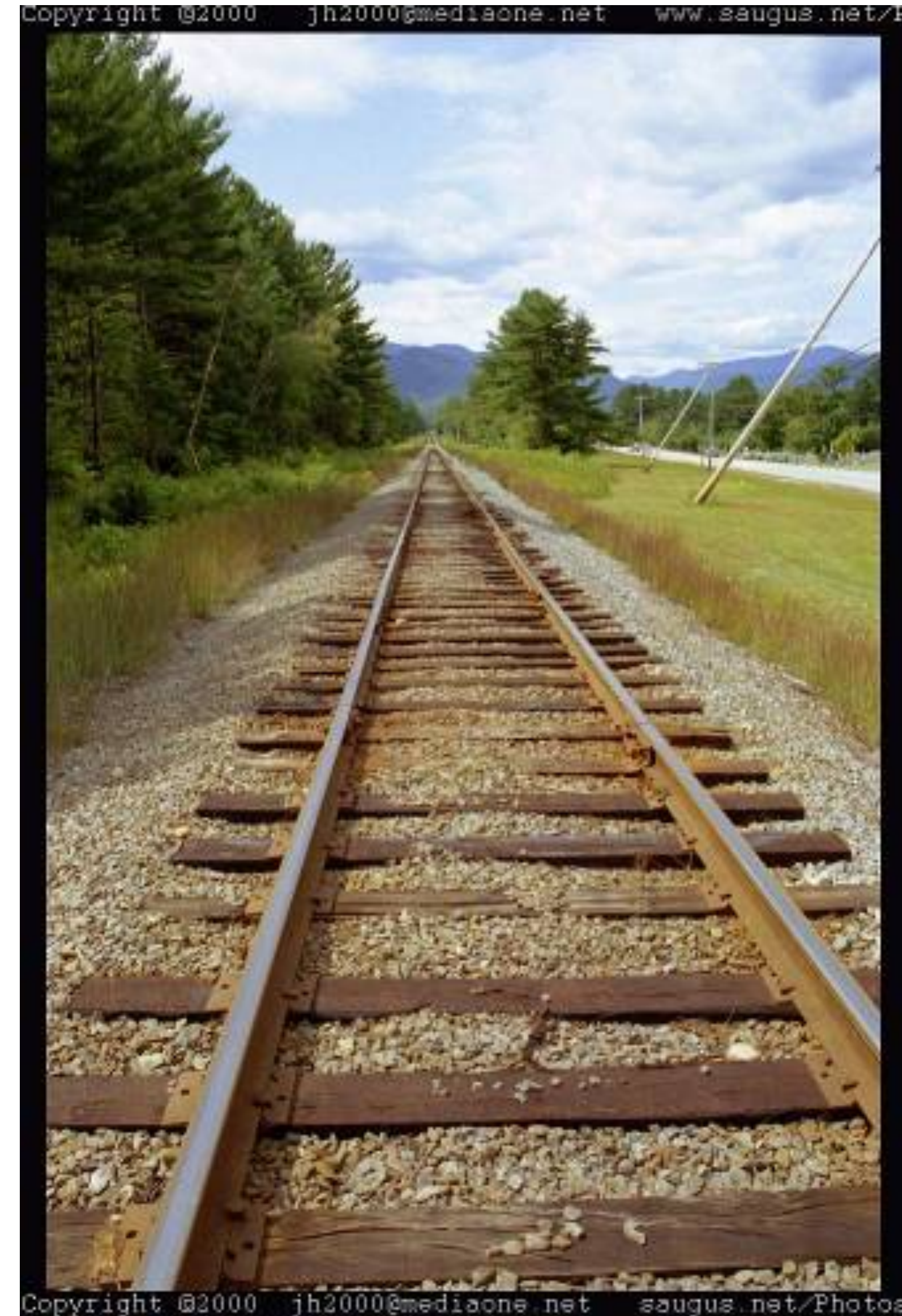
**Question:** What if we add another line parallel to the first one?



# Vanishing points

Each direction in space has its own vanishing point

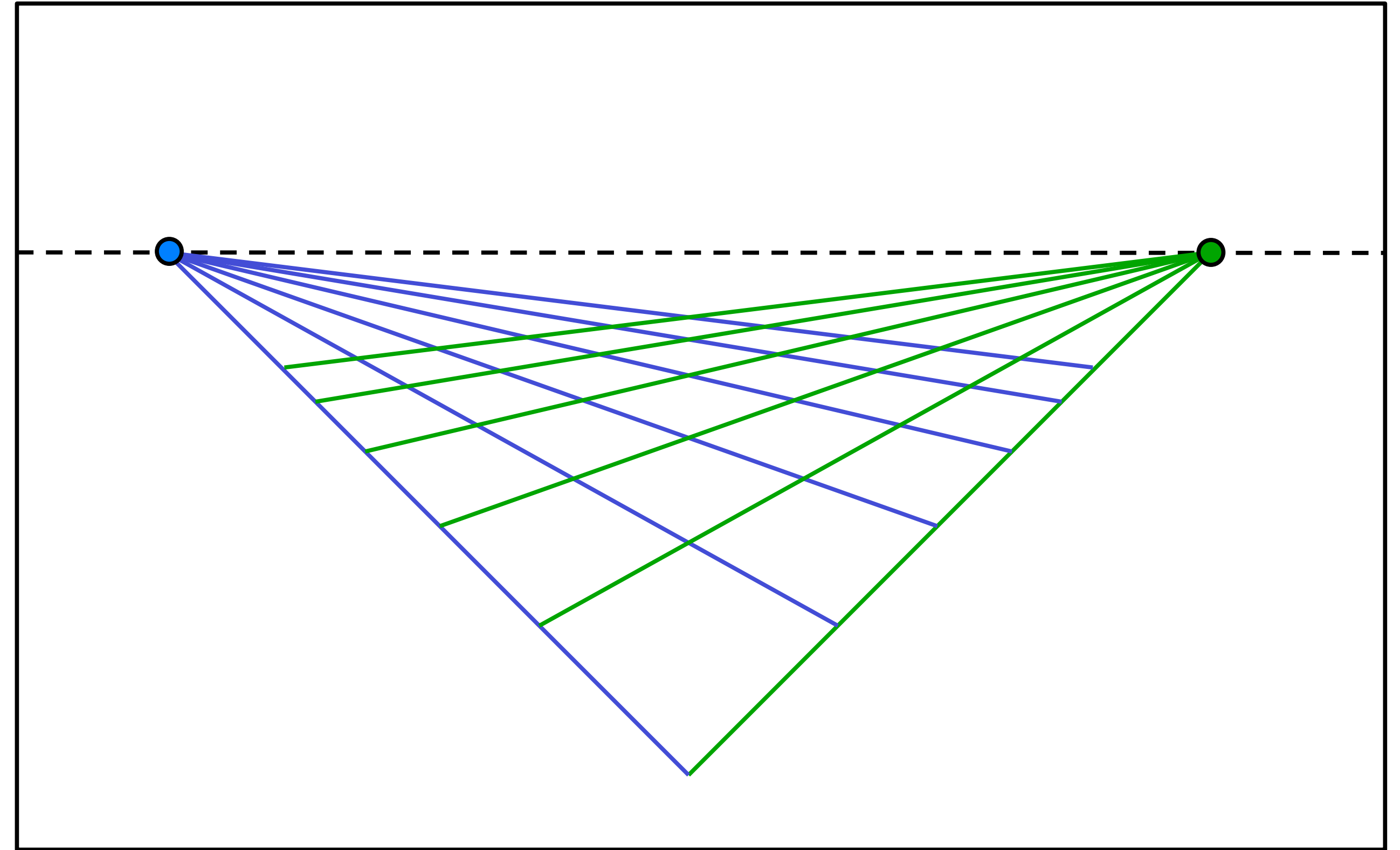
- All lines going in the that direction converge at that point
- **Exception:** directions that are parallel to the image plane



# Vanishing points

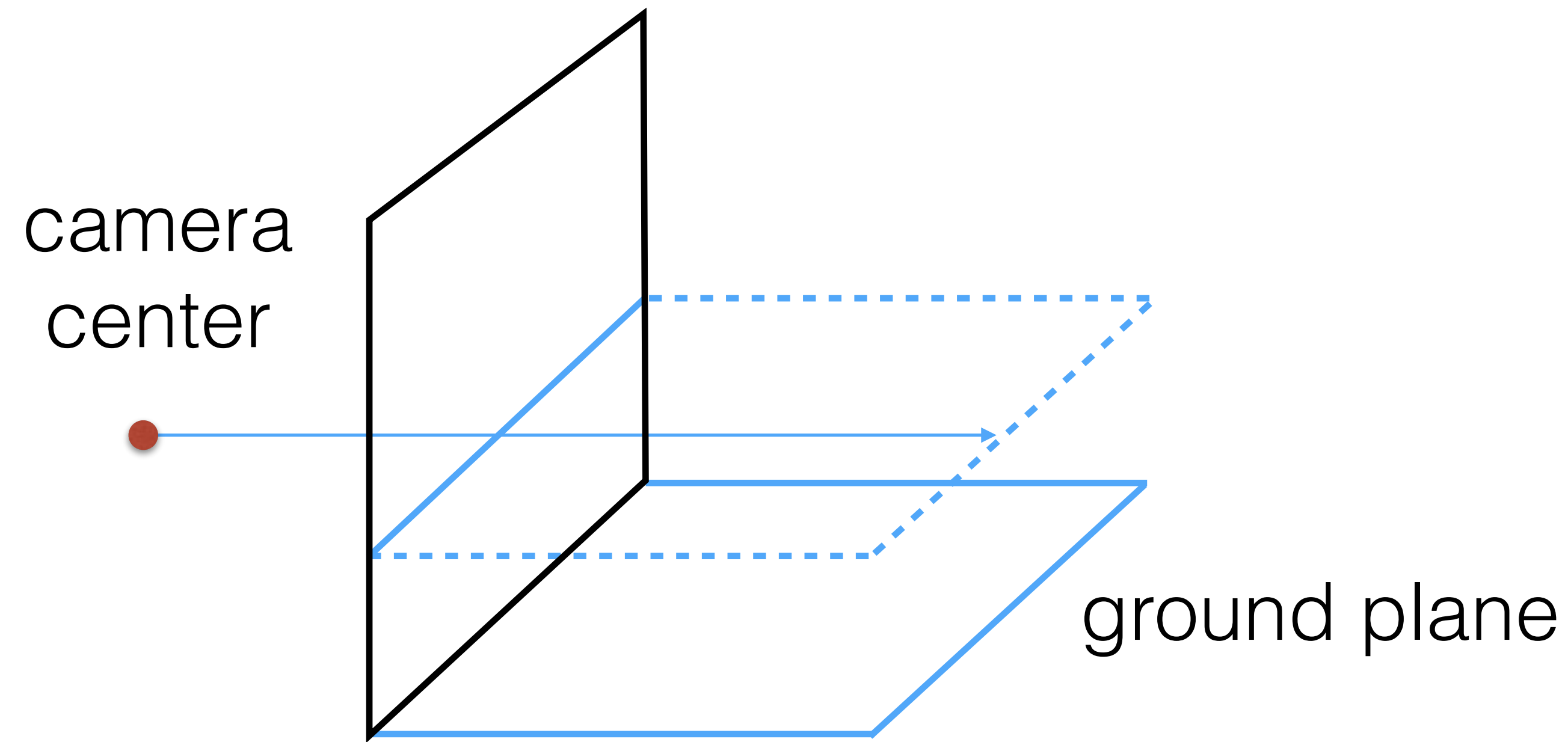
Each direction in space has its own vanishing point

- All lines going in the that direction converge at that point
- **Exception:** directions that are parallel to the image plane
- **What happens to the ground plane?**





# The horizon



# Vanishing line of the ground plane

- All points at the same height of the camera project to the horizon
- Points above the camera project above the horizon
- Provides a way of comparing heights of objects

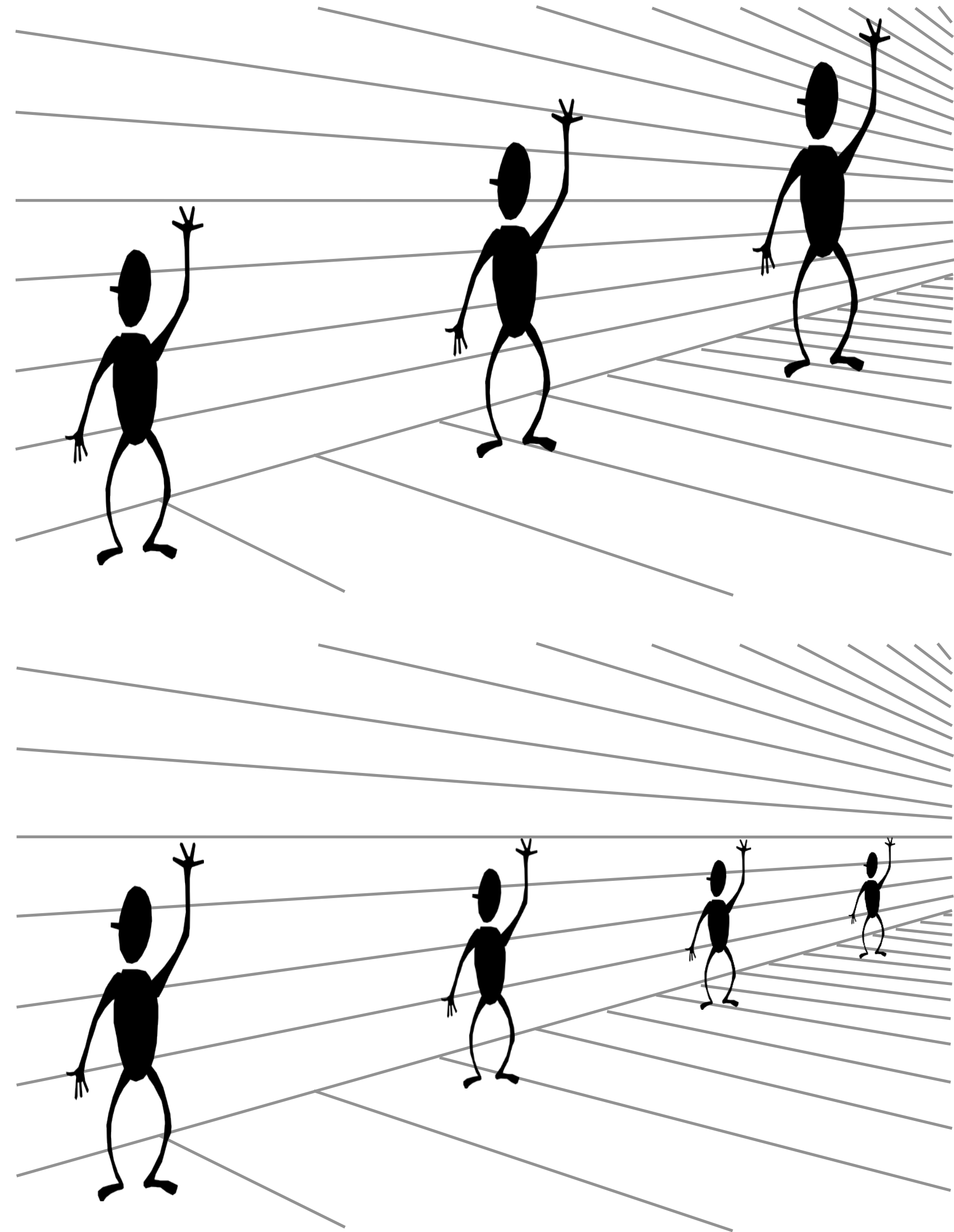
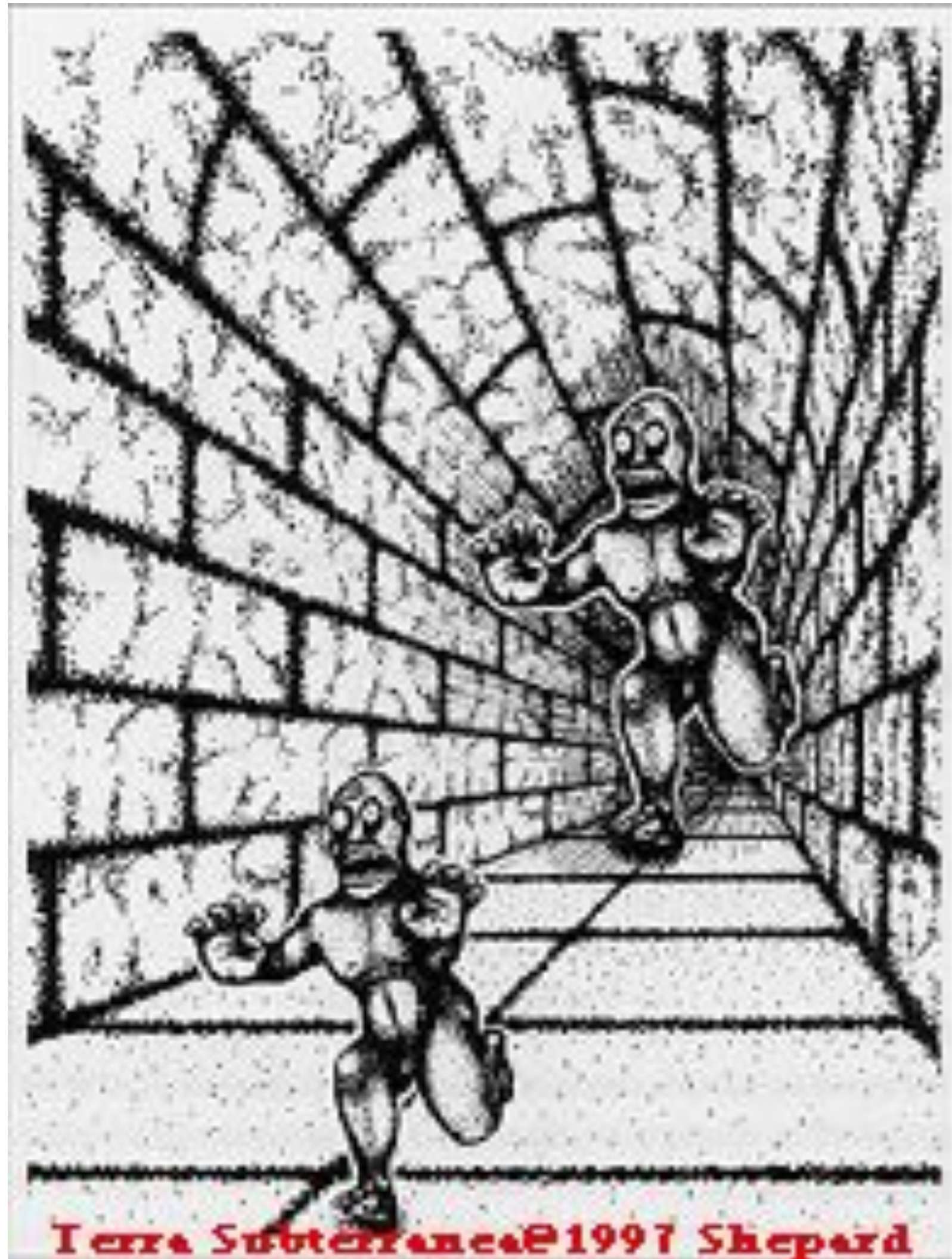
# The horizon



Is the person above or below the viewer?

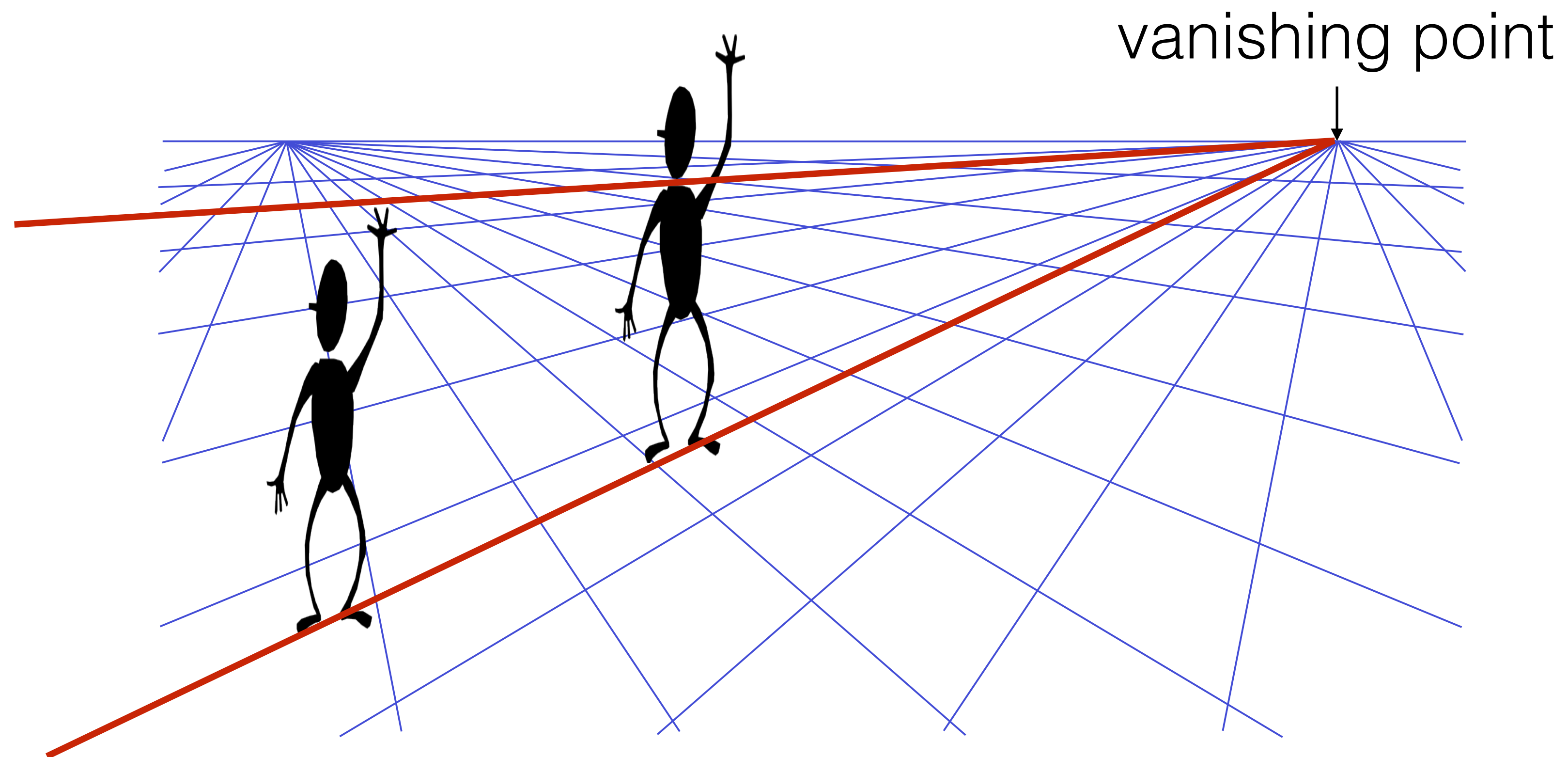


# Perspective cues

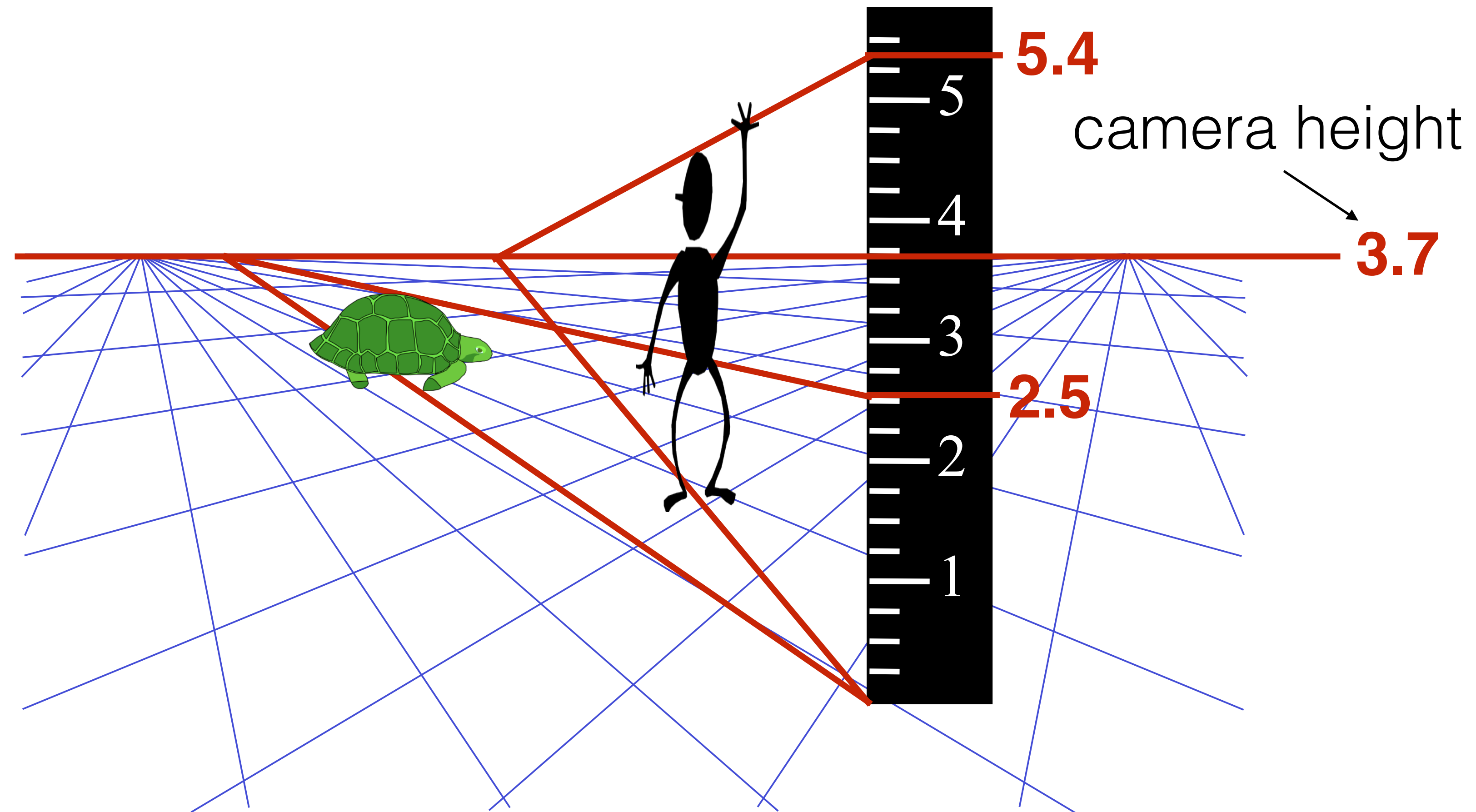




# Comparing heights



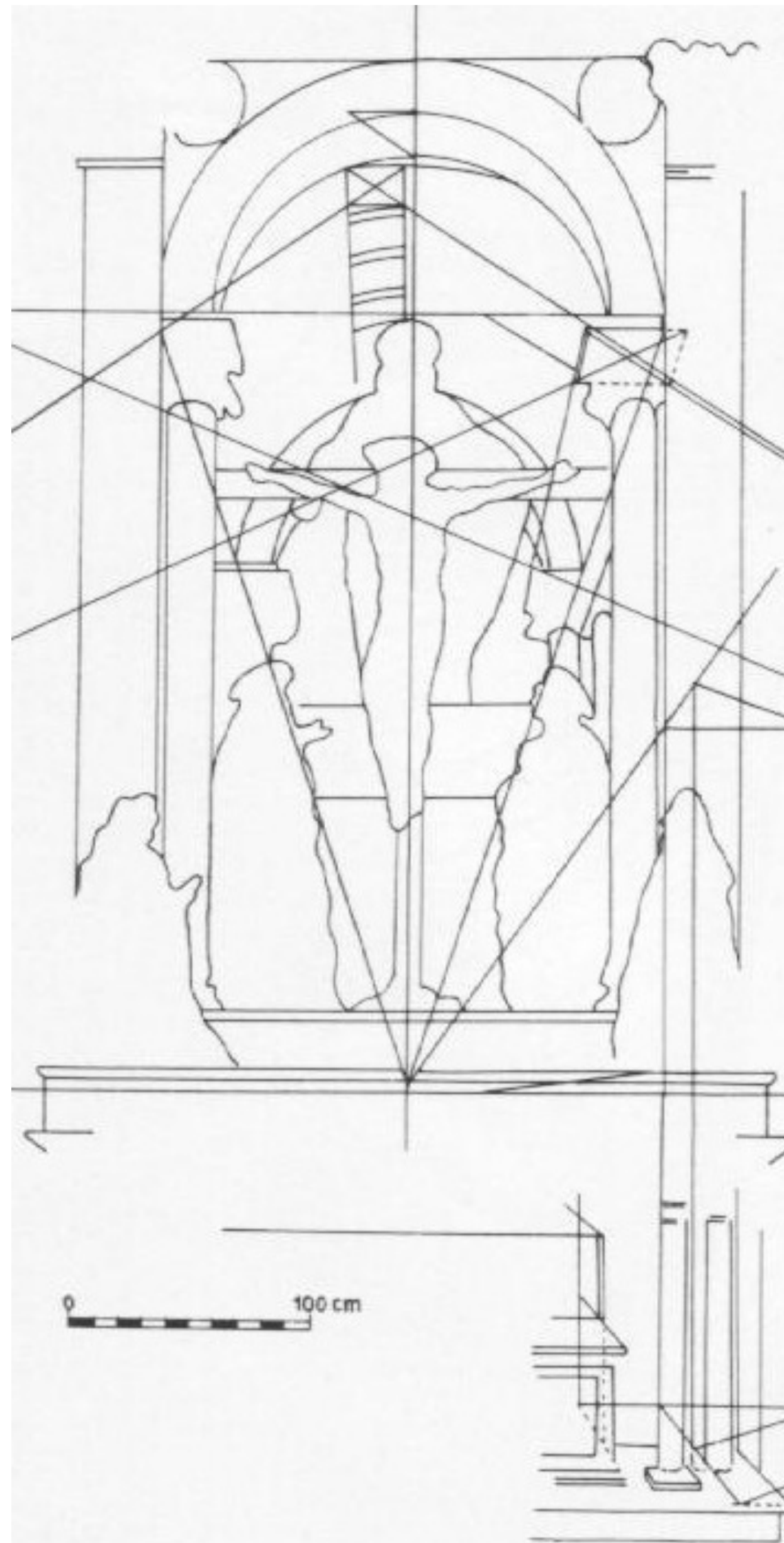
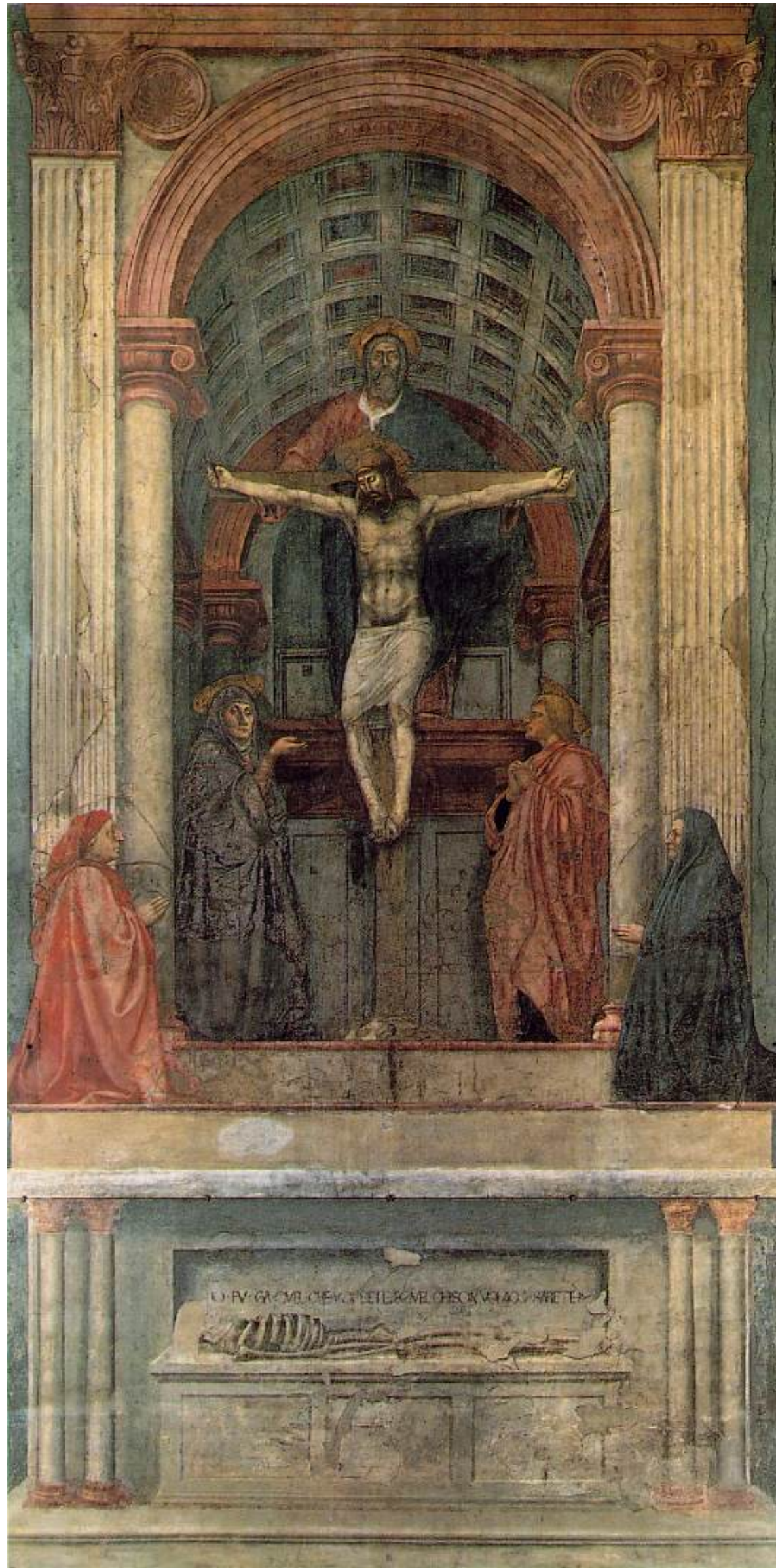
# Measuring heights



What is the height of the camera?



# Perspective in art



Masaccio,  
*Trinity*, Santa  
Maria Novella,  
Florence,  
1425-28

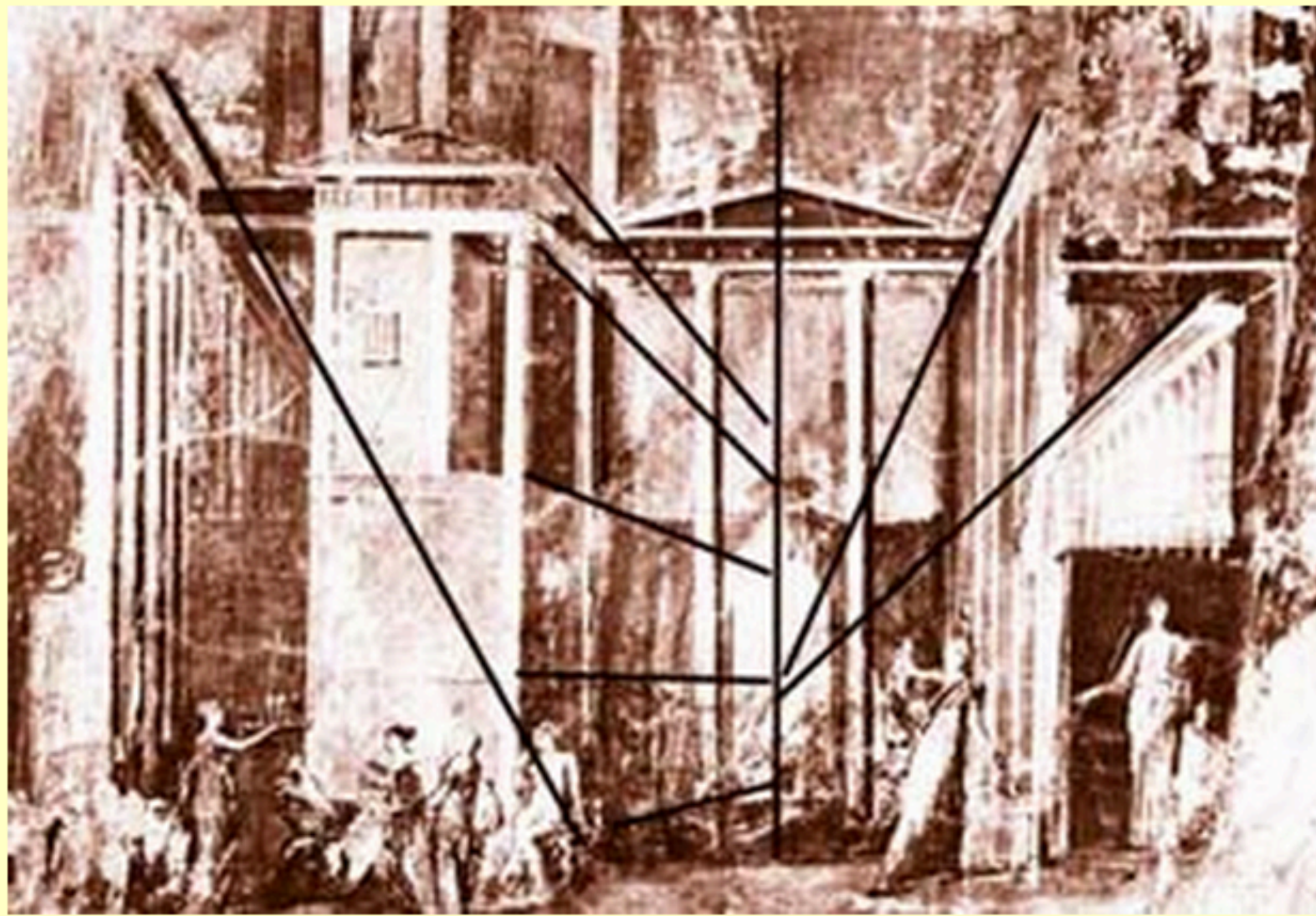
One of the first  
consistent uses  
of perspective  
in Western art



# Perspective in art

(At least partial) Perspective projections in art well before the Renaissance

Several Pompeii wallpaintings show the fragmentary use of linear perspective:



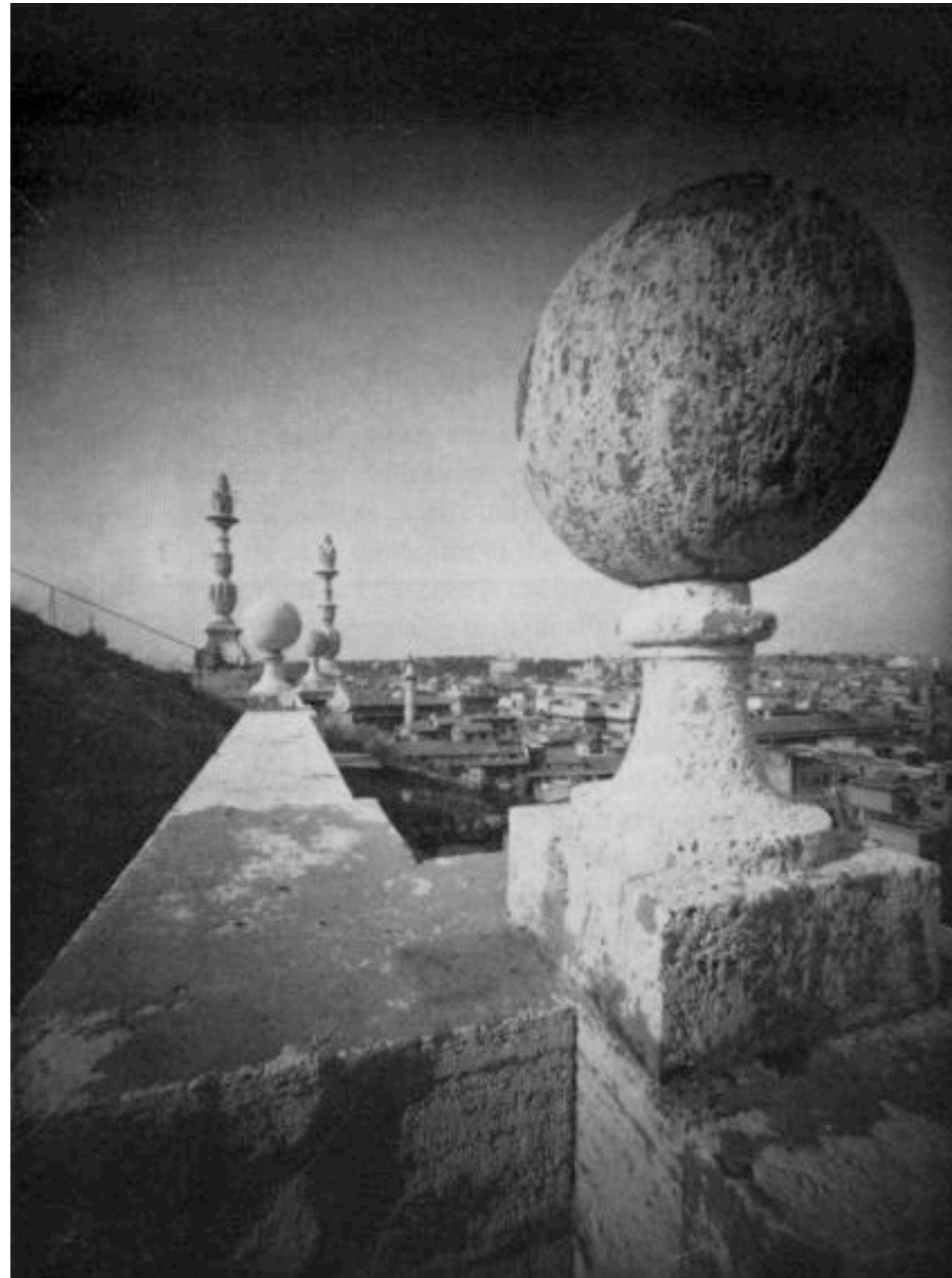
From [ottobwiersma.nl](http://ottobwiersma.nl)

Also some Greek examples,  
So apparently pre-renaissance...



# Perspective distortion

What does a sphere project to?

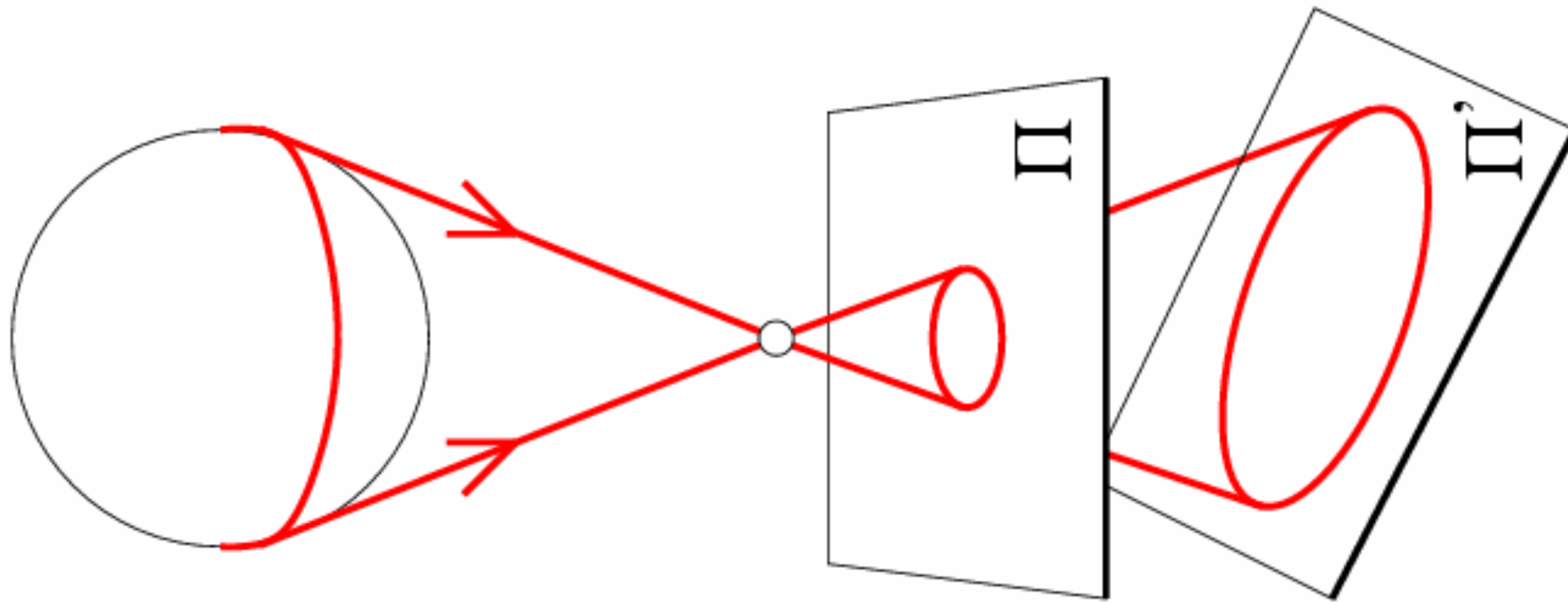


M. H. Pirenne



# Perspective distortion

What does a sphere project to?

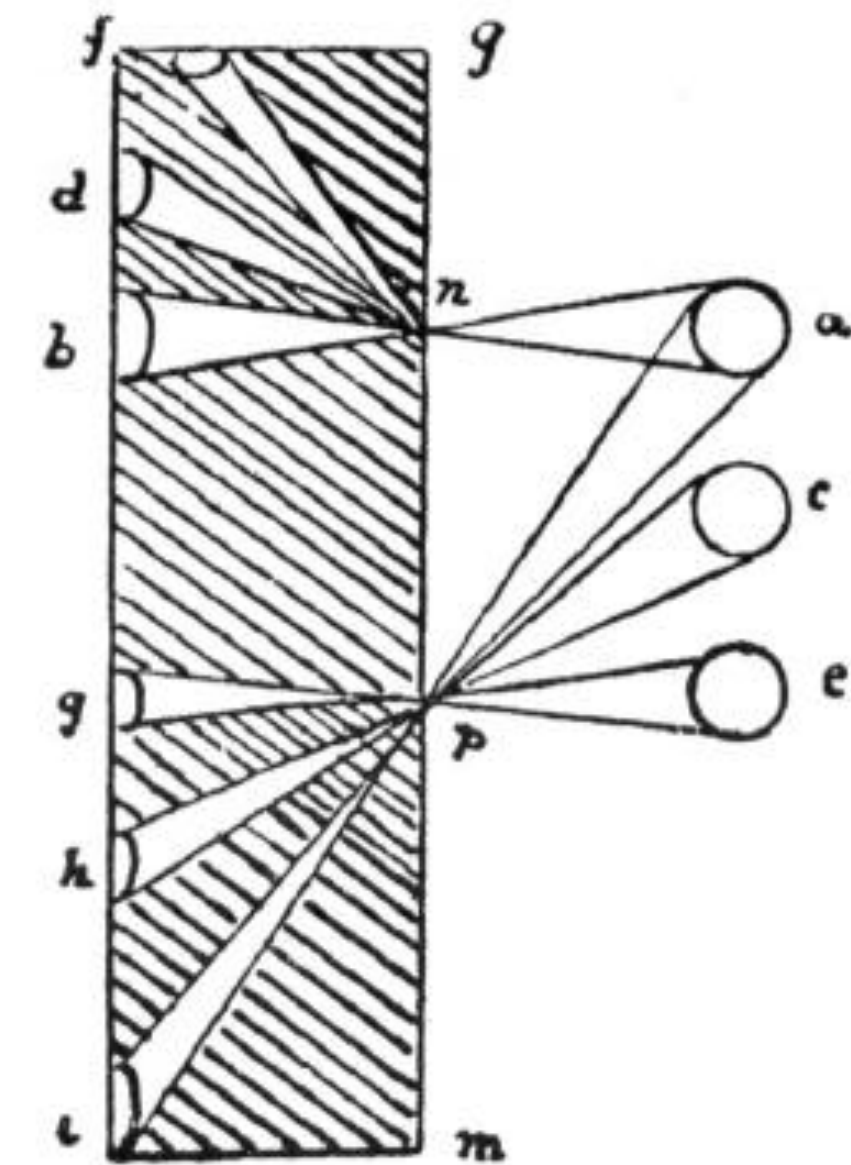
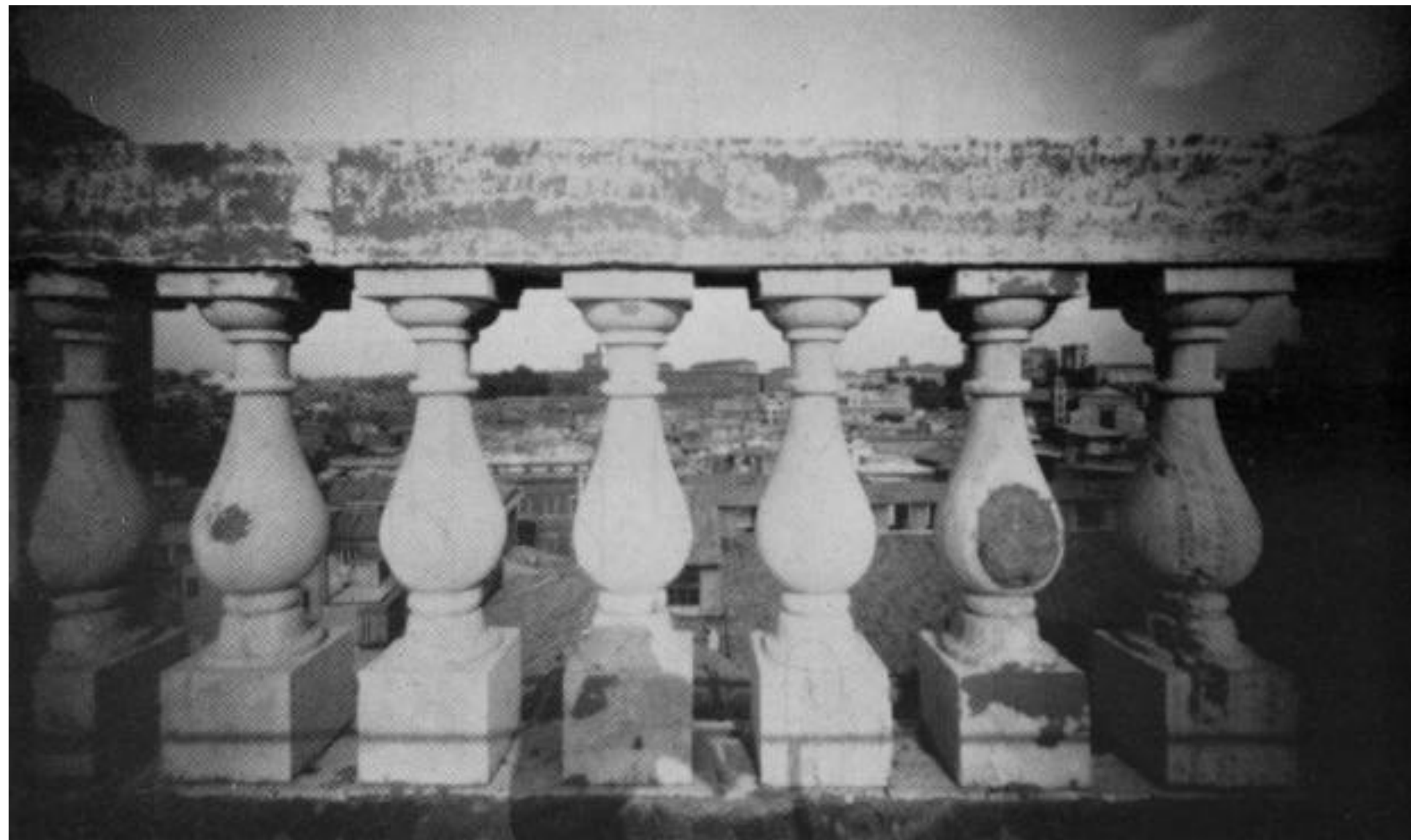


# Perspective distortion

The exterior looks bigger

The distortion is not due to lens flaws

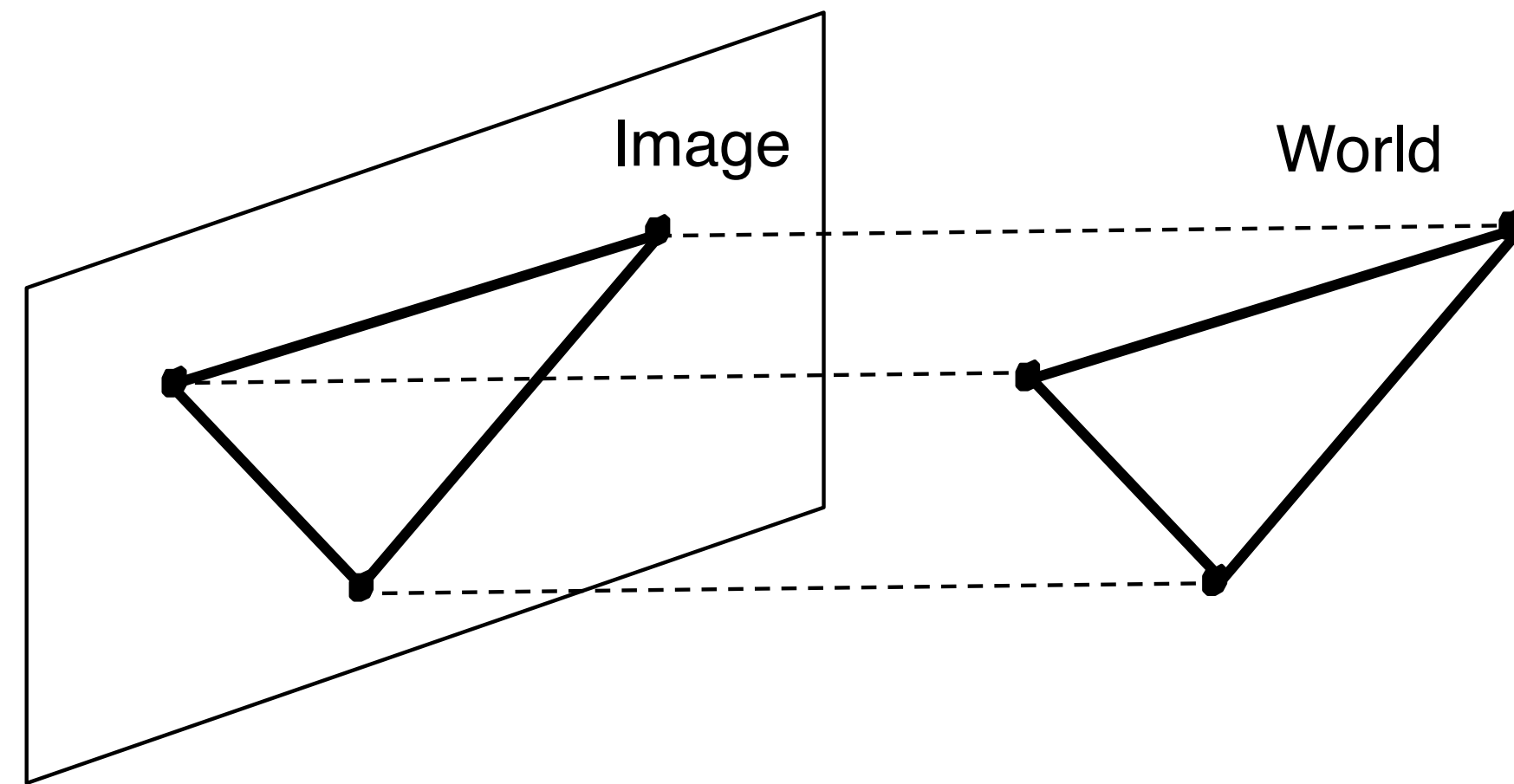
Problem pointed out by Da Vinci



# Orthographic projection

## Special case of perspective projection

- Distance of the object from the image plane is infinite
- Also called the “parallel projection”





# Orthographic projection

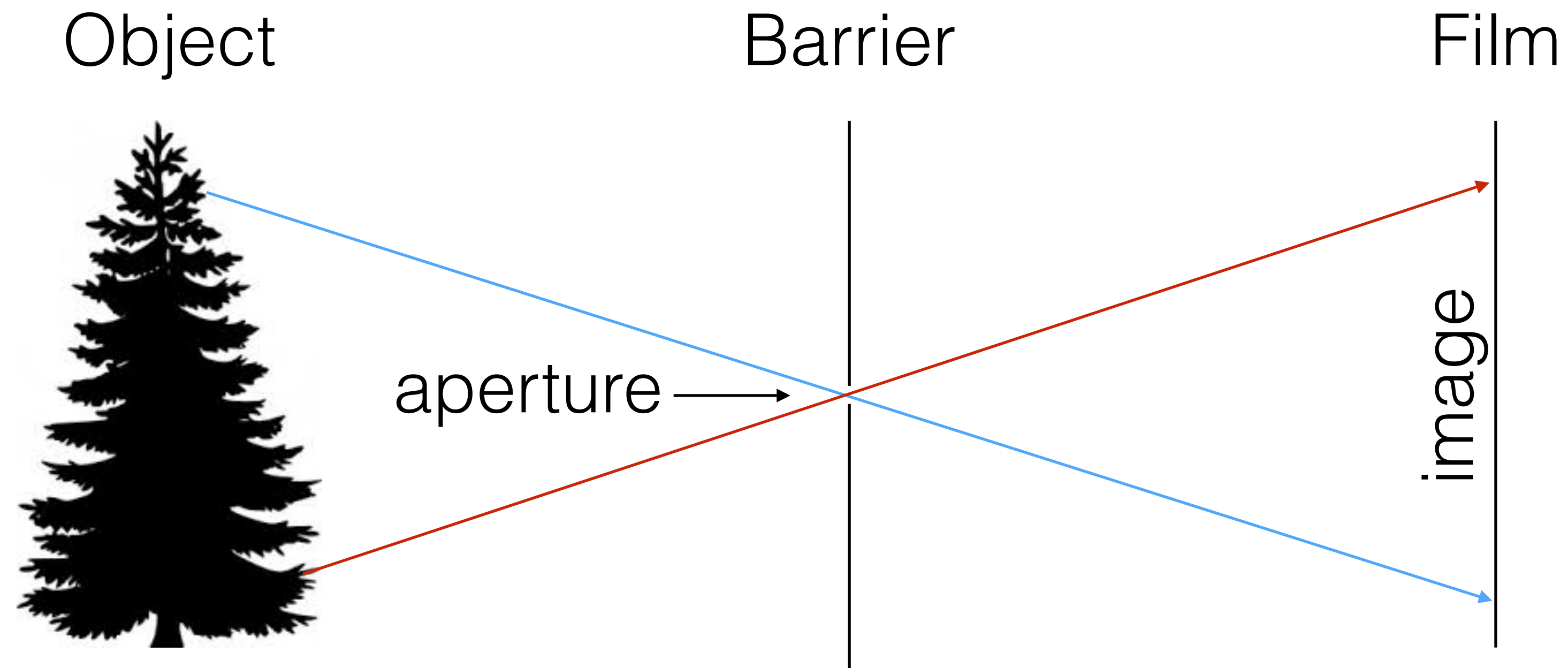
Special case of perspective projection

- Distance of the object from the image plane is infinite
- Also called the “parallel projection”

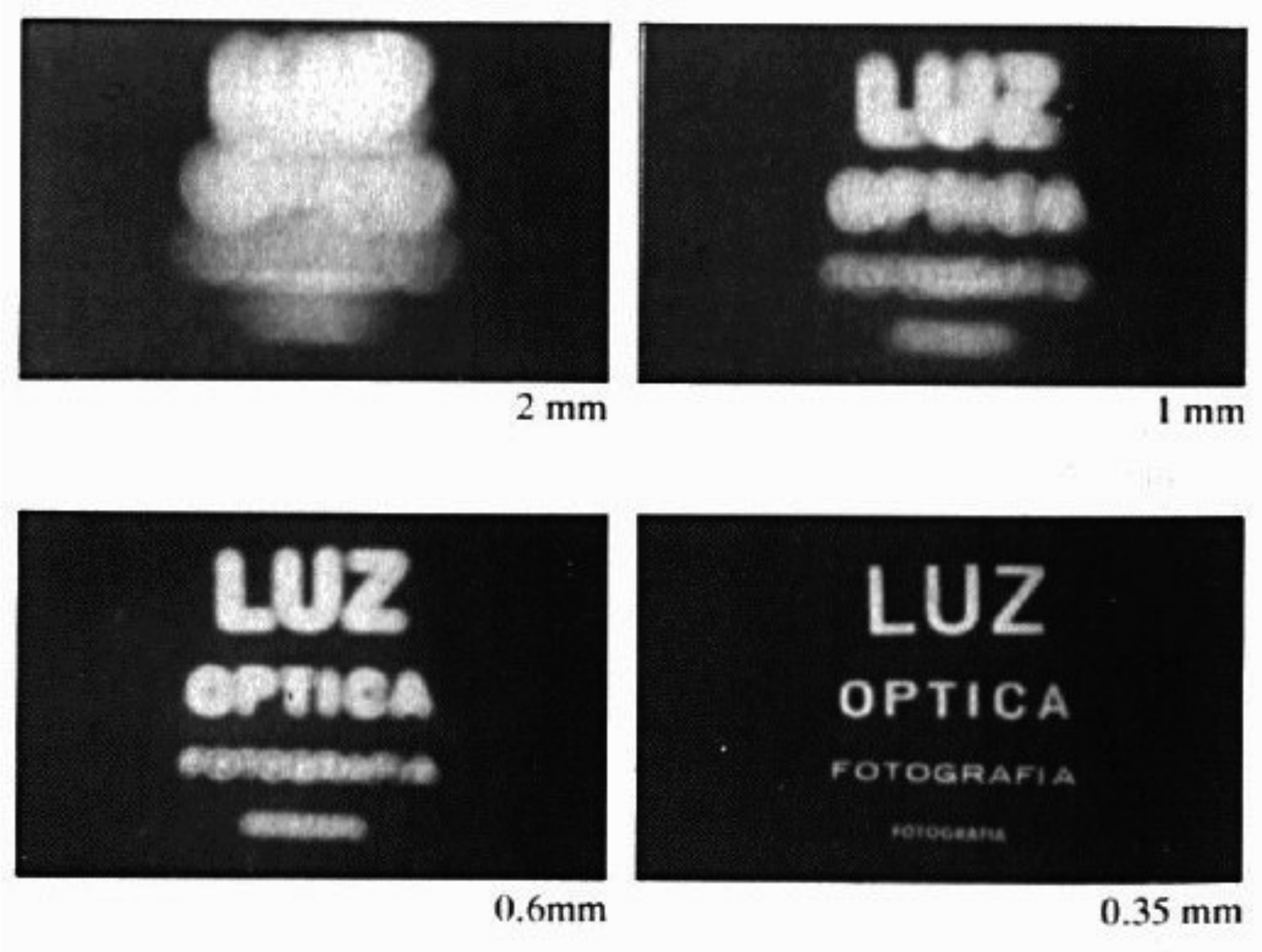




# Pinhole camera

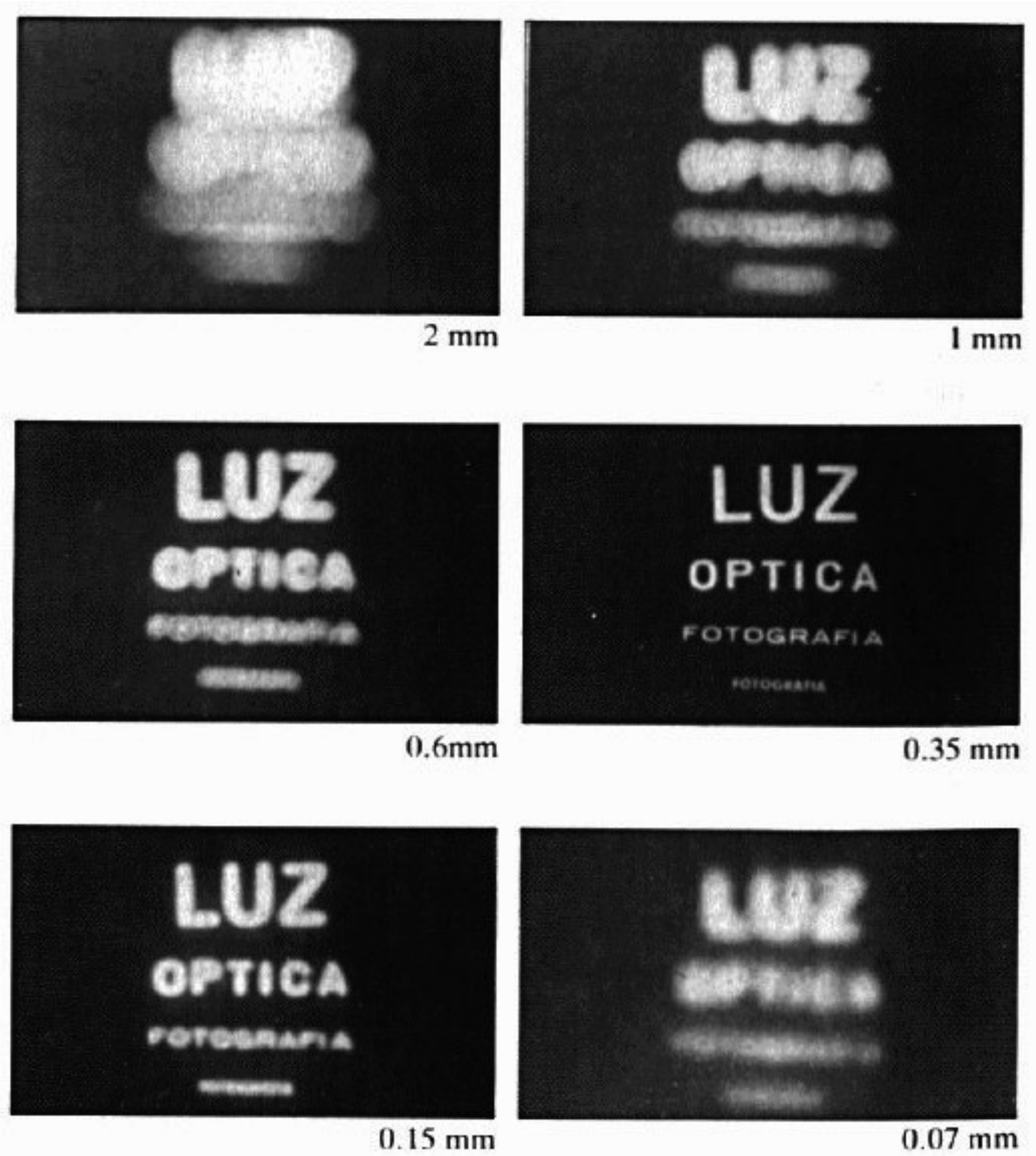


# Shrinking the aperture

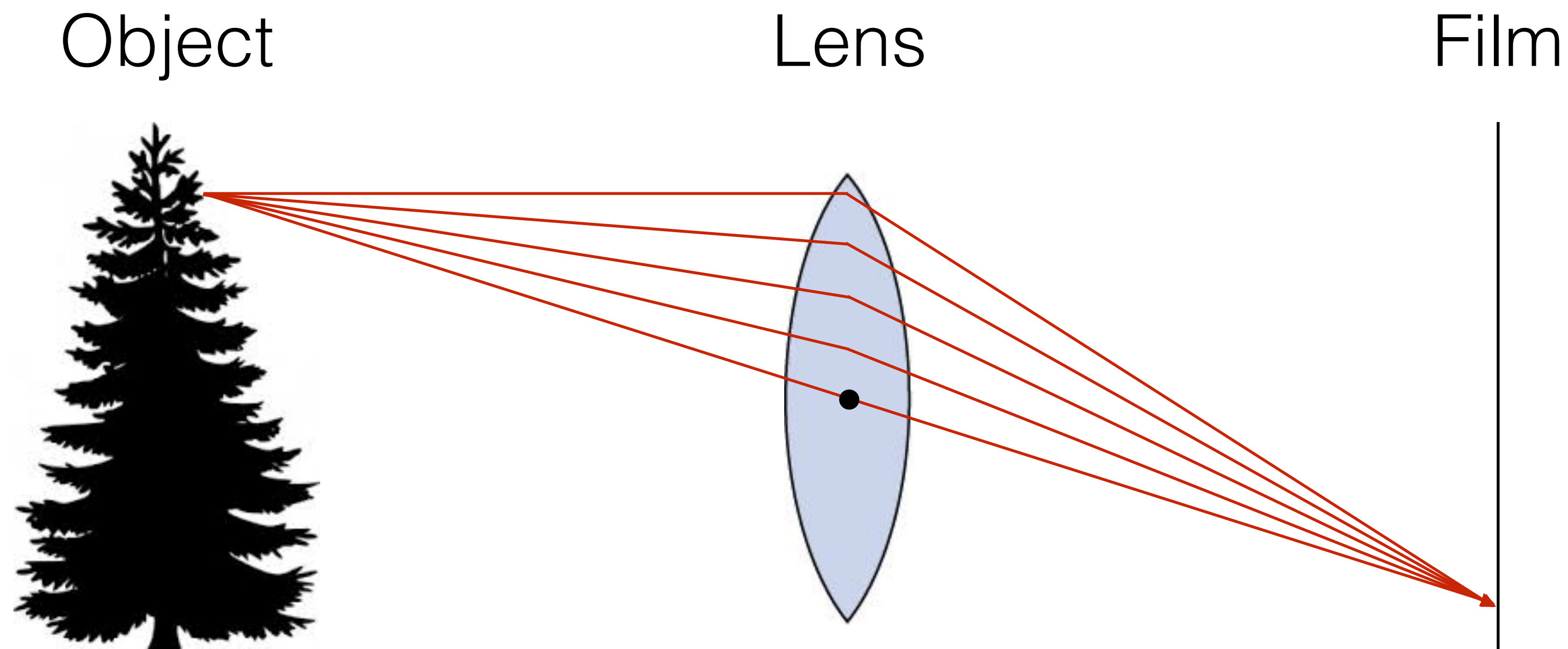




# Shrinking the aperture



# Adding a lens

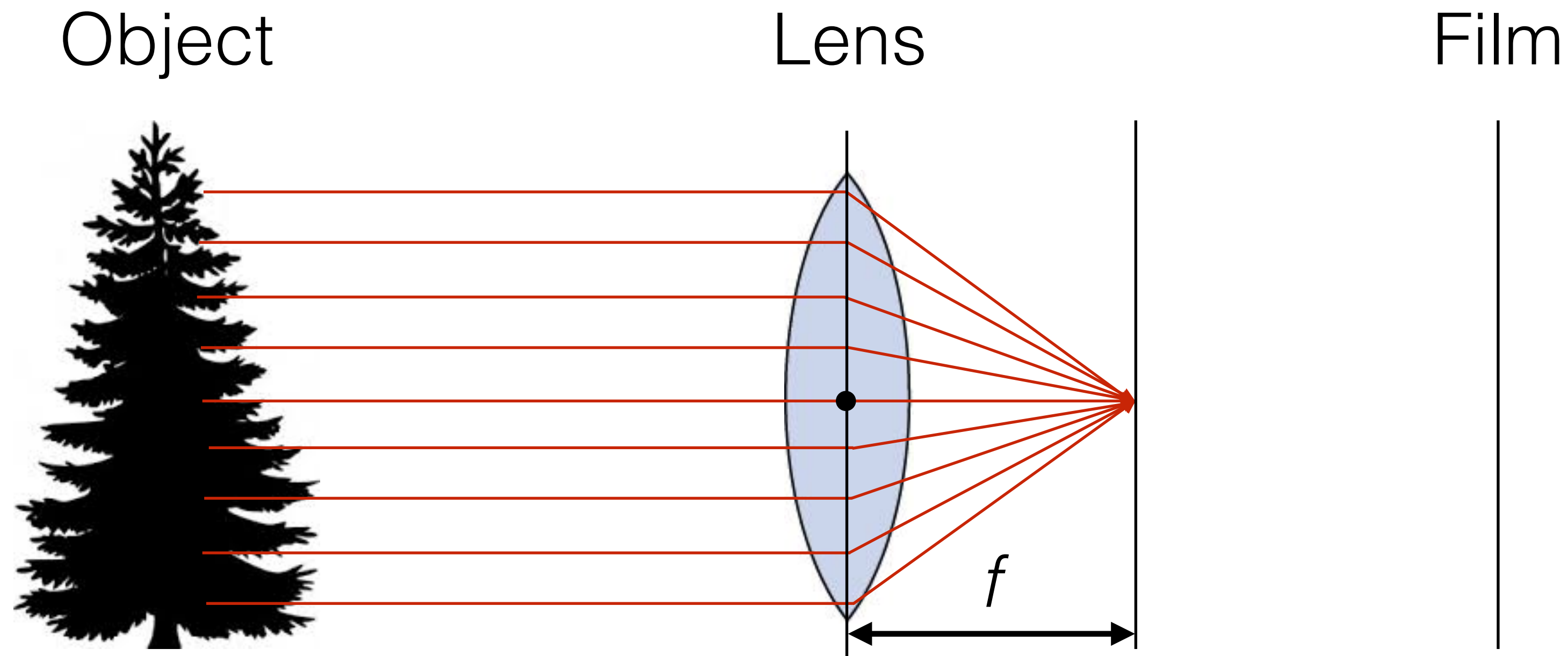


A lens focuses light on to the film

## Thin lens model:

- Rays passing through the center are not deviated (pinhole projection model still holds)

# Adding a lens



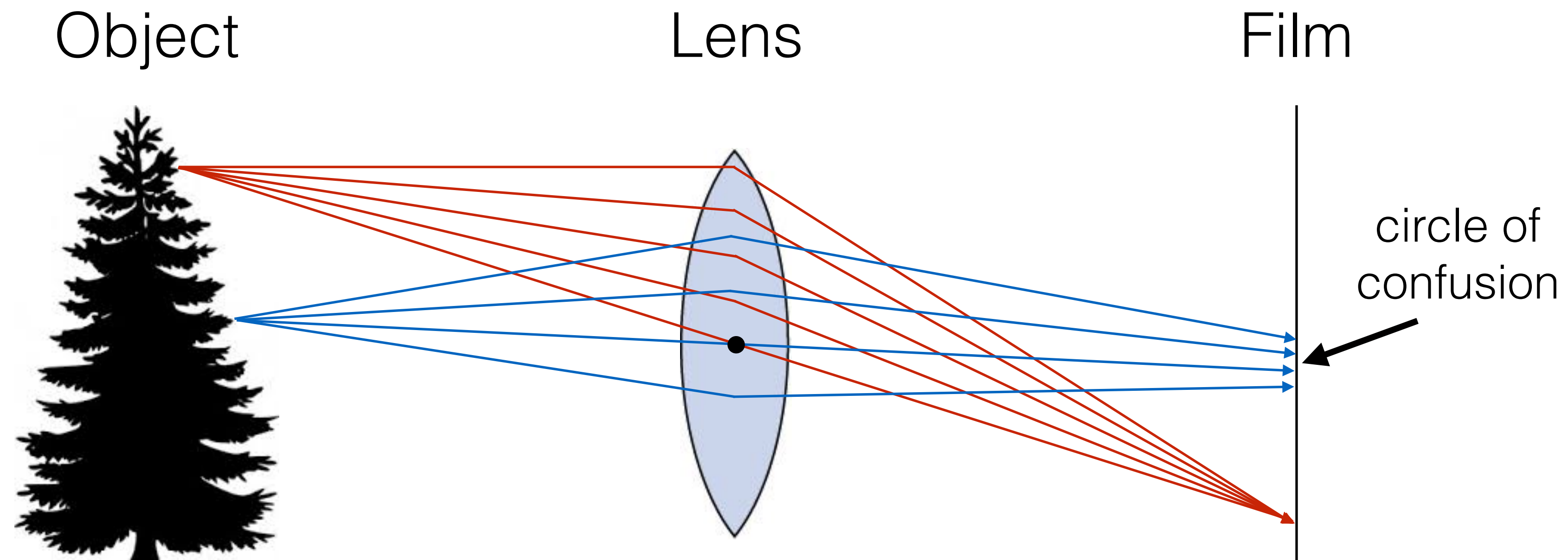
A lens focuses light on to the film

## Thin lens model:

- Rays passing through the center are not deviated (pinhole projection model still holds)
- All parallel rays converge to one point on a plane located at the *focal length*  $f$



# Adding a lens

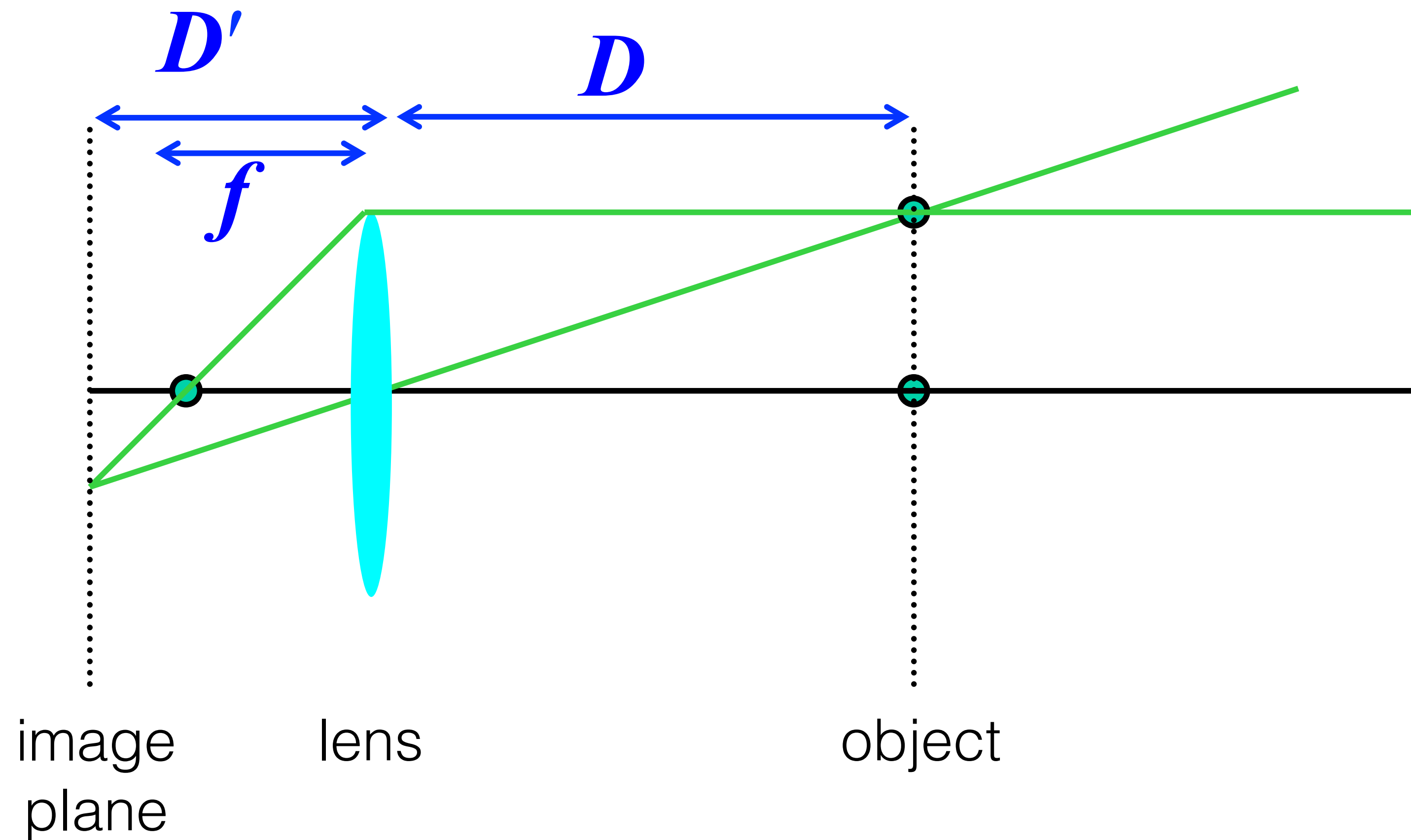


A lens focuses light on to the film

- There is a specific distance at which objects are “in focus”
- other points project on to a “circle of confusion” in the image

# Thin lens formula

What is the relation between the focal length ( $f$ ), the distance of the object from the optical center ( $D$ ) and the distance at which the object will be in focus ( $D'$ )?

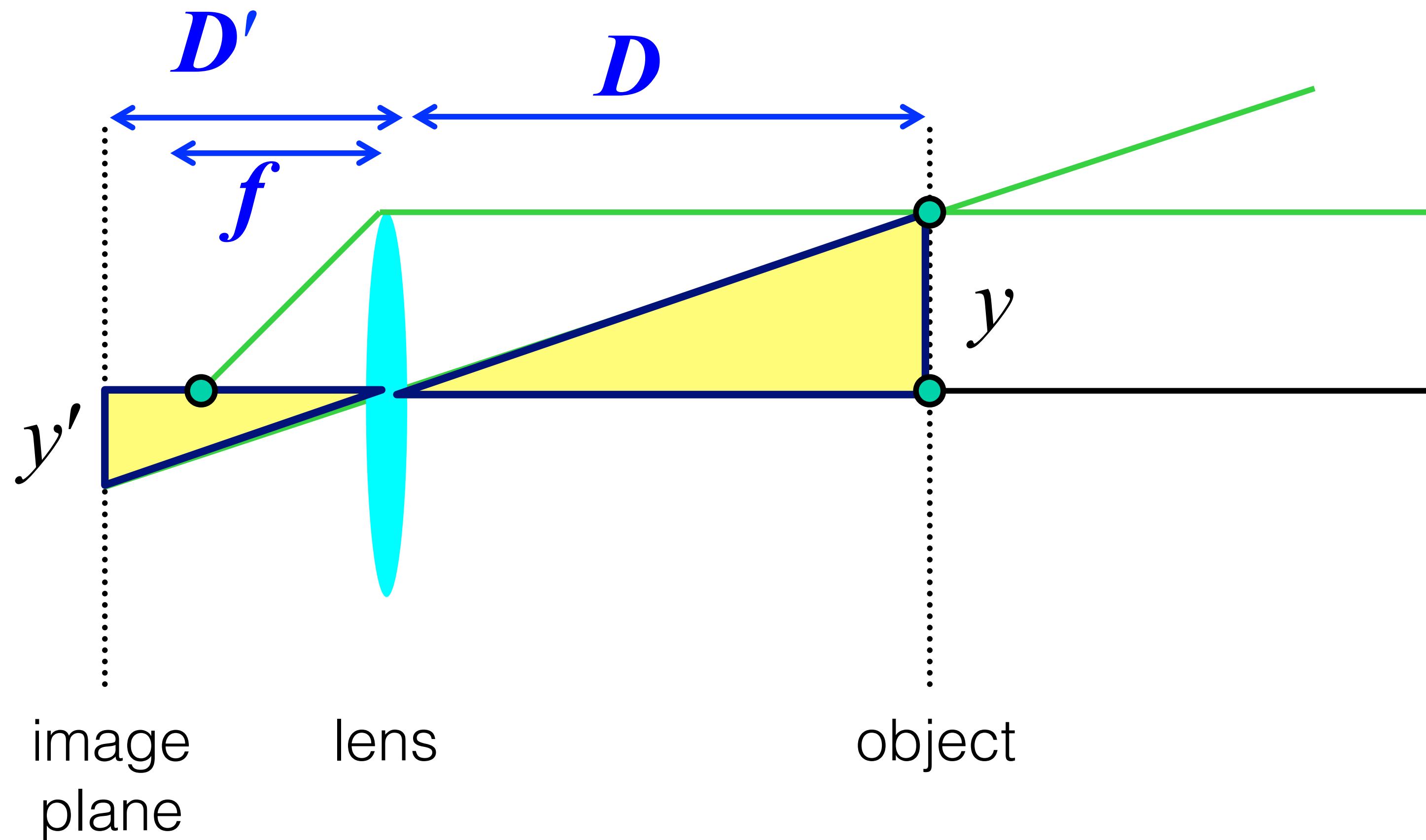




# Thin lens formula

Similar triangles everywhere!

$$y'/y = D'/D$$

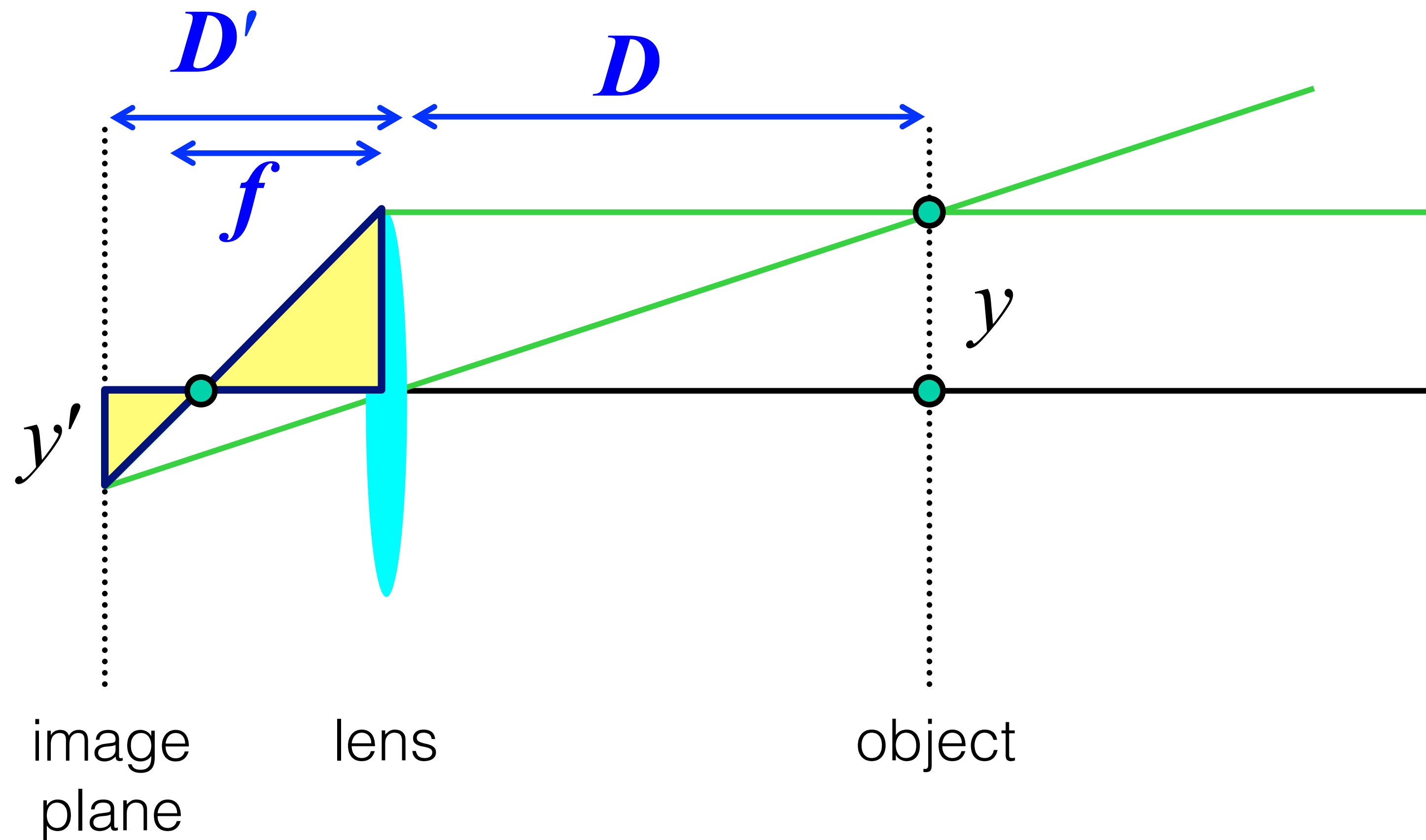


# Thin lens formula

Similar triangles everywhere!

$$y'/y = D'/D$$

$$y'/y = (D' - f)/f$$

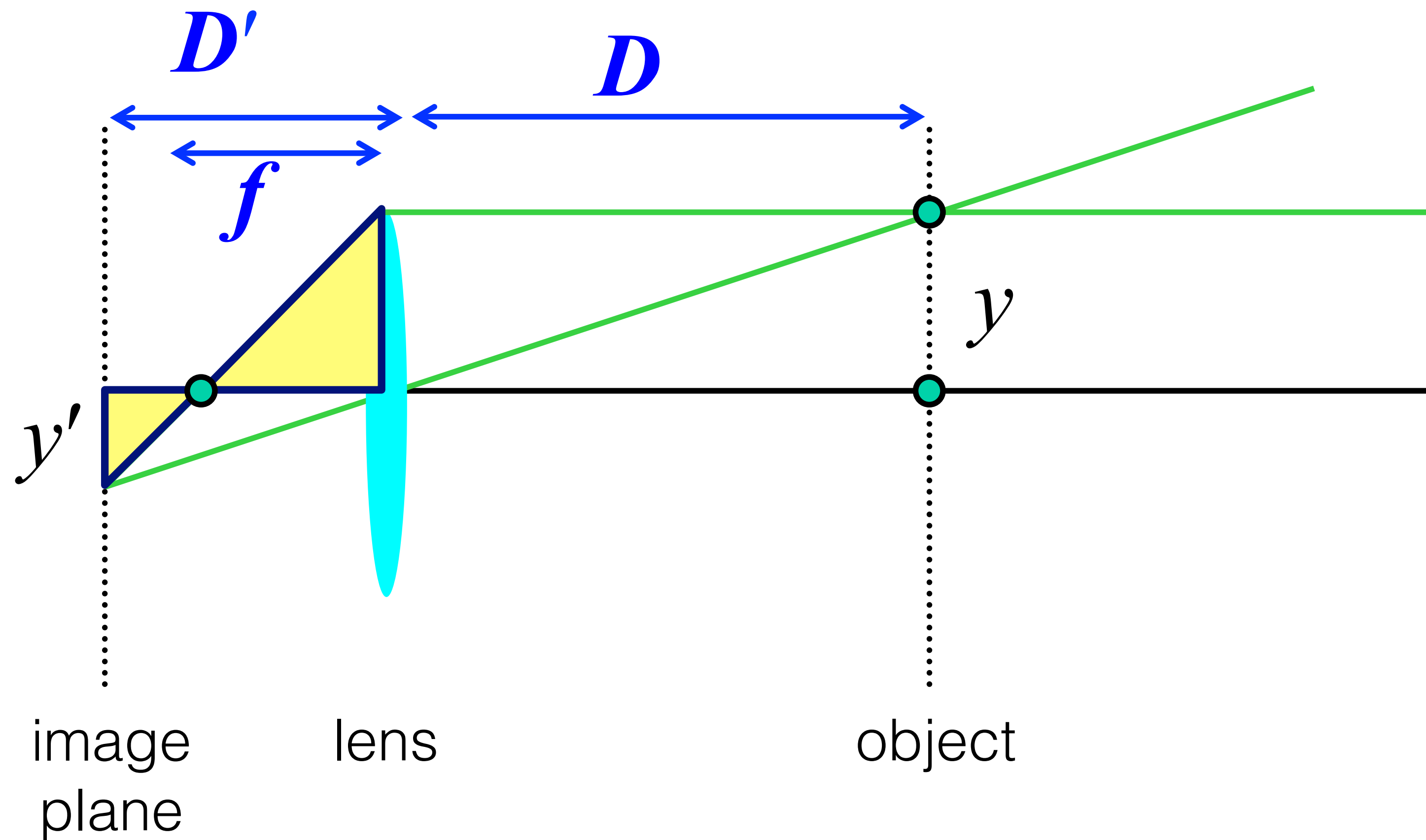




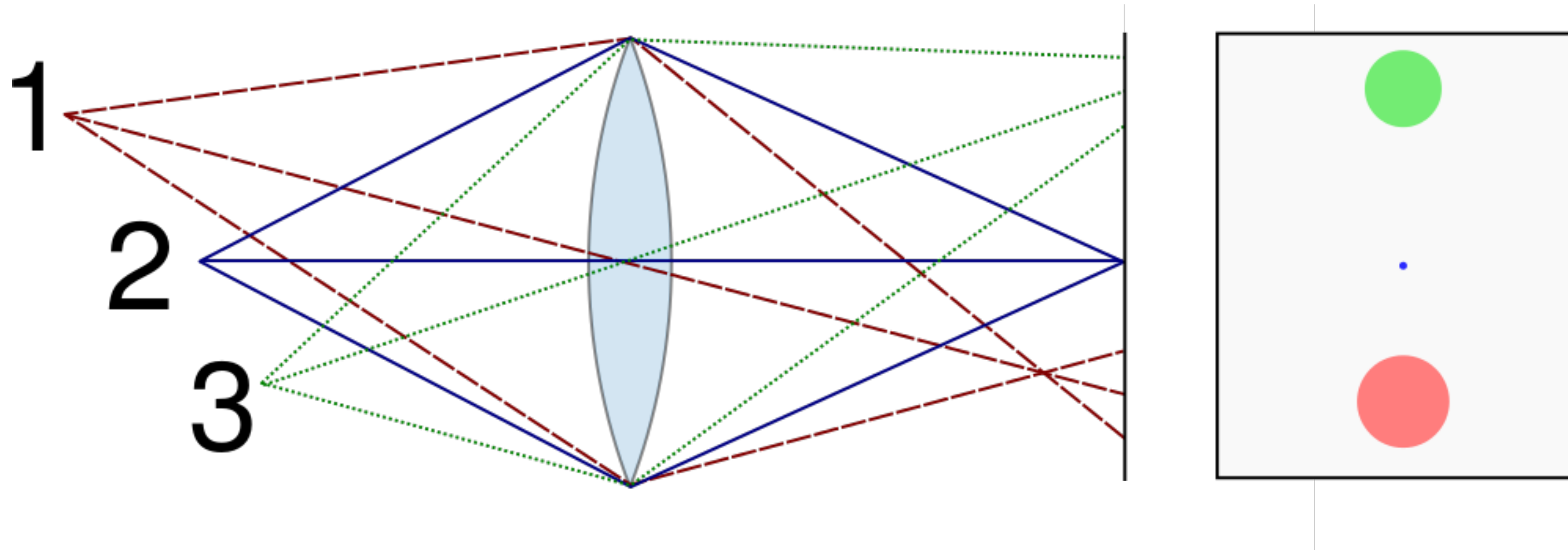
# Thin lens formula

$$\frac{1}{D'} + \frac{1}{D} = \frac{1}{f}$$

Any point satisfying the thin lens equation is in focus



# Depth of field



DOF is the distance between the nearest and farthest objects in a scene that appear acceptably sharp in an image



# Depth of field

Narrow Depth of Field



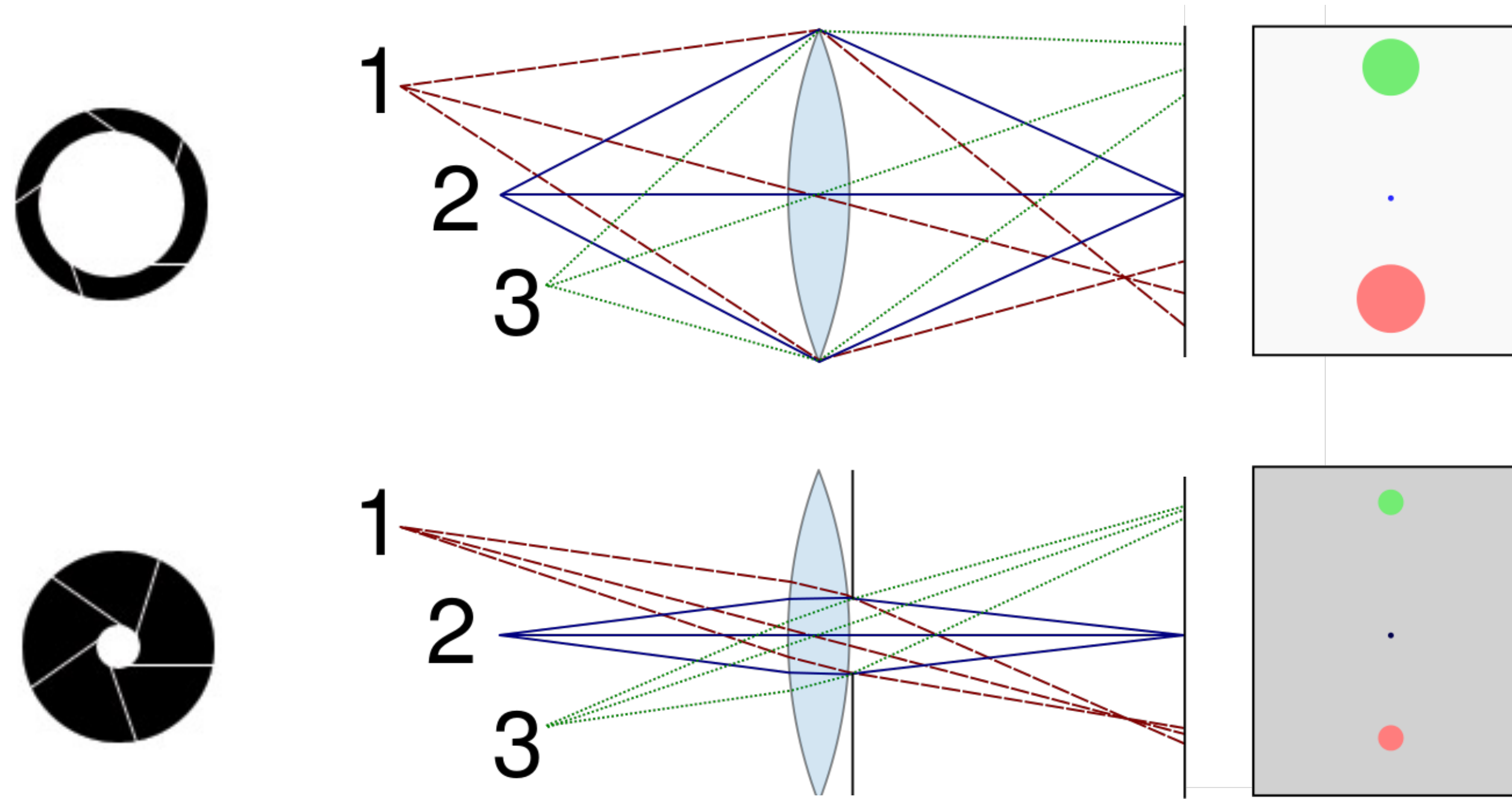
Wide Depth of Field



Photos by Monoram



# Controlling depth of field



## Changing the aperture size affects the depth of field

- A smaller aperture increases the range in which the object is approximately in focus
- But small aperture reduces the amount of light — need to increase the exposure for contrast
- Pinhole camera has an infinite depth of field



# Varying the aperture



Large aperture = small DOF



Small aperture = large DOF



# iPhone portrait mode

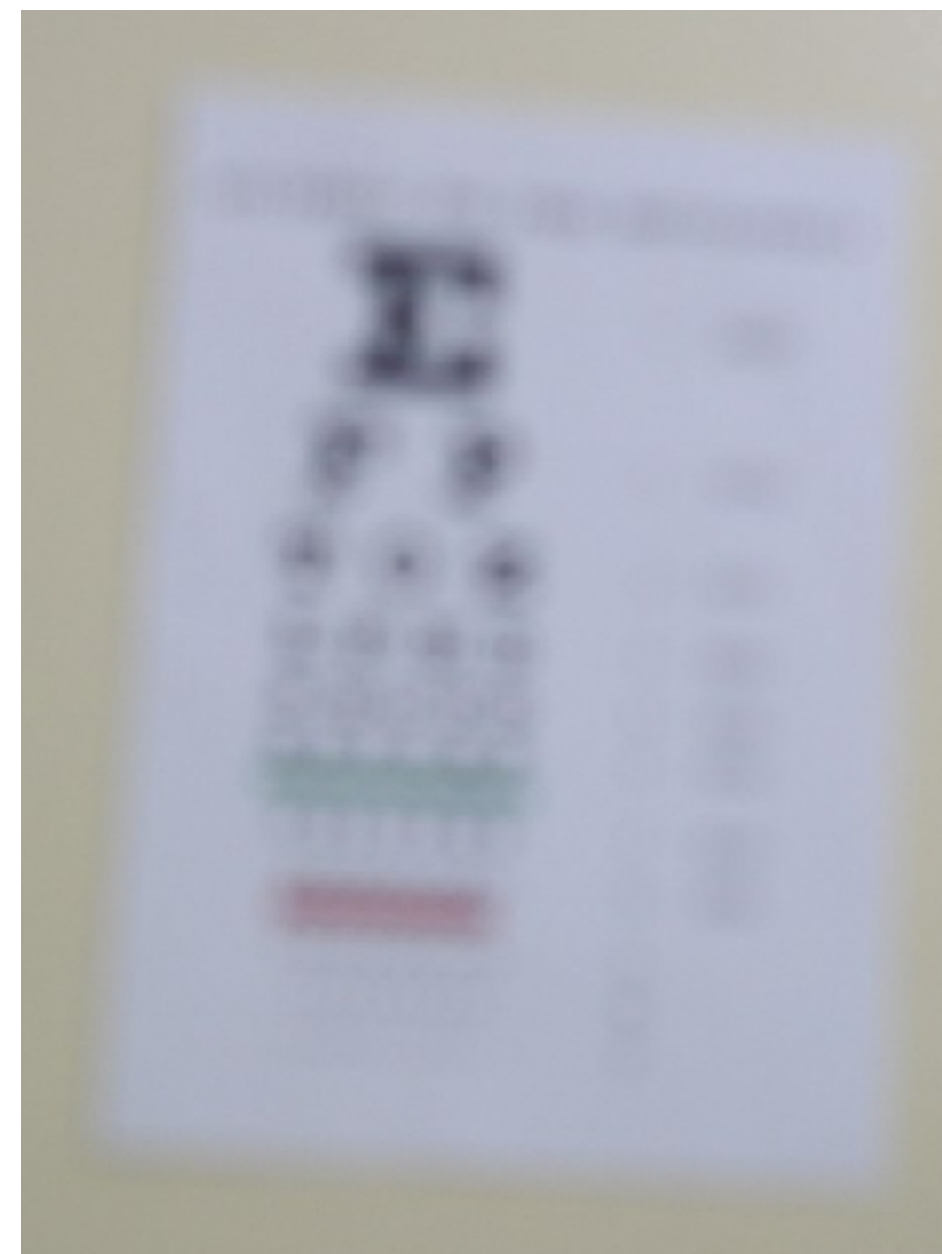
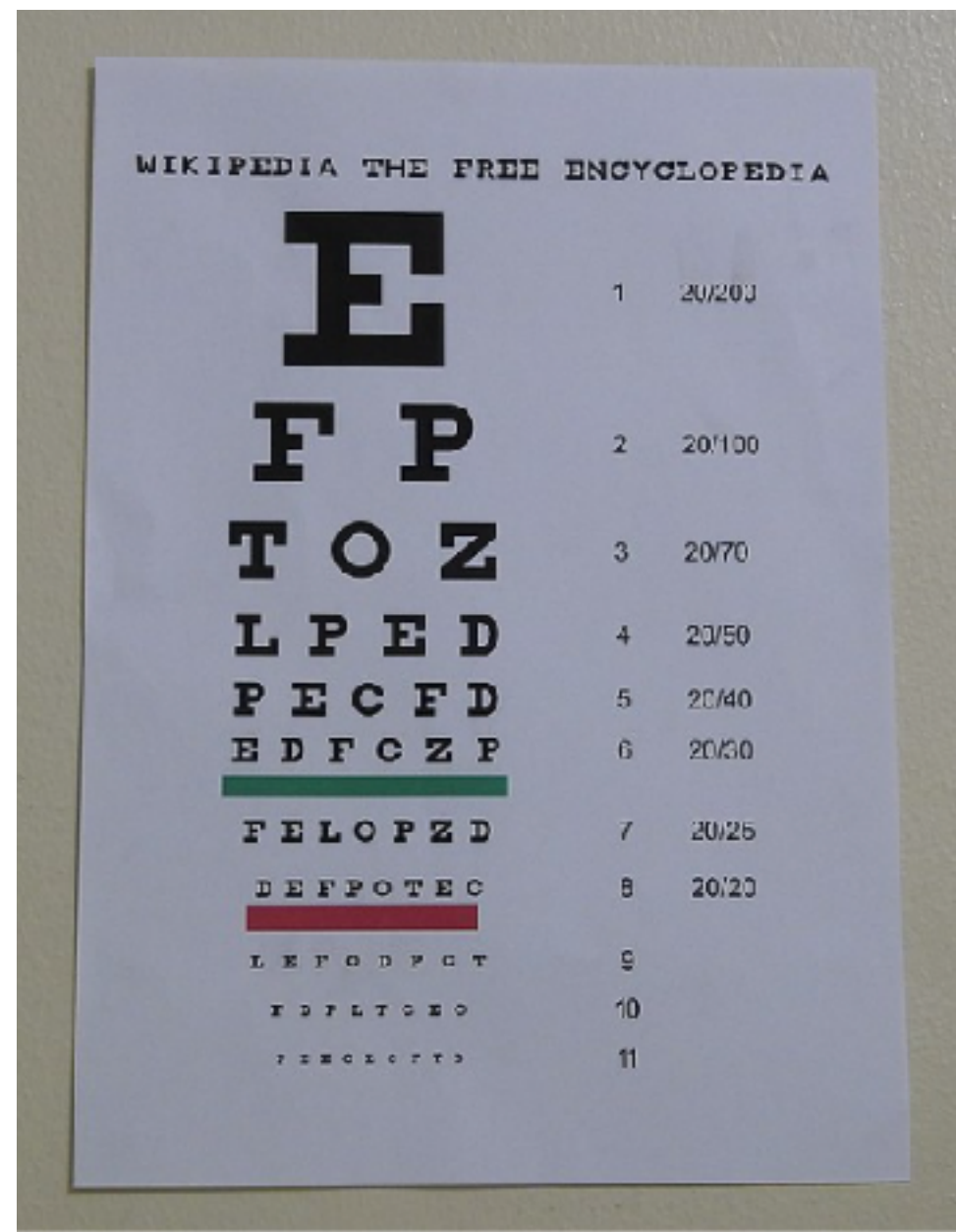


<http://www.businessinsider.com/apple-iphone-portrait-mode-explained-2017-10>

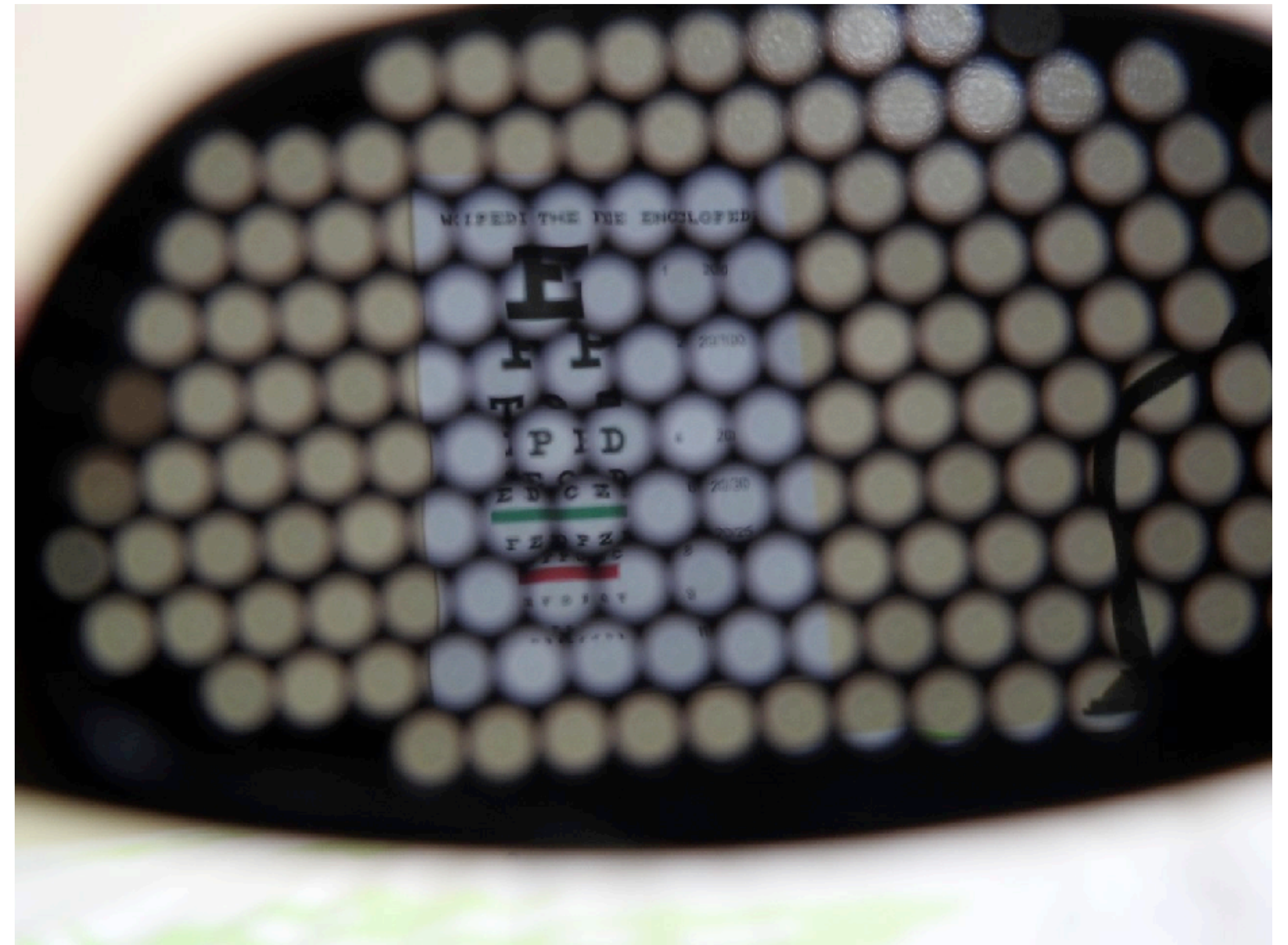


# Pinhole glasses

[https://en.wikipedia.org/wiki/Pinhole\\_glasses](https://en.wikipedia.org/wiki/Pinhole_glasses)



Out of focus

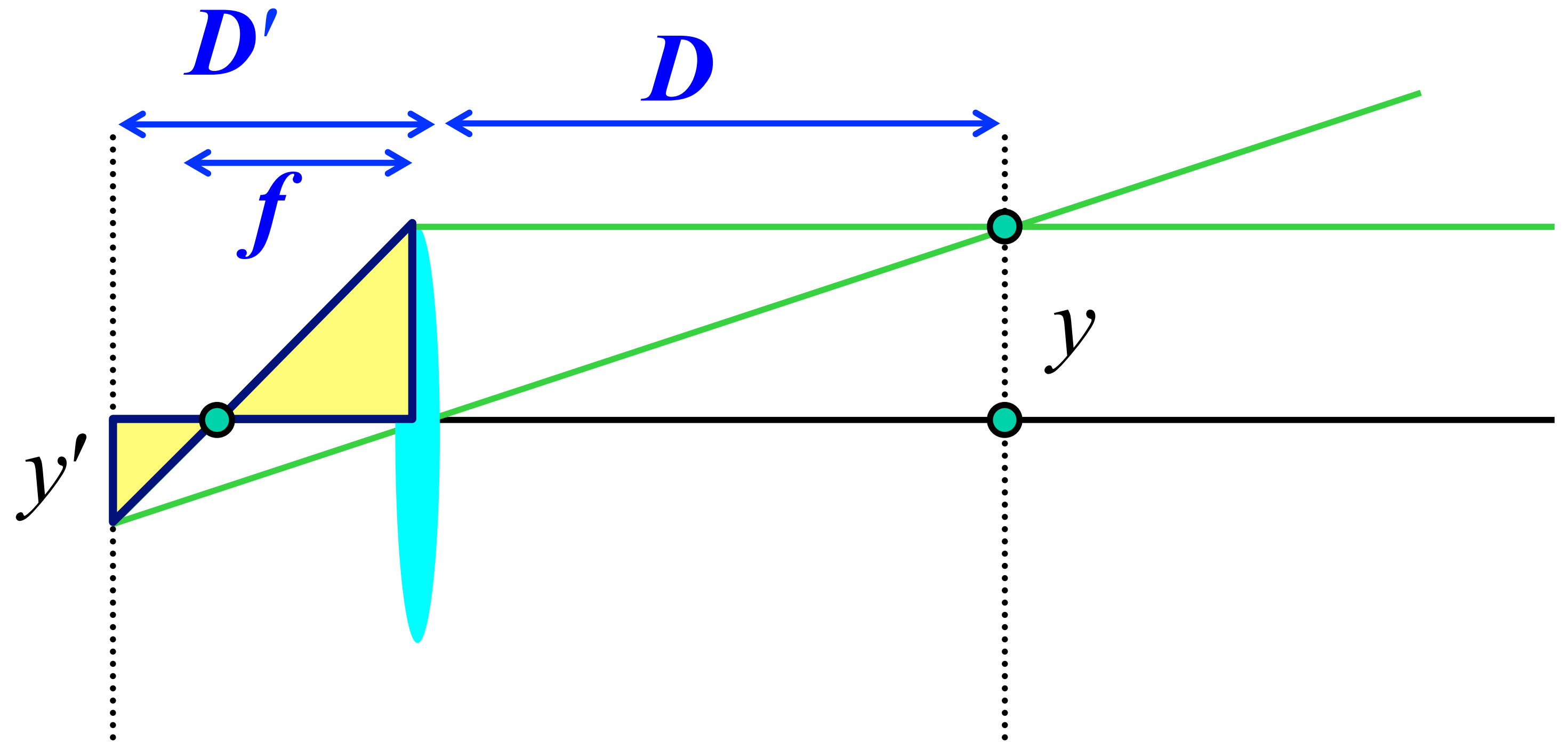


In focus, but darker



# Controlling depth of field

$$\frac{1}{D'} + \frac{1}{D} = \frac{1}{f}$$



DOF depends on the distance of the object ( $D$ ) and the focal length ( $f$ ) of the camera

- Objects far away have a larger depth of field
- Increasing the focal length reduces the depth of field



# Fake miniature photography



"Jodhpur rooftops" by Paul Goyette



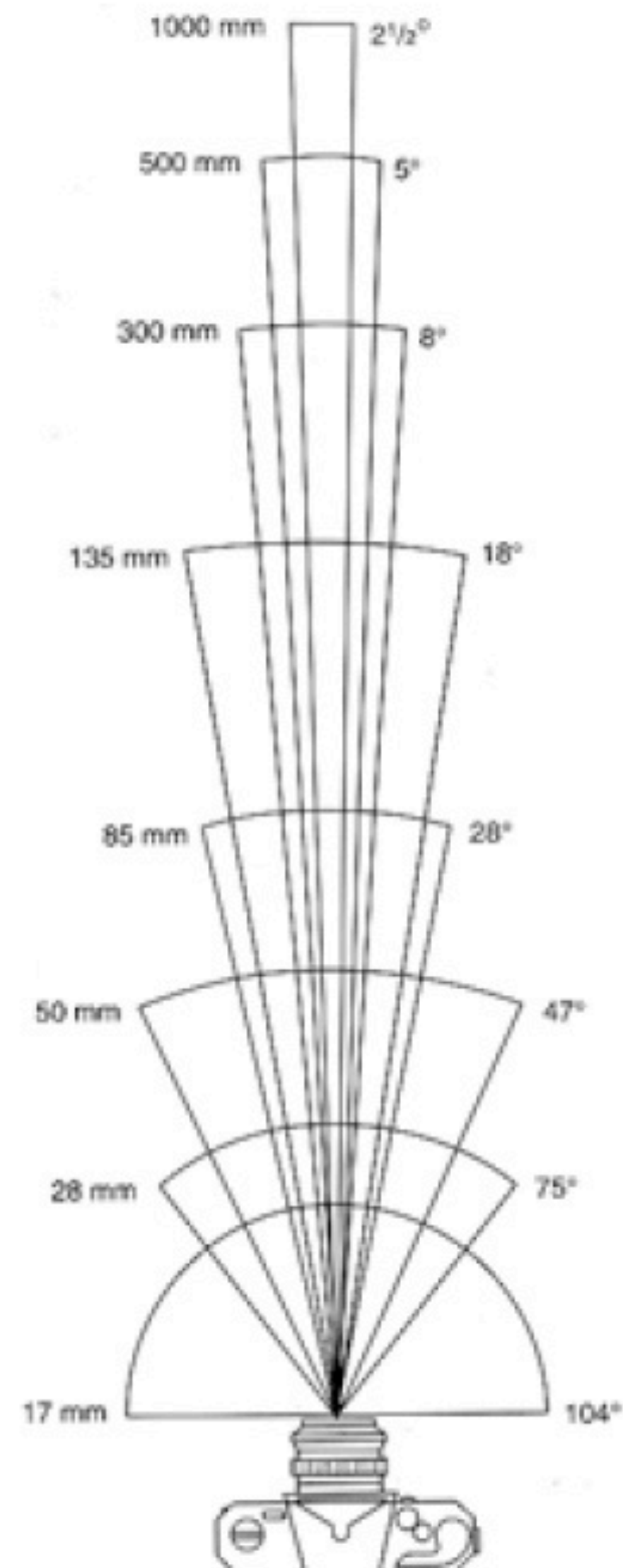








# Field of view



17mm



28mm



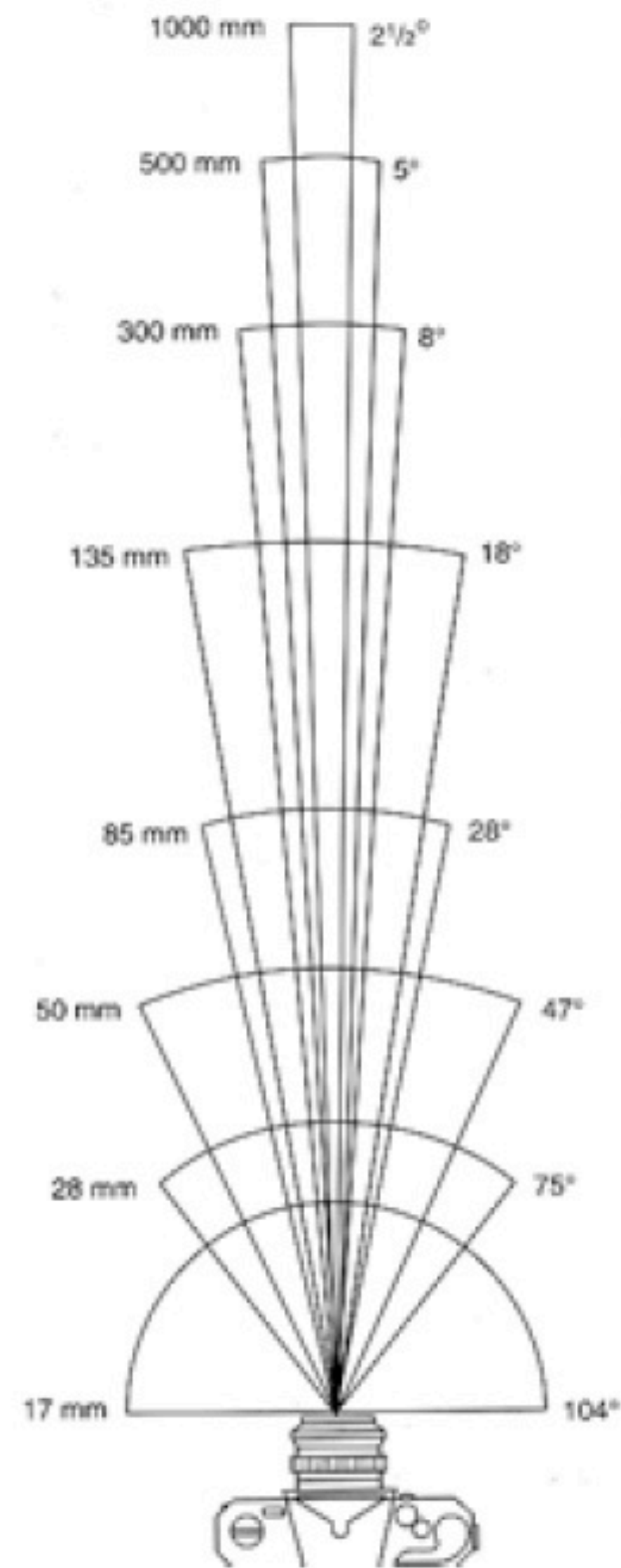
50mm



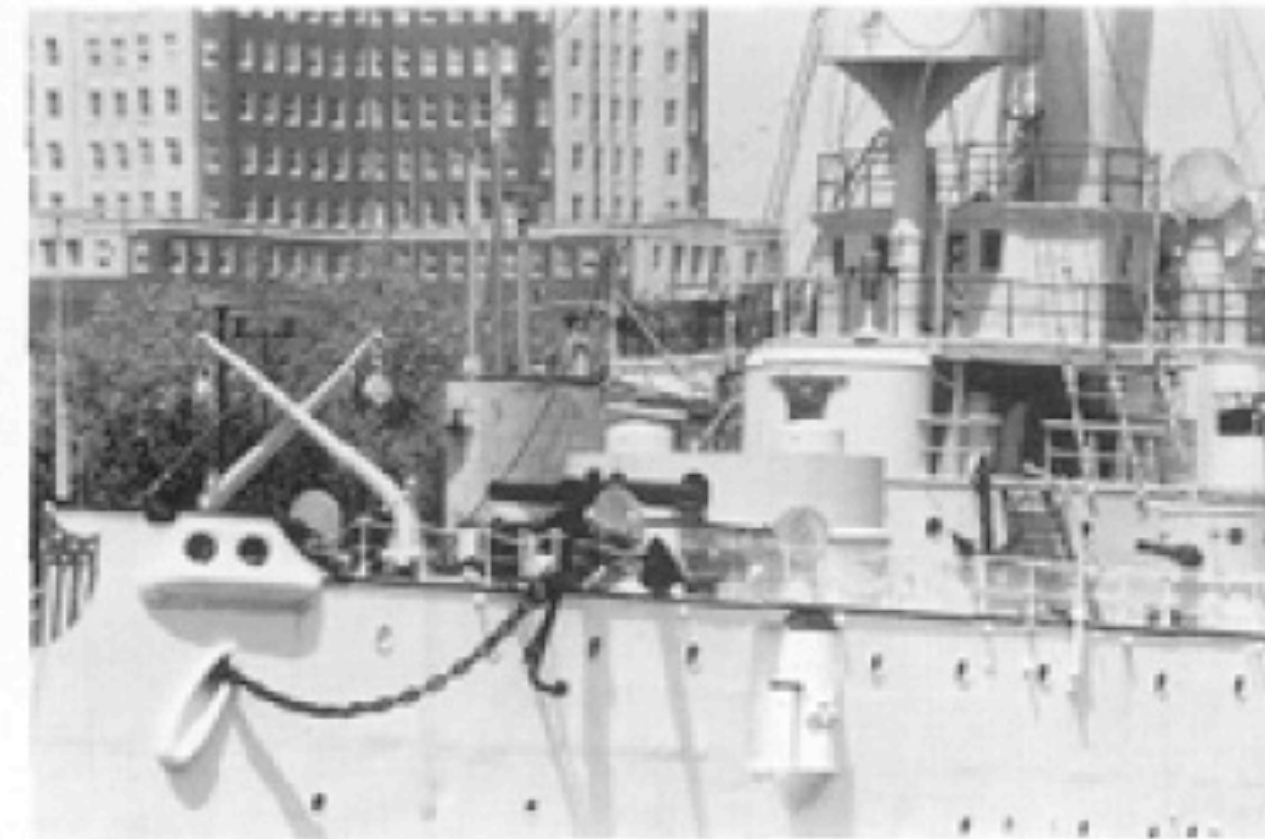
85mm



# Field of view



135mm



300mm

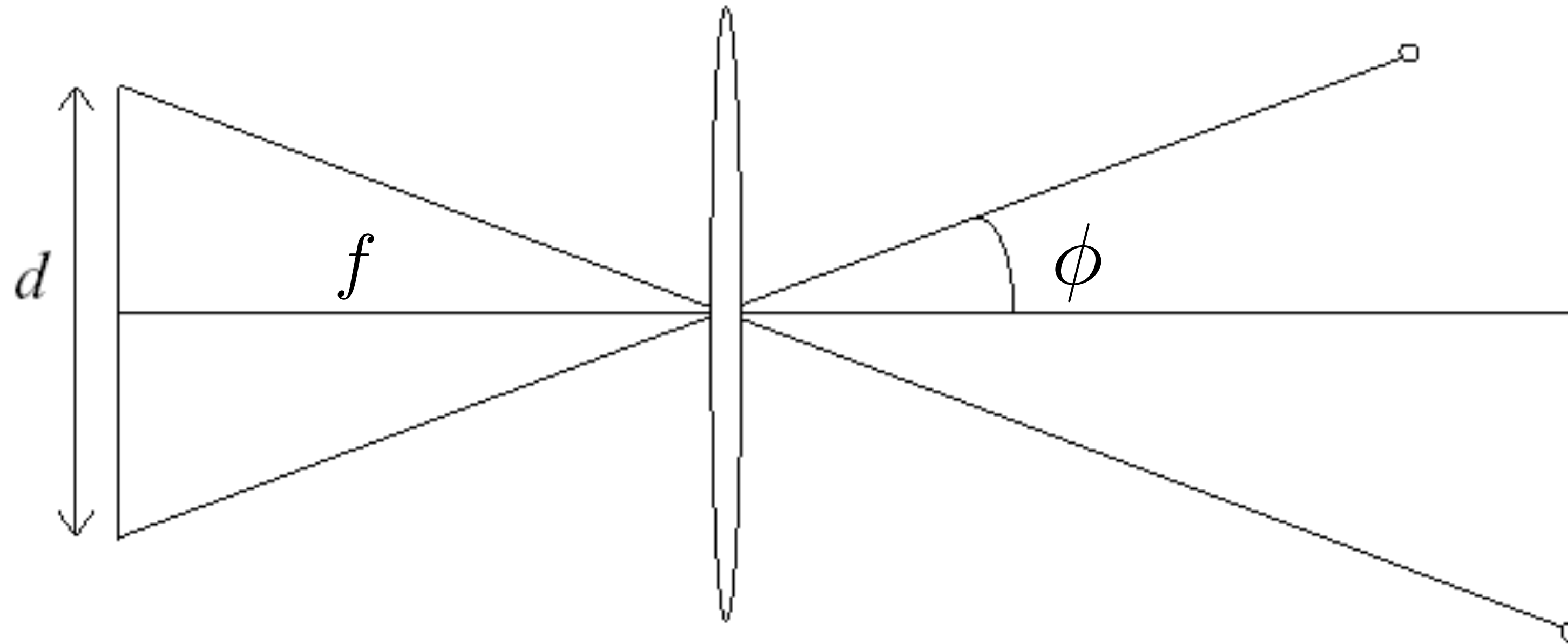


50mm



28mm

# Field of view



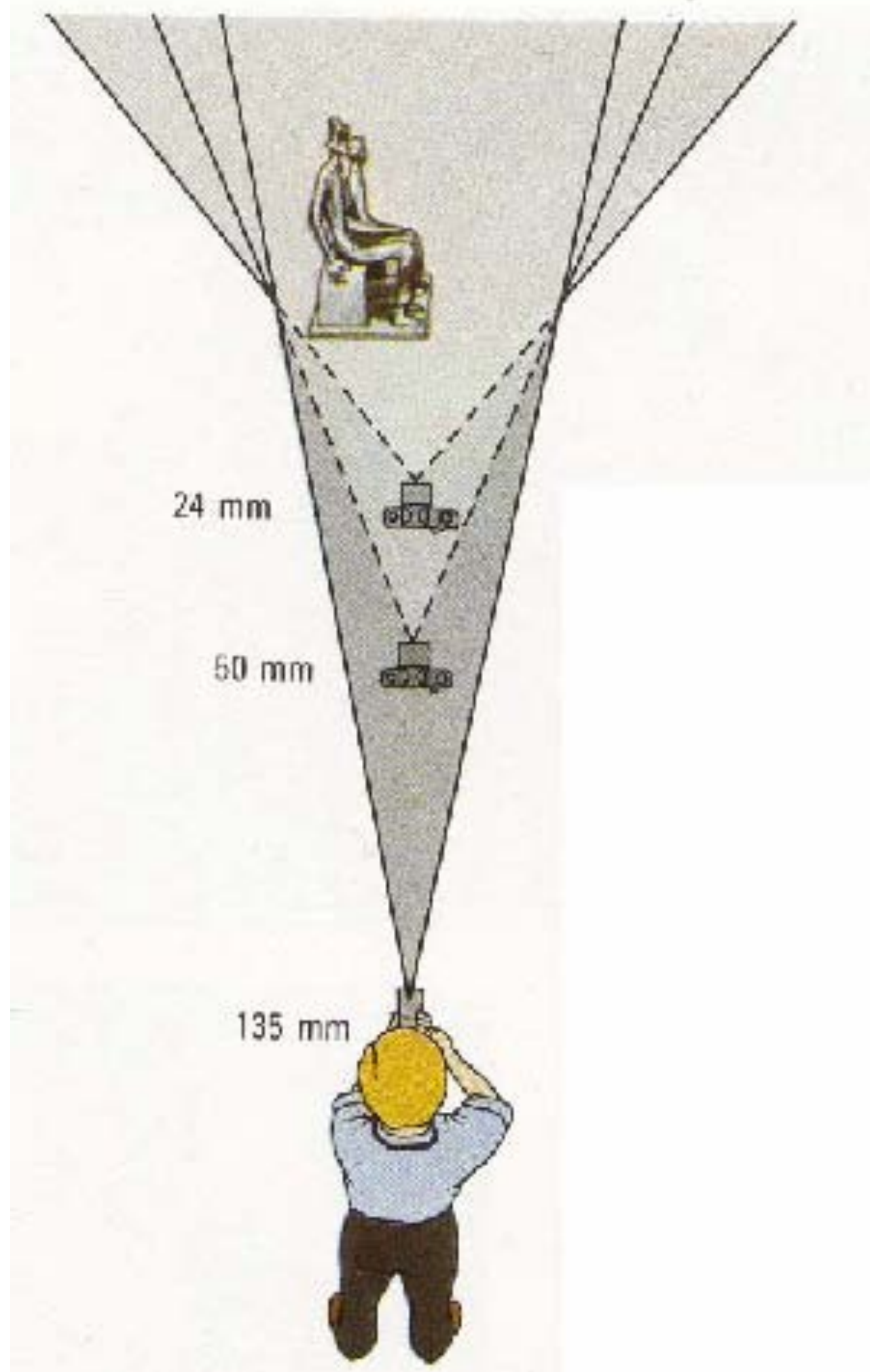
Field of view (FOV) depends on the focal length and the size of the camera retina

$$\phi = \tan^{-1} \left( \frac{d}{2f} \right)$$

Larger focal length = smaller FOV



# Field of view, focal length



$$\tan(\phi) \times 2f = d$$

$$\sim (\phi) \times 2f = d$$



Large FOV, small  $f$  — Camera close to the car



Small FOV, large  $f$  — Camera far from the car



# Same effect for faces



wide-angle  
(short focus)



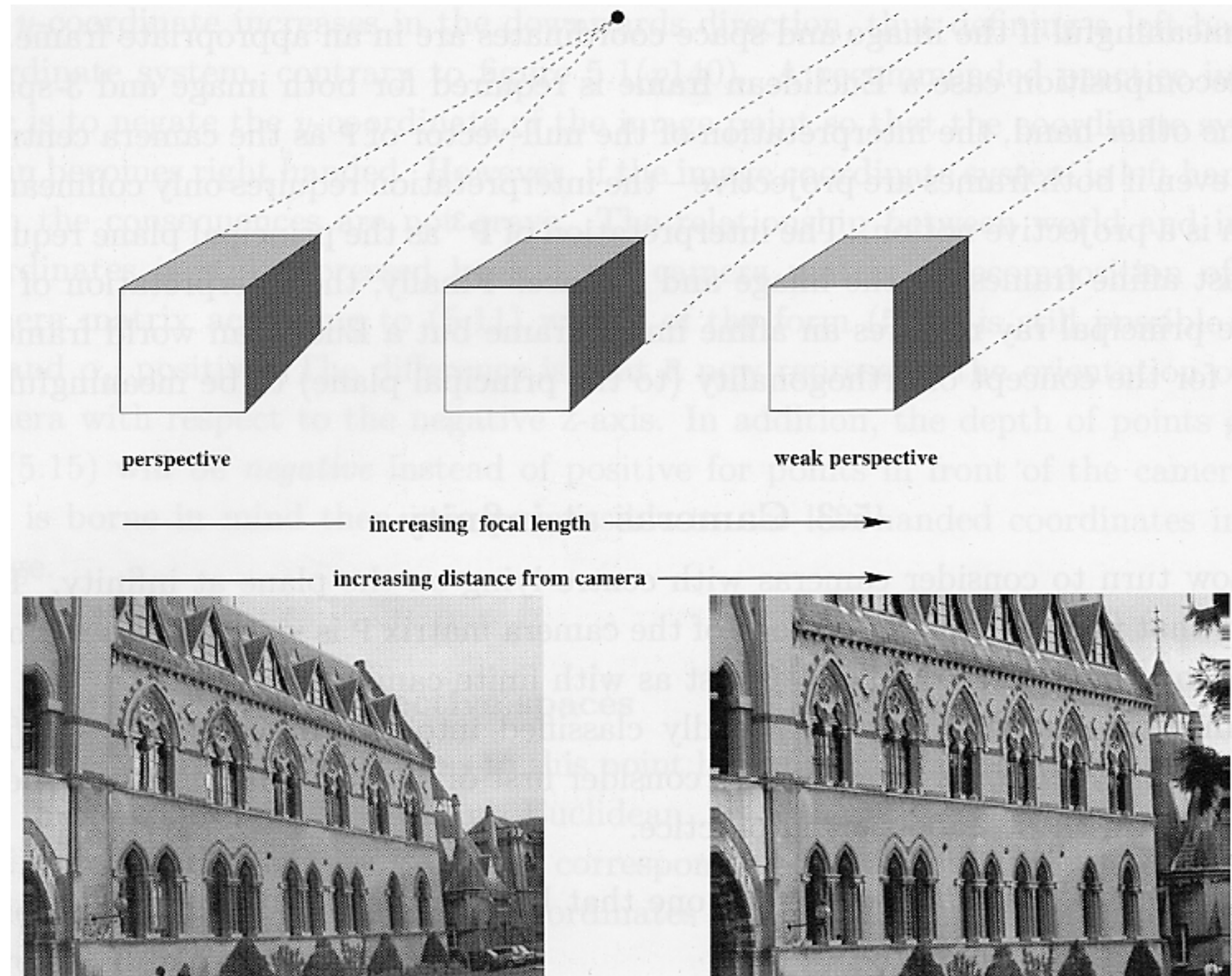
standard



telephoto  
(long focus)



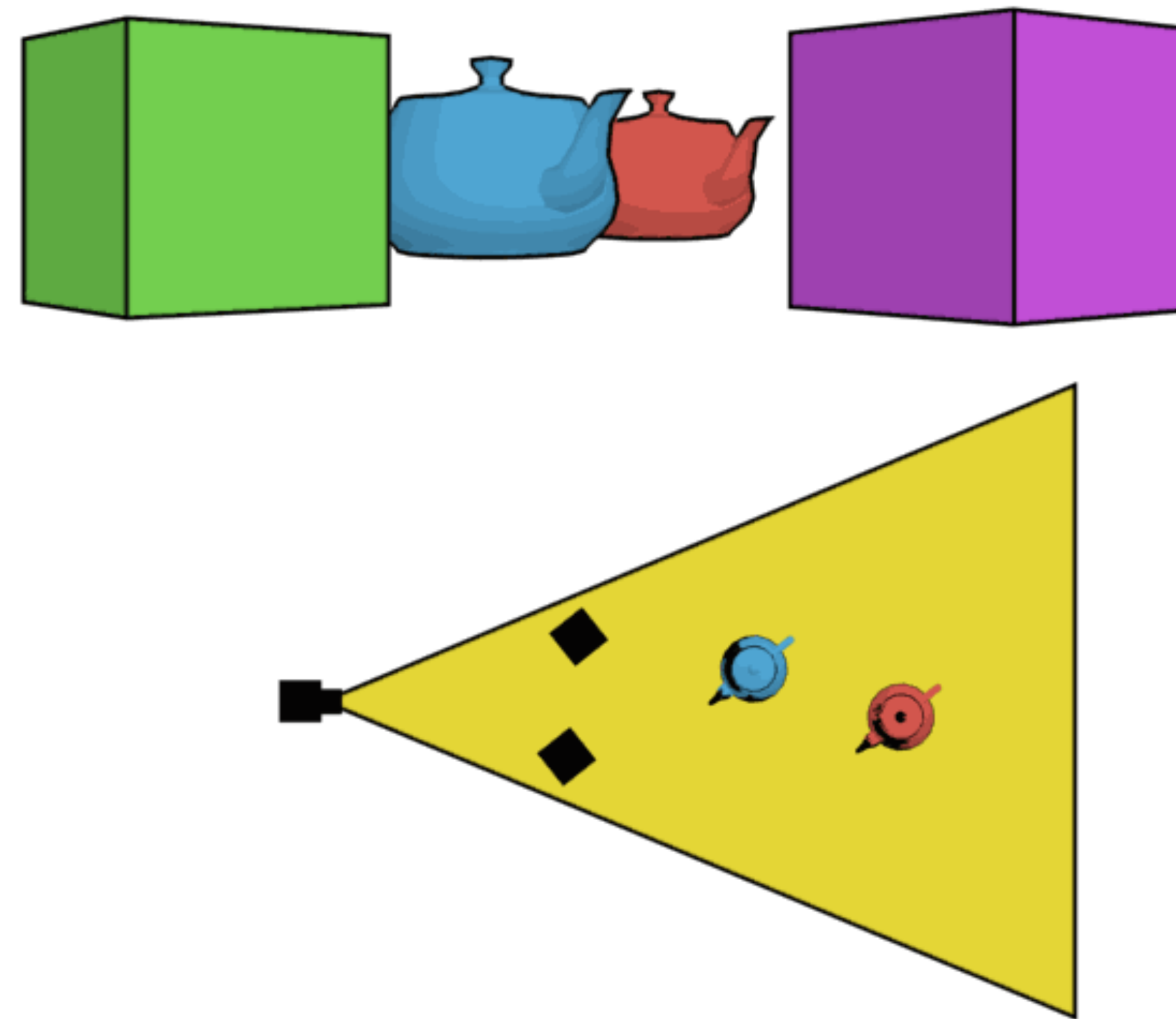
# Approximating an orthographic camera





# The dolly zoom

Continuously adjusting the camera focal length while the camera moves away from (or towards) the subject



[http://en.wikipedia.org/wiki/Dolly\\_zoom](http://en.wikipedia.org/wiki/Dolly_zoom)



# The dolly zoom

Continuously adjusting the camera focal length while the camera moves away from (or towards) the subject

Also called as “Vertigo shot” or the “Hitchcock shot”



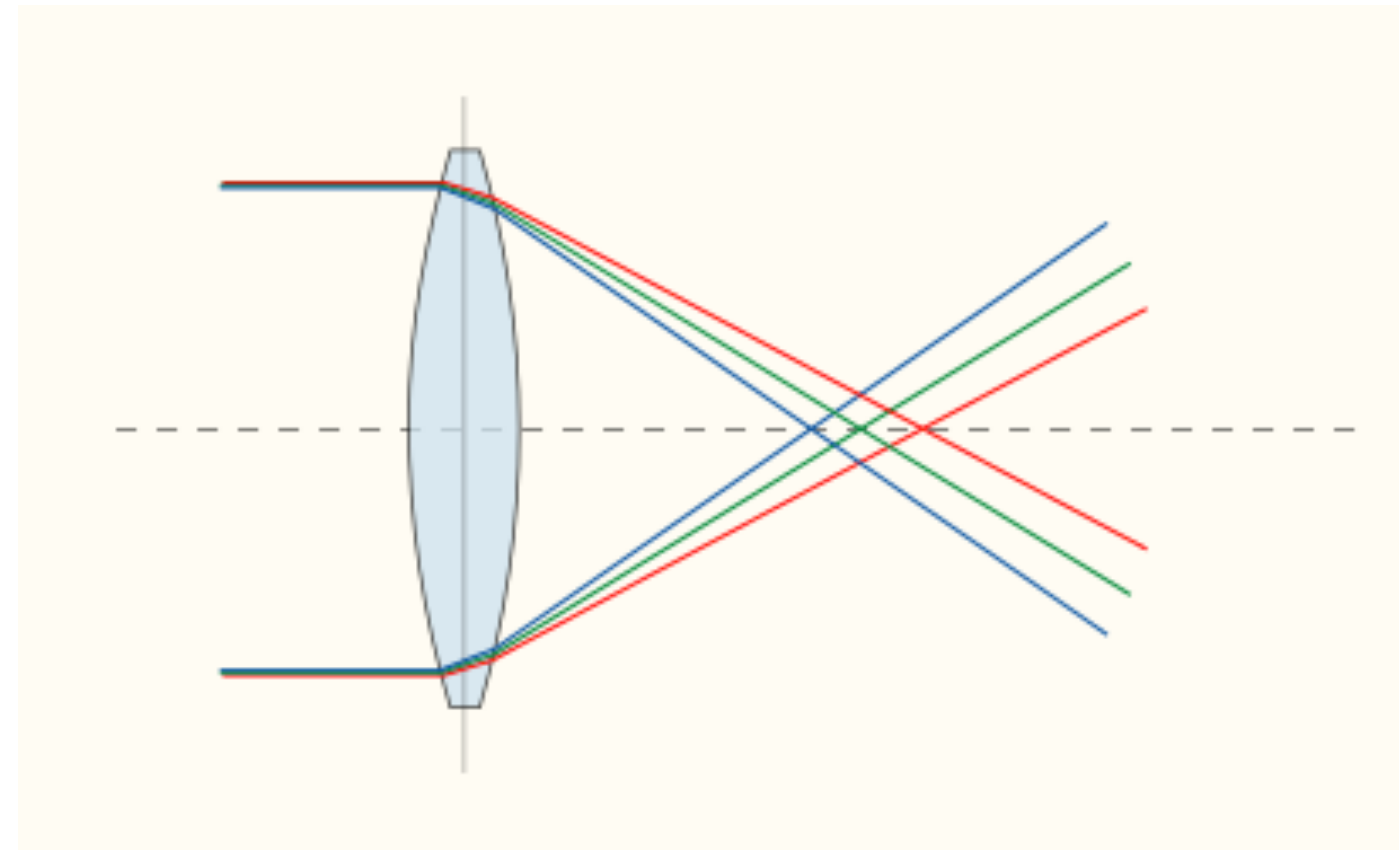
[Example of dolly zoom from Goodfellas](#)

[Example of dolly zoom from La Haine](#)



# Lens flaws: Chromatic aberration

Lens have different refractive indices ([Snell's law](#)) for different wavelengths: causes color fringing



near lens center



near lens outer

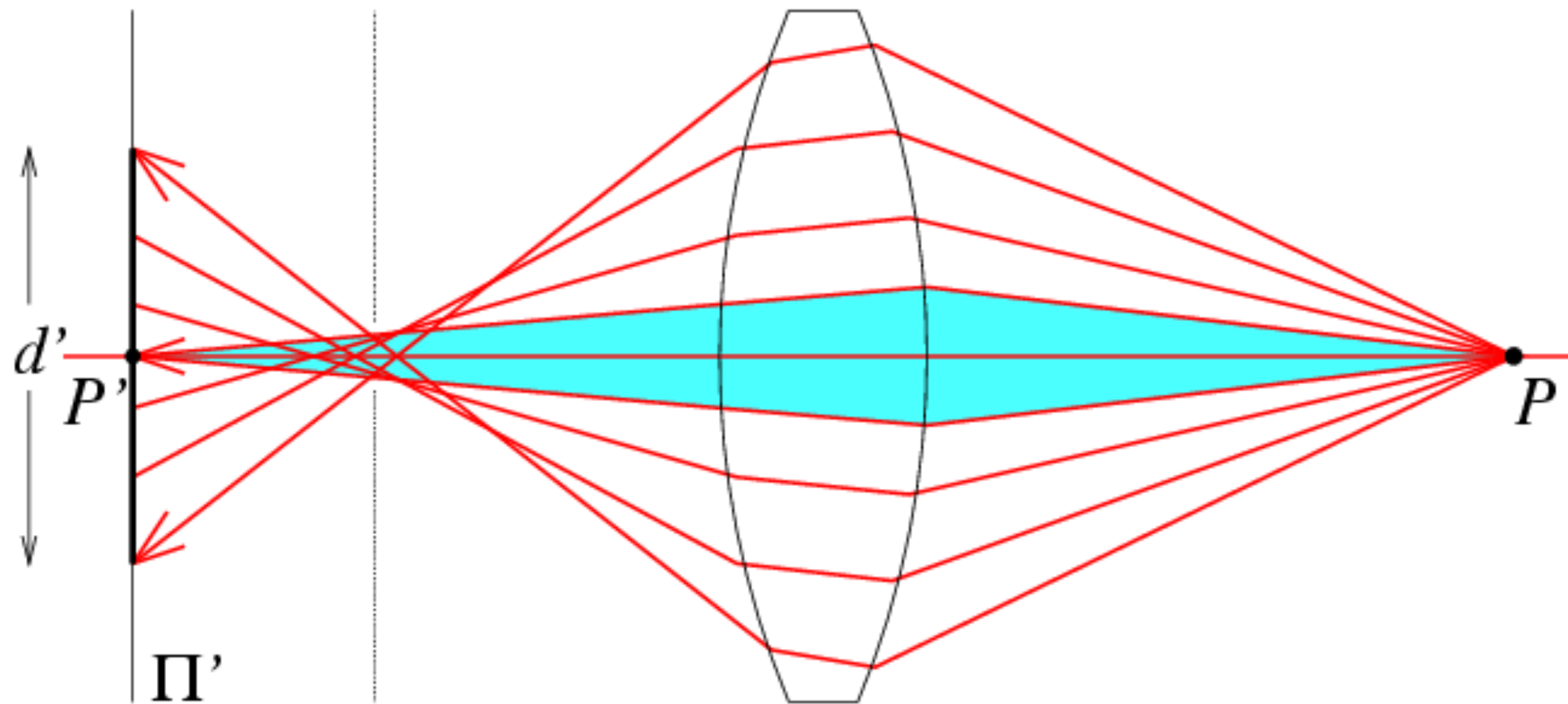




# Lens flaws: Spherical aberration

Spherical lenses don't focus light perfectly (thin lens model)

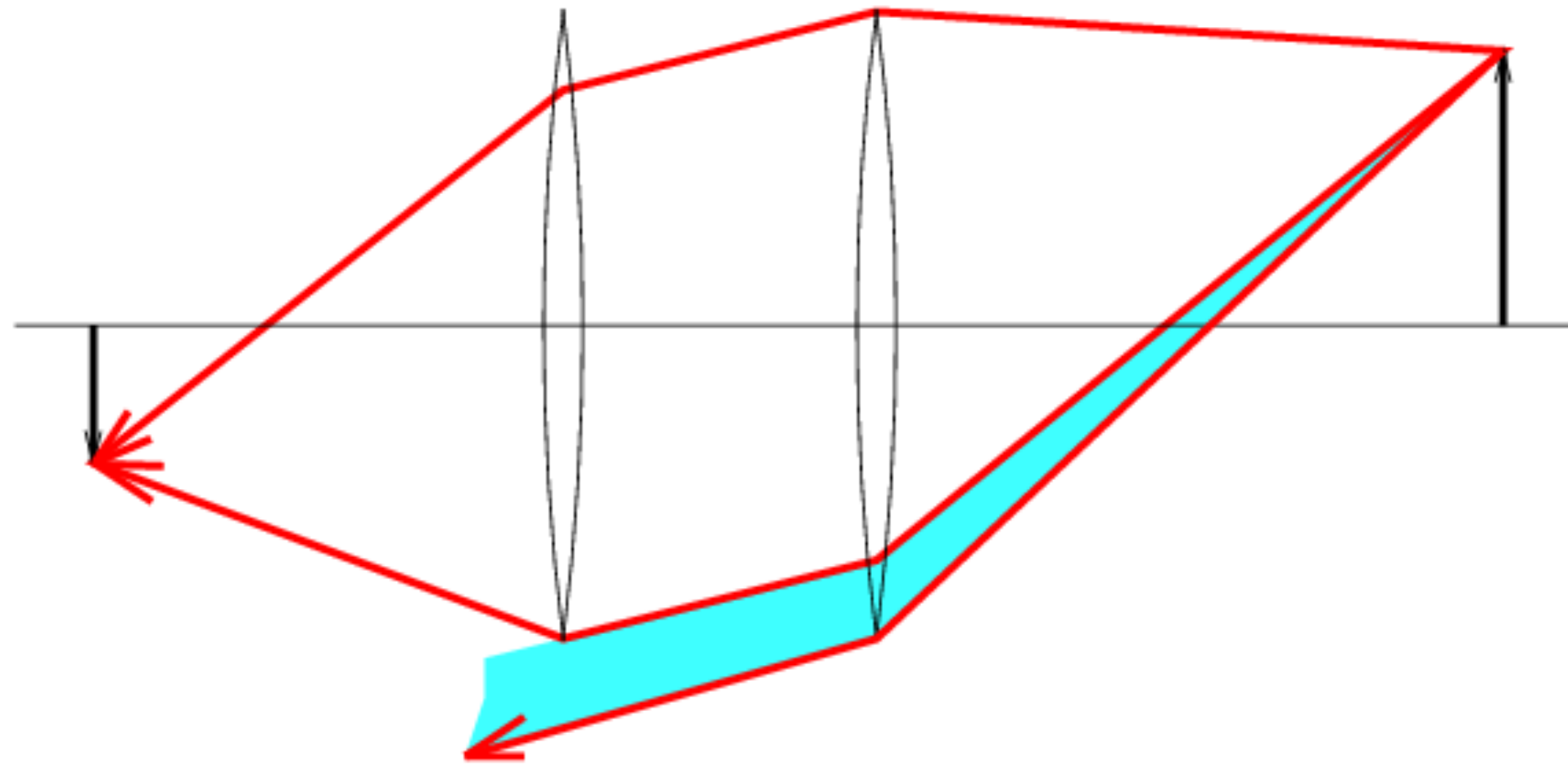
- Rays farther from the optical axis are focussed closer



objects lack sharpness

# Lens flaws: Vignetting

Reduction of image brightness in the periphery



Not all rays reach the sensor

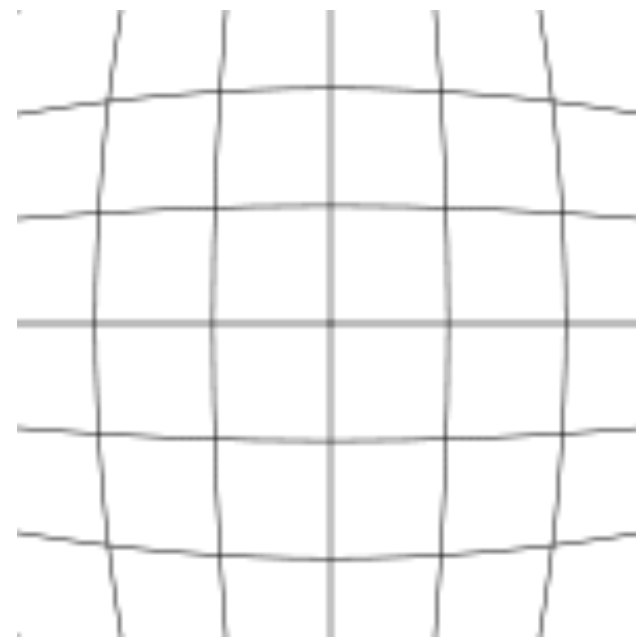




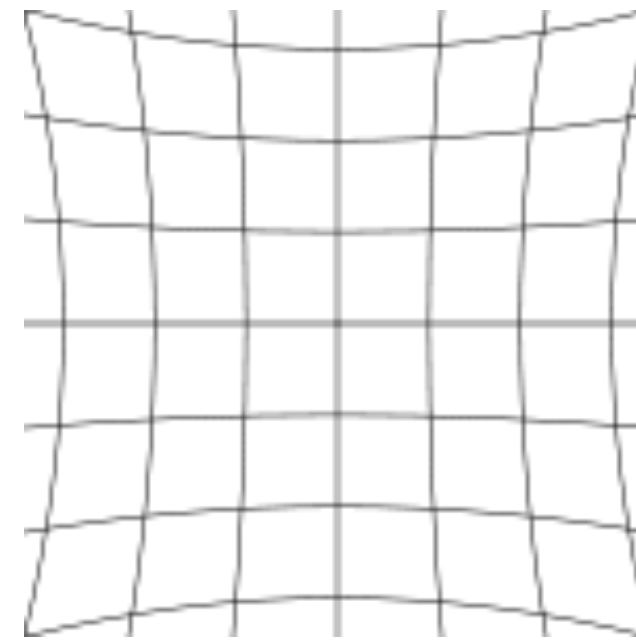
# Lens flaws: Radial distortion

Caused by asymmetry of lenses

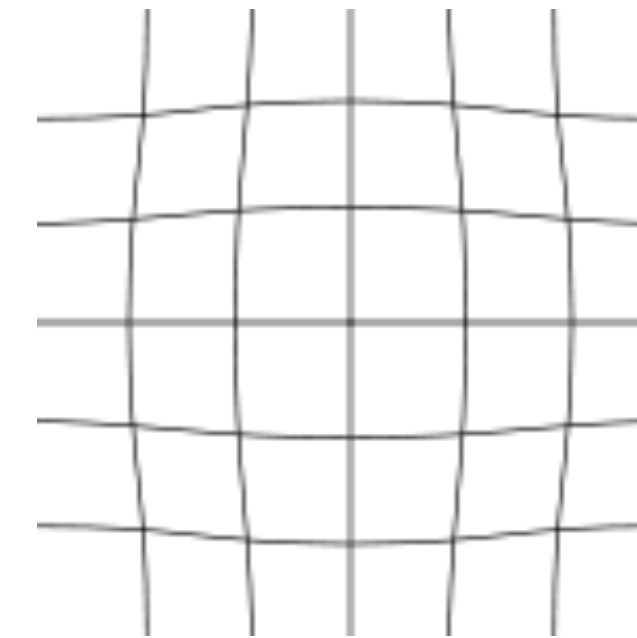
Deviations are most noticeable near the periphery



**barrel distortion**



**pincushion distortion**



**mustache distortion**



<http://clanegesselphotography.blogspot.com/>



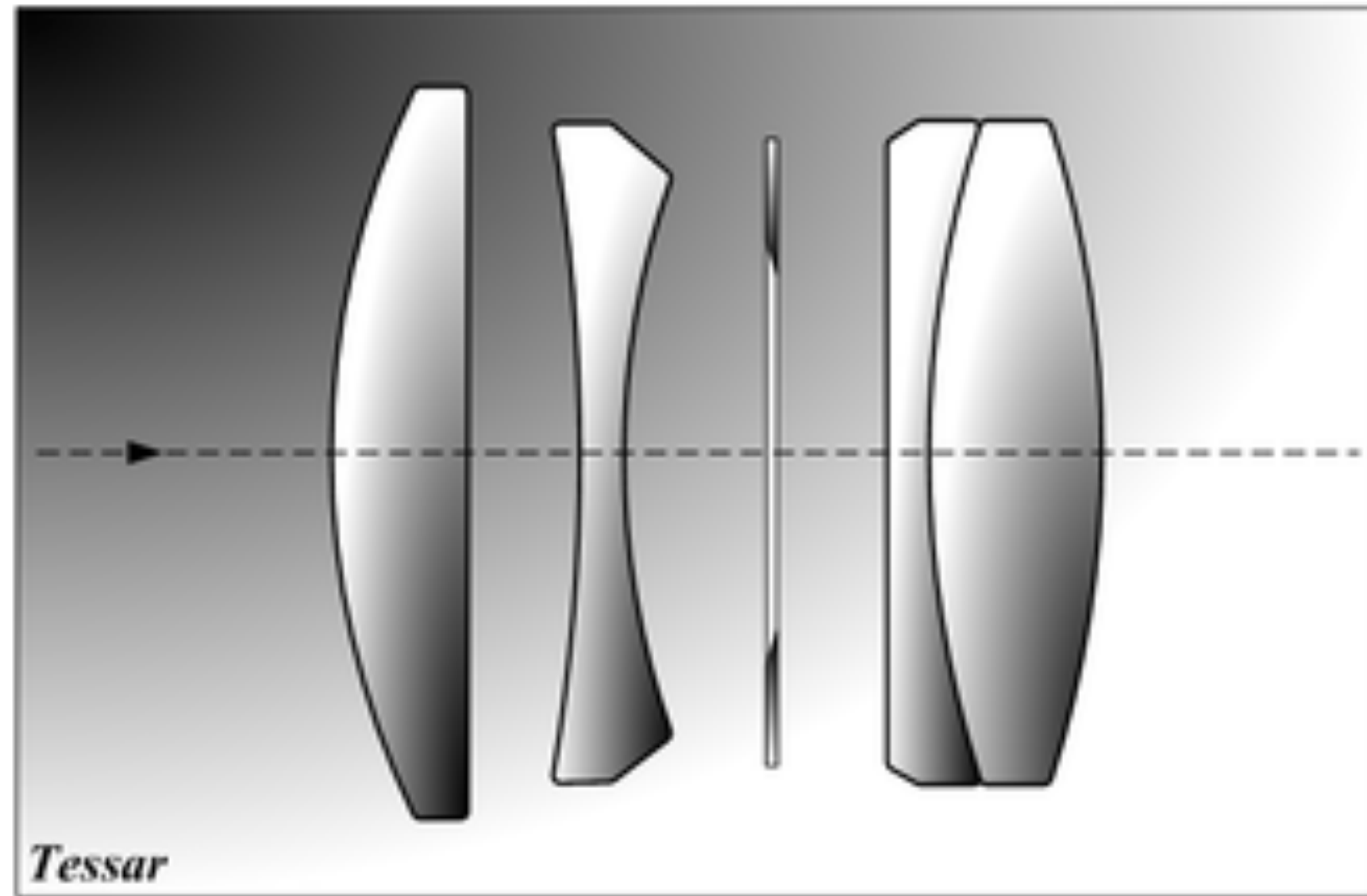
<http://parkingandyou.com>



# Real photographic lens

Many uses: cameras, telescopes, microscopes, etc

fixed focal length



Example of a prime lens - Carl Zeiss [Tessar](#)

adjustable zoom



[Nikkor](#) 28-200 mm zoom lens, extended to 200 mm at left and collapsed to 28 mm focal length at right.

[http://en.wikipedia.org/wiki/Zoom\\_lens](http://en.wikipedia.org/wiki/Zoom_lens)



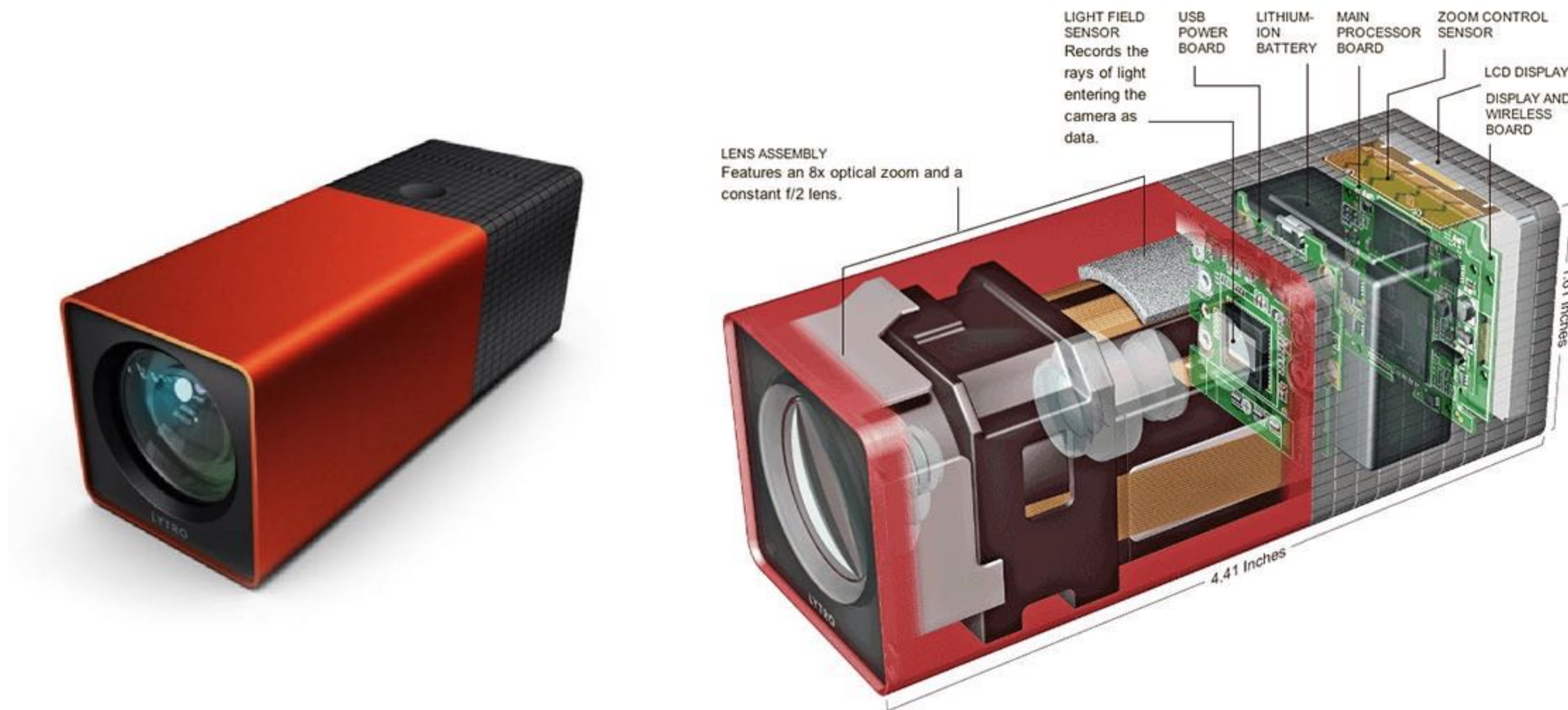
# Lytro camera

Light field camera: capture intensity along each direction of the light

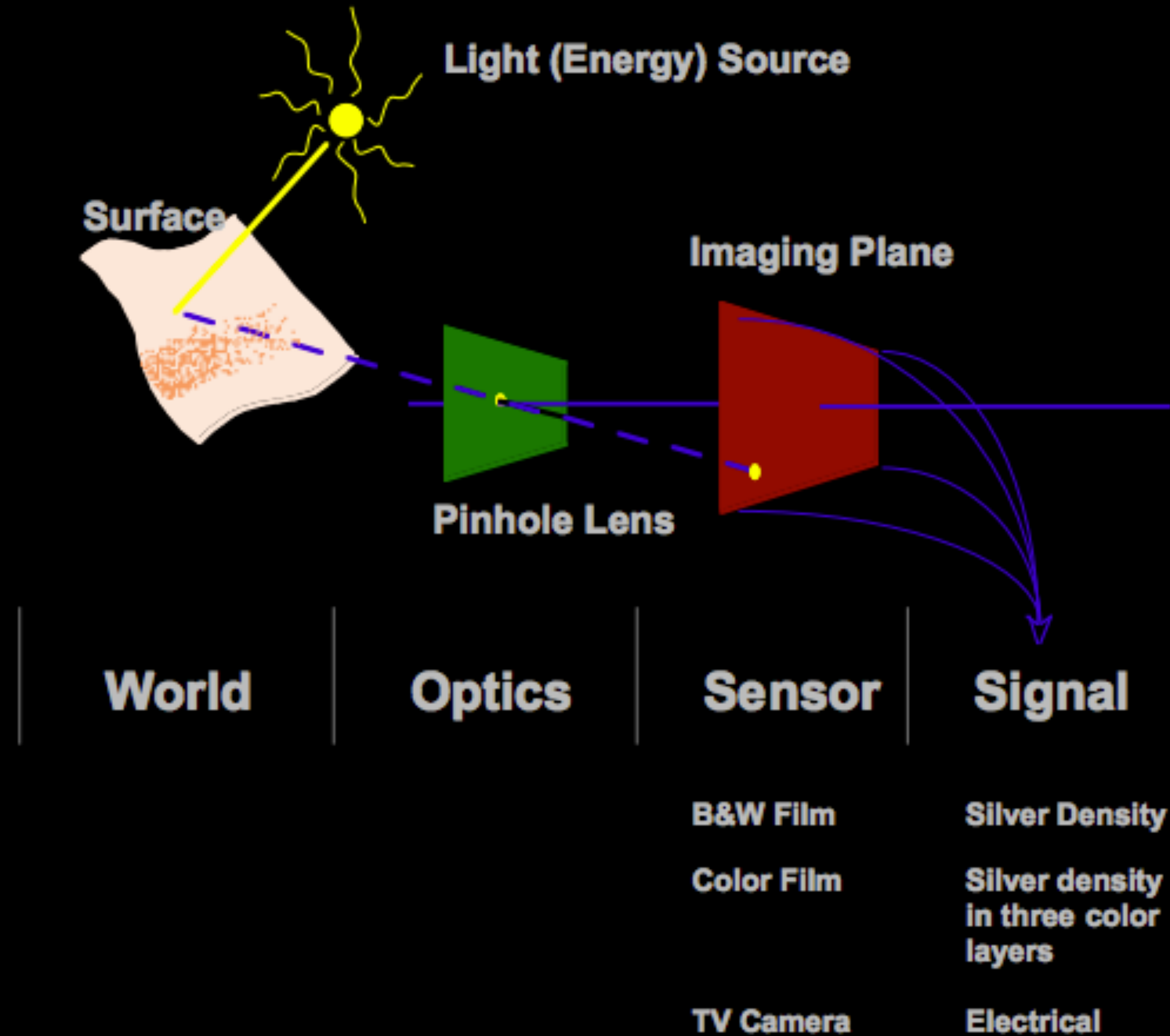
- Traditional cameras integrate light coming from all directions

A captured light field allows you re-render an image post-hoc

- <https://pictures.lytro.com/lytro/collections/41/pictures/1088670>



# Image capture





# Measuring light

**Photographic film** — strip of transparent plastic film base coated on one side with a gelatin emulsion containing light-sensitive materials

Creates a latent image when exposed to light for short duration

Films are then chemically developed to form a photograph

Early films/photographic plates could *only* capture intensity





# An incredible story...



Sergey Prokudin-Gorsky  
(1912)

1909



Nicholas II of Russia





Dagestani Sunni Muslim,  
1904<sup>[27][47]</sup>



Greek women and children  
harvesting tea in Chakvi,  
Georgia, circa 1905–1915



Italian woman in formal dress,  
posed, standing near gate, circa  
1905–1915



Jewish children with their  
teacher in Samarkand, circa  
1905–1915



Minister of the Interior,  
Bukhara, circa 1905–1915



Armenian woman in national  
costume near Artvin (then in  
the Russian Empire, now in  
Turkey), circa 1905–1915



Zindan (prison) in Bukhara, 1907



A chapel in Myatusovo, 1909



Staraya Ladoga  
Fortress, 1909



Staraya Ladoga Fortress,  
1909



Young Russian peasant  
women in a rural area along  
the Sheksna River near the  
small town of Kirillov, 1909



Church of St. John the  
Baptist on Malyshevaya Hill;  
Staraya Ladoga, 1909



The St Nicholas Monastery  
Staraya Ladoga, 1909



General view of the city of  
Perm, 1910



General view of the city of Perm  
from Gorodskie Gorki, 1910



Razguliai, outskirts of the  
city of Perm, 1910



Summertime location of  
the exchange in the city  
Perm, 1910



Staro-Sibirskaya Gate in the city  
of Perm, 1910



Headquarters of the Ural  
Railway Administration in the  
city of Perm, 1910



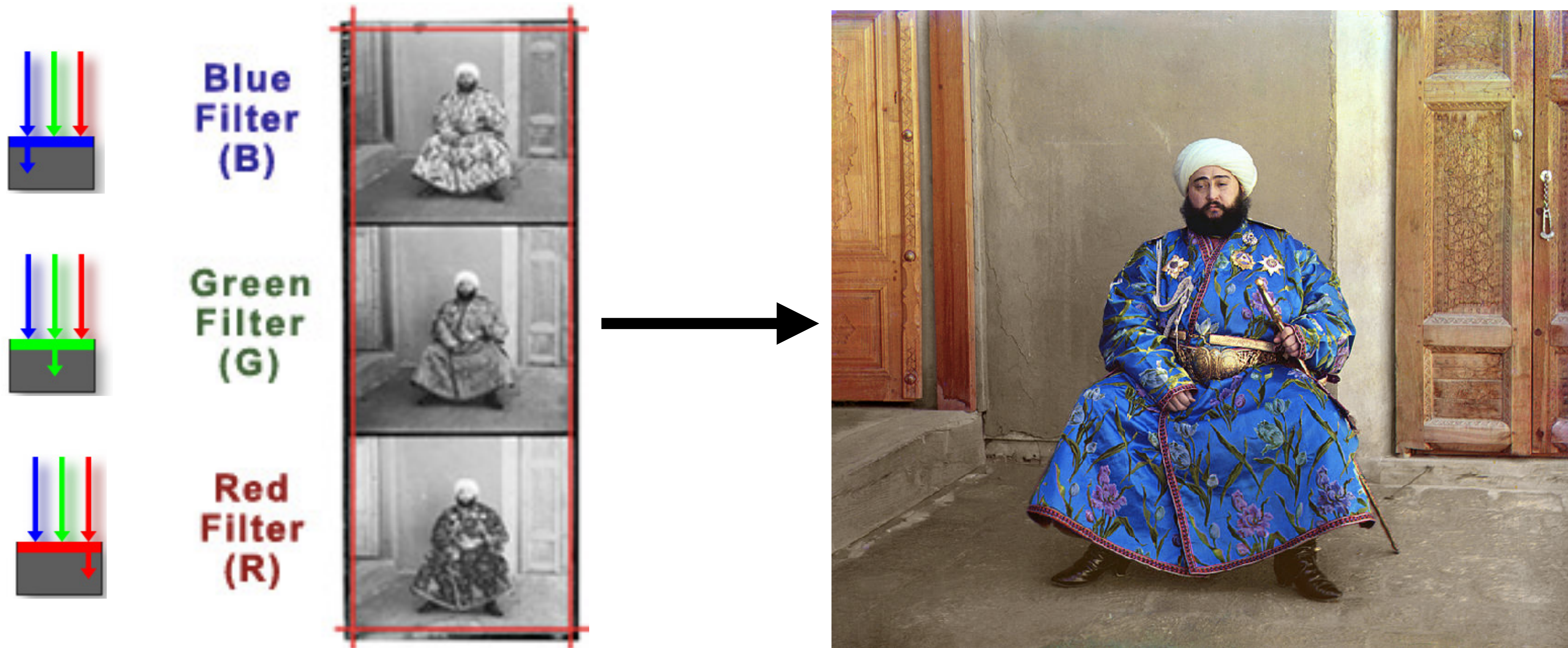
Mary Magdalene Church in  
the city Perm, 1910



# Early color photography — three color technique

Sergey Prokudin-Gorskii (1863-1944)

Photographs of the Russian empire (1909-1916)





# Only problem!





# Idea for alignment

Blue  
Filter  
(B)

Green  
Filter  
(G)

Red  
Filter  
(R)



Fix one channel (say **red**).

Assume that channels are only translated, i.e., no rotation, scaling, etc.

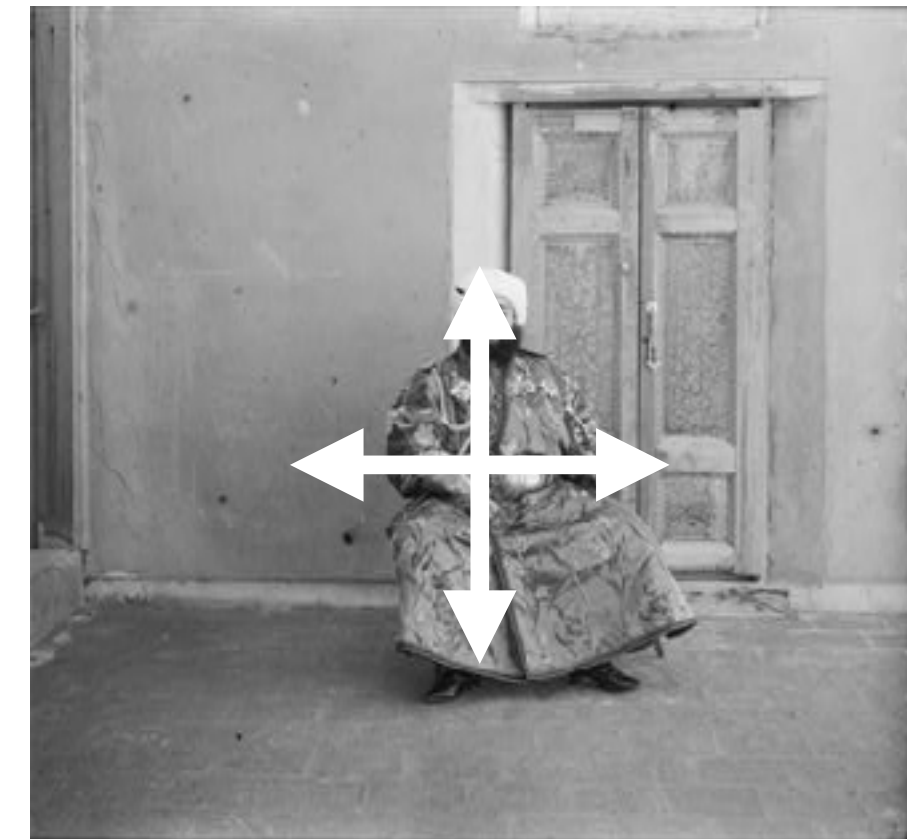
For each shift, say:  $x \in (-15, 15), y \in (-15, 15)$

- Measure similarity
- Pick the shift that *maximizes* similarity

**red**



**green**



Repeat for the **blue** channel



# How to measure similarity?

Measure similarity using Euclidean distance

Align a central region of the images to avoid boundary artifacts



red



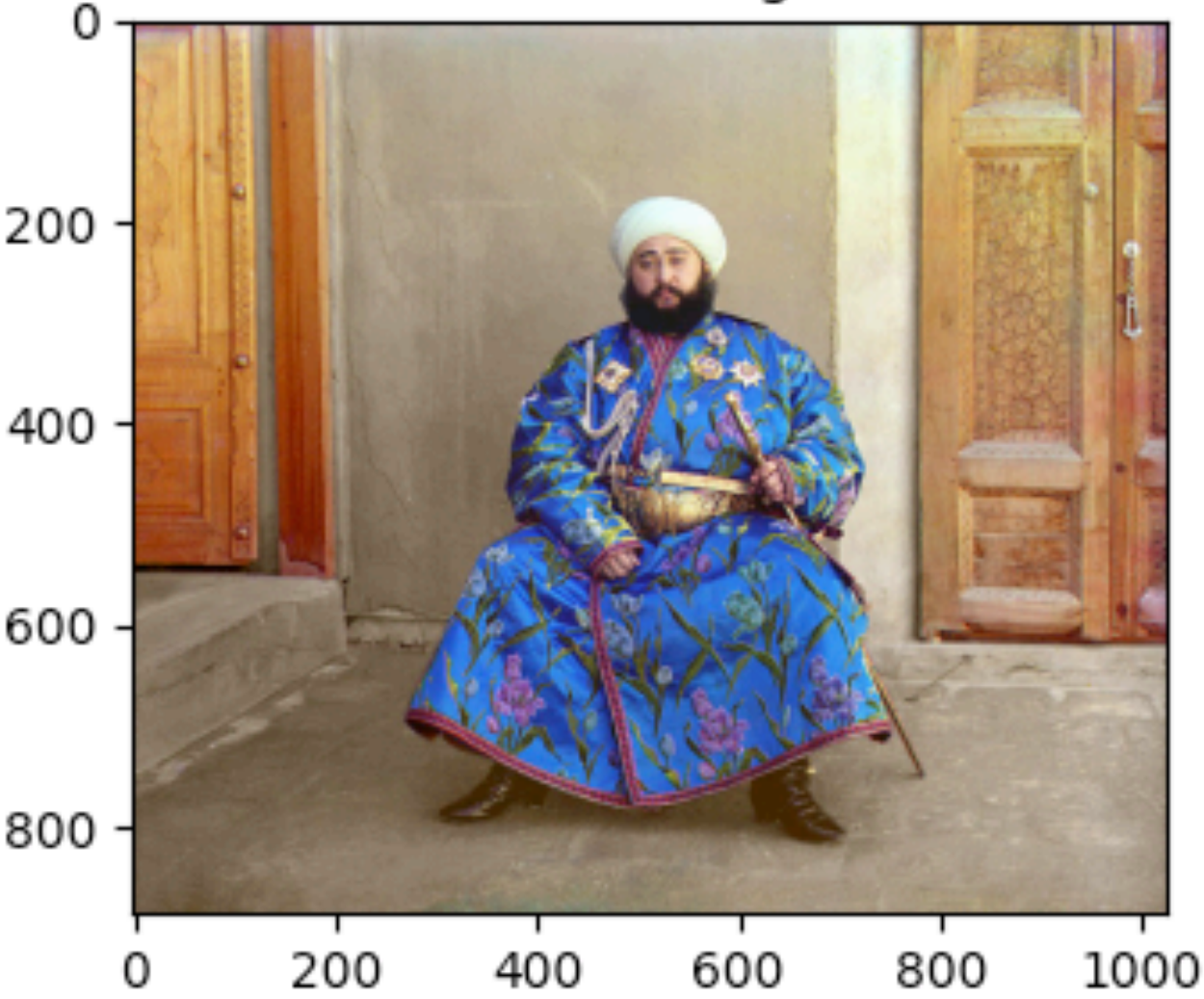
green

$$d(\mathbf{p}, \mathbf{q}) = d(\mathbf{q}, \mathbf{p}) = \sqrt{(q_1 - p_1)^2 + (q_2 - p_2)^2 + \cdots + (q_n - p_n)^2}$$

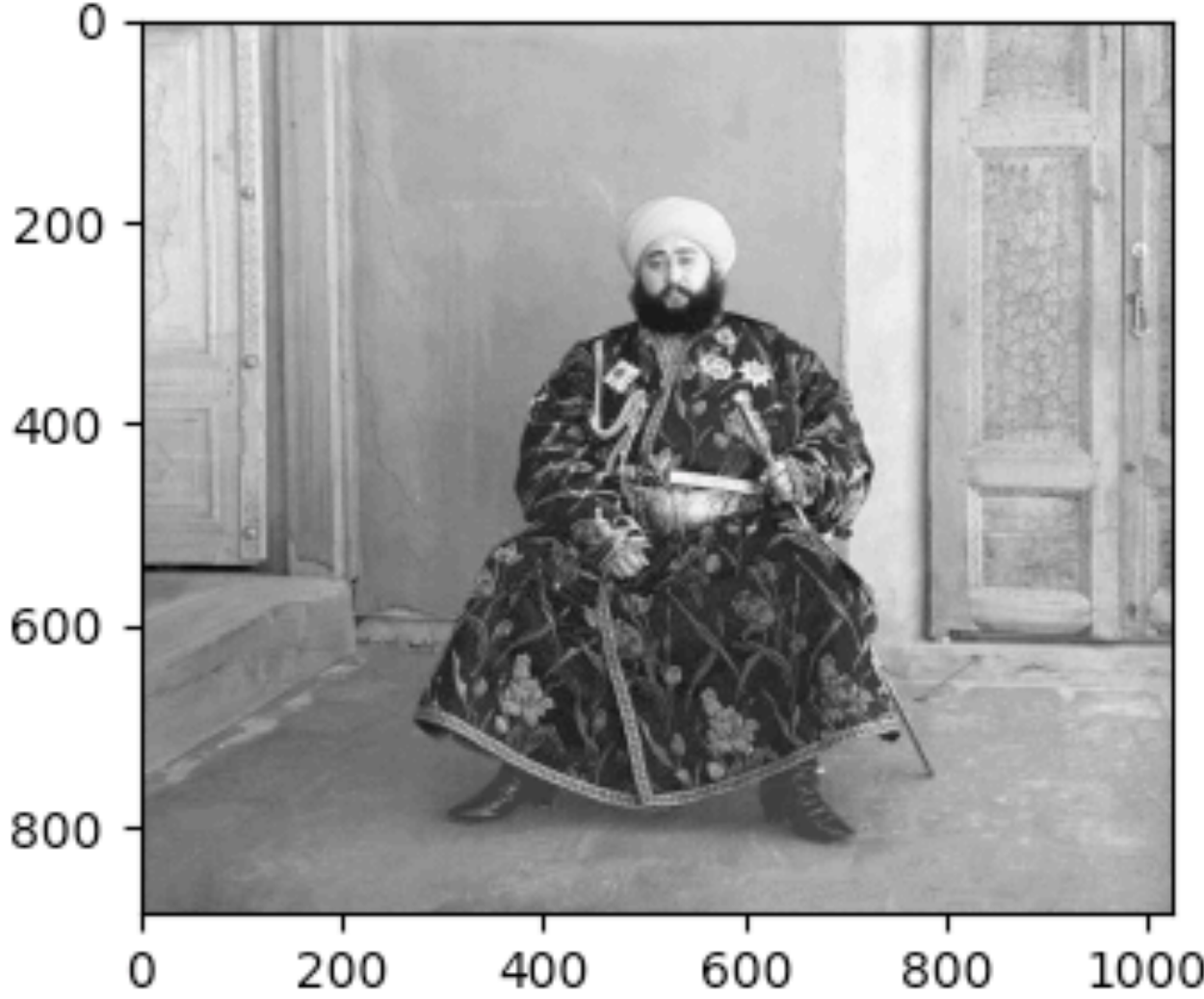


# Why does it work?

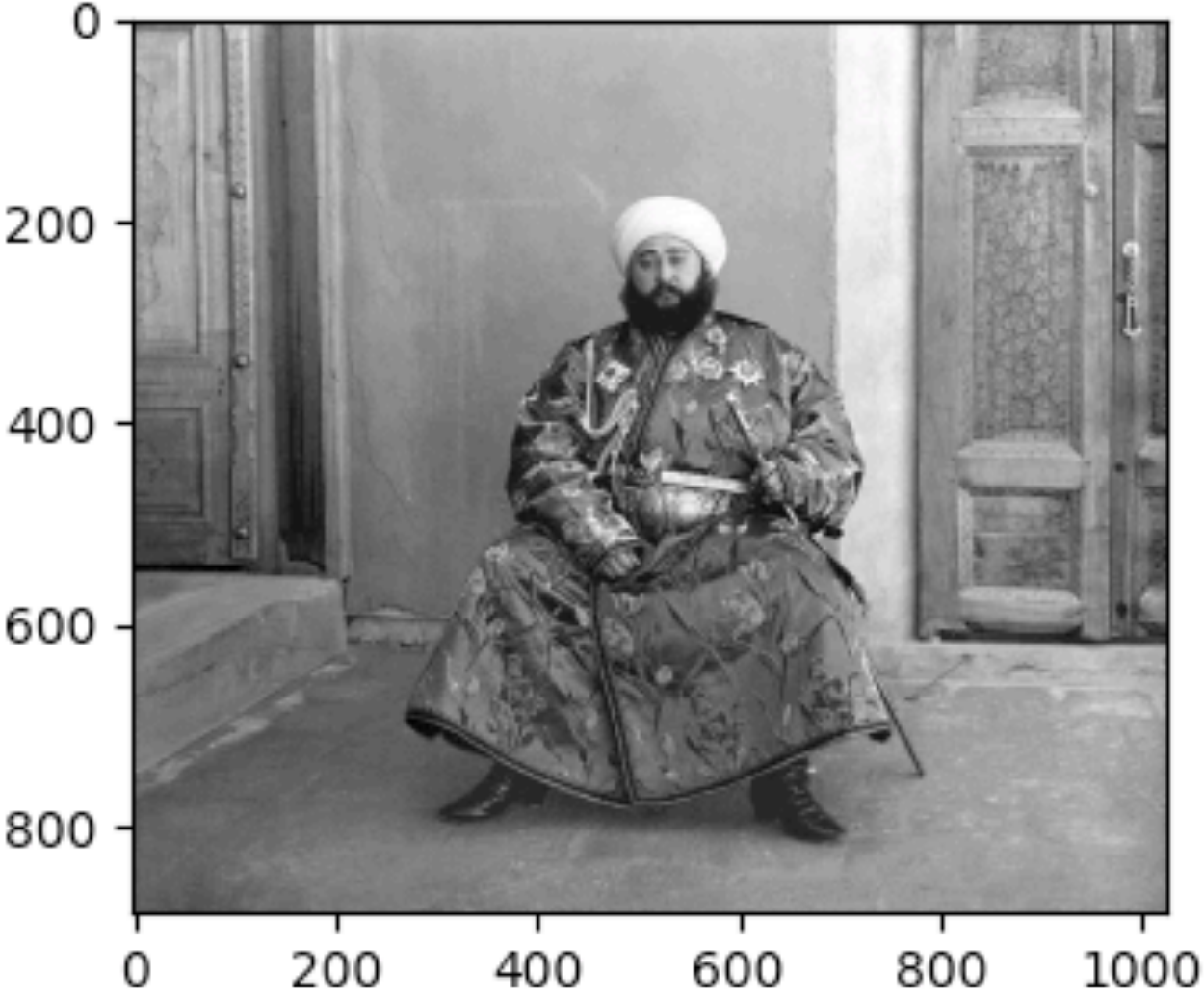
Color image



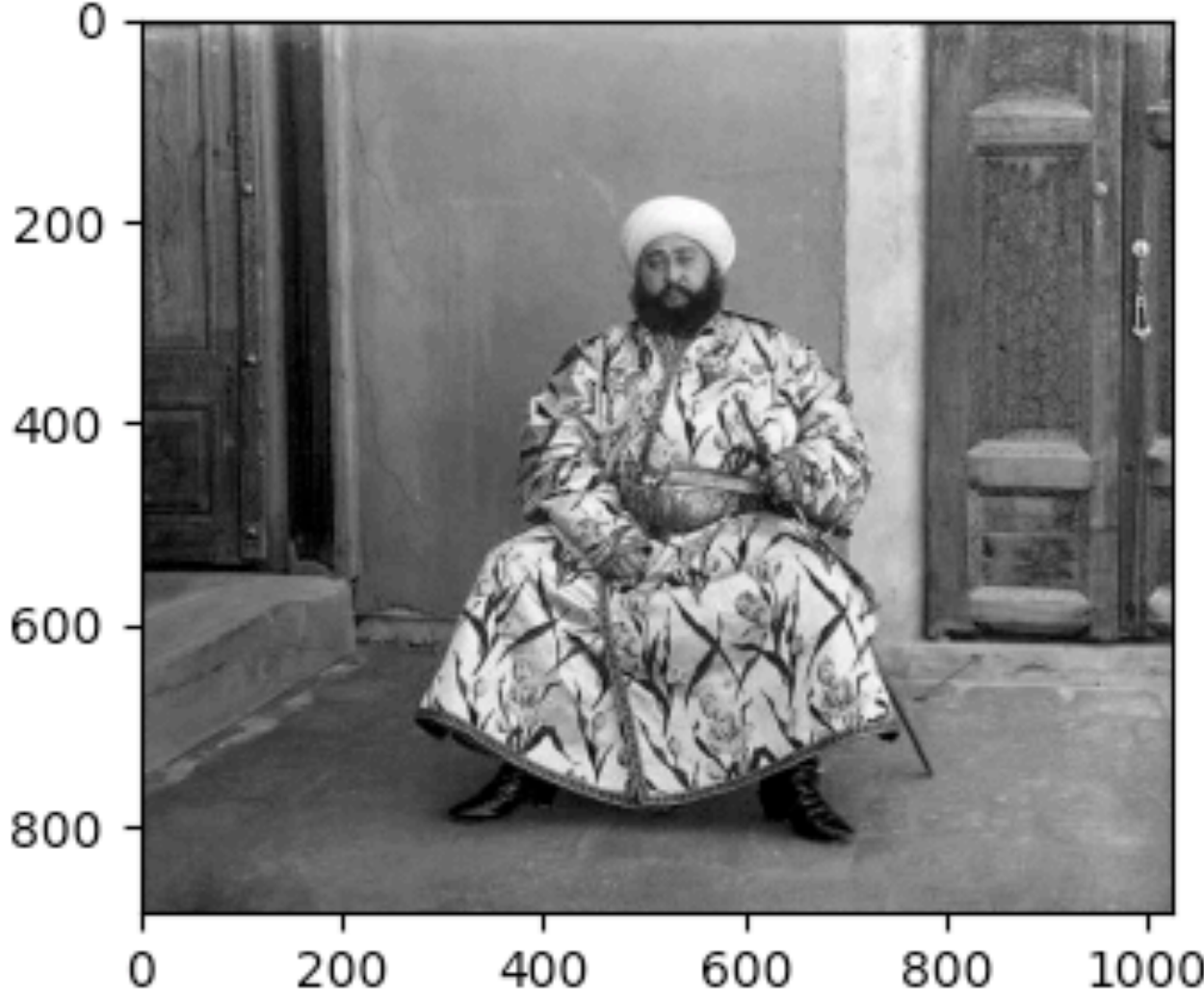
Red channel



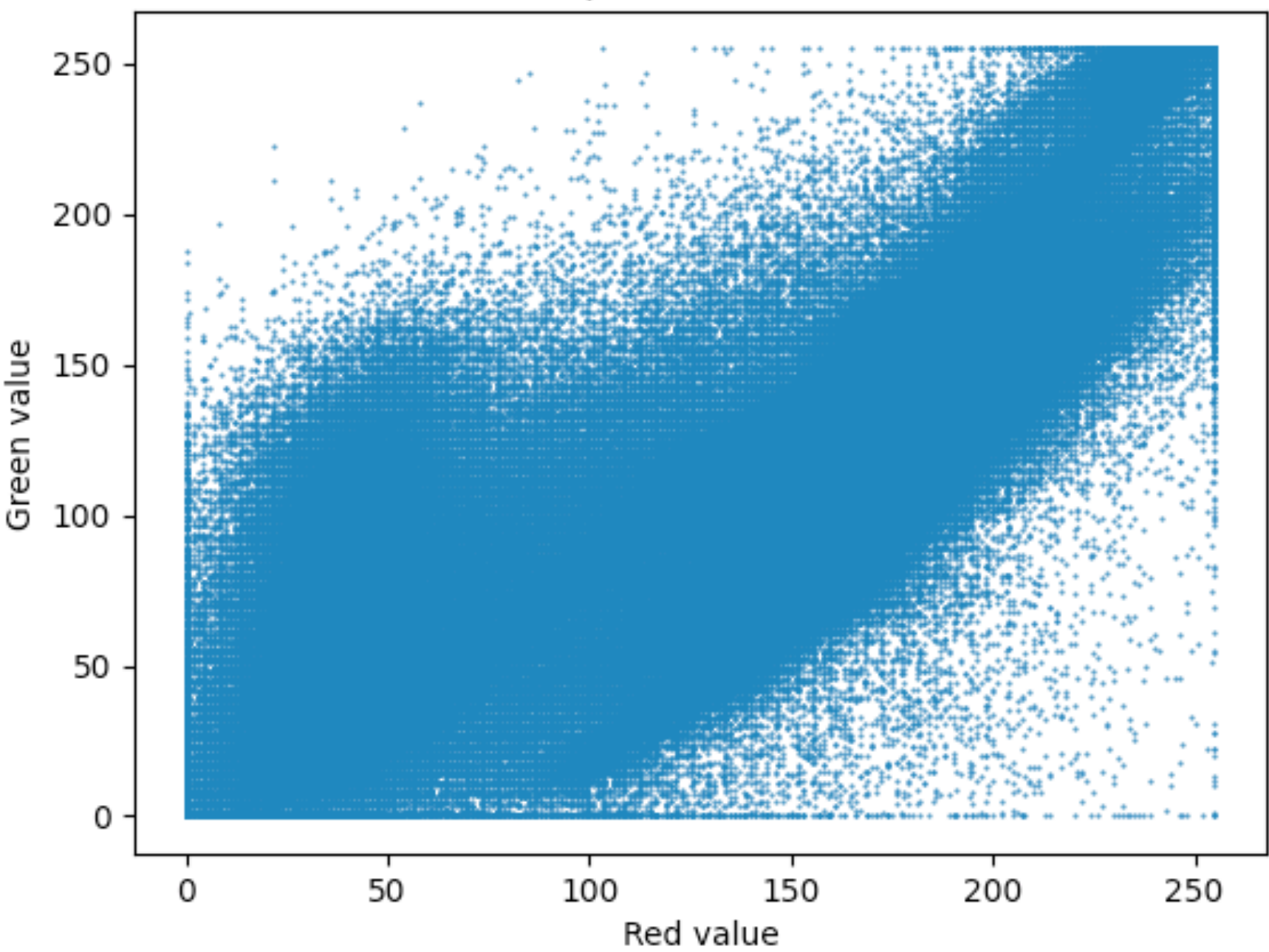
Green channel



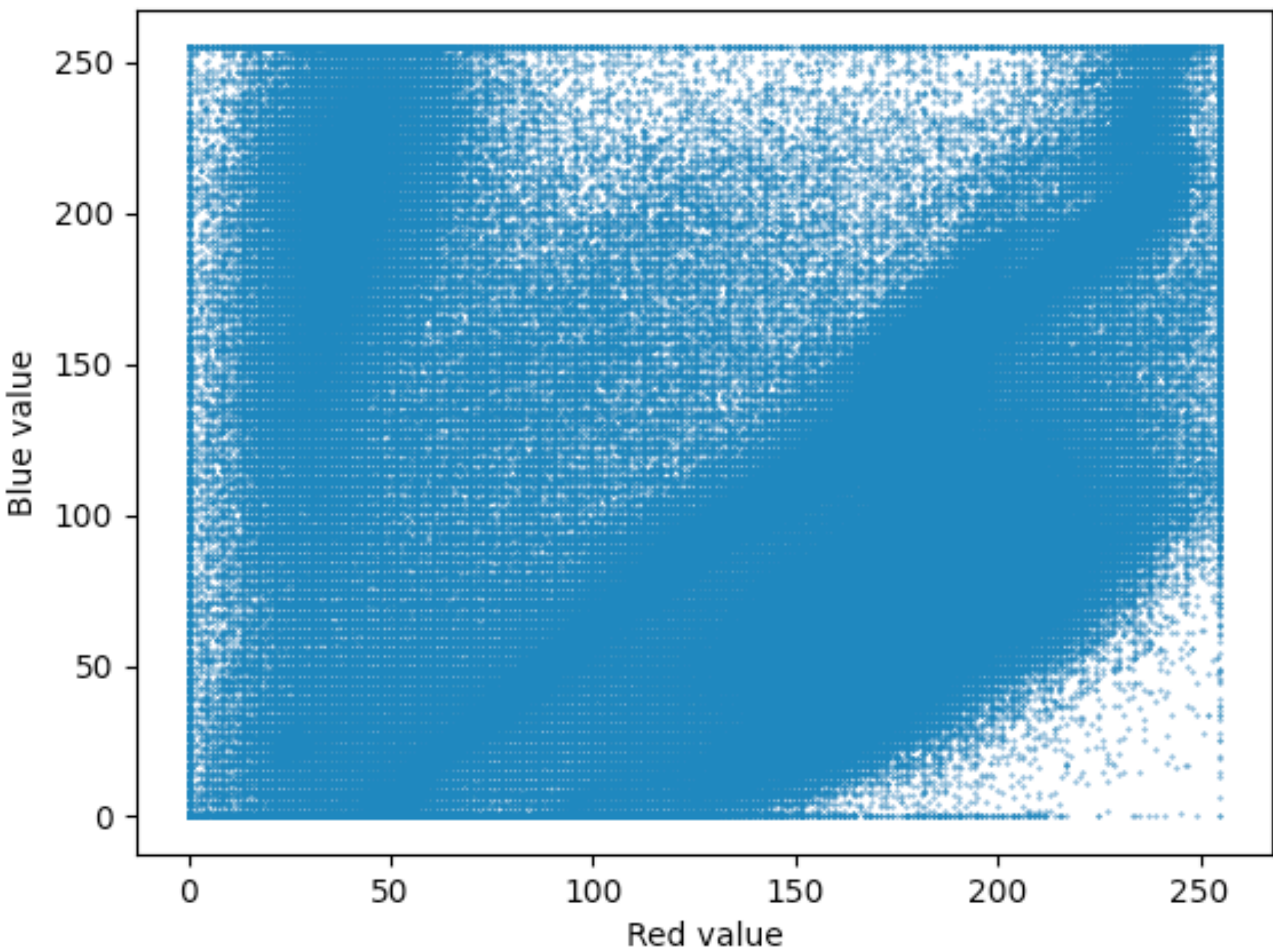
Blue channel



Scatter plot [Red vs. Green]



Scatter plot [Red vs. Blue]

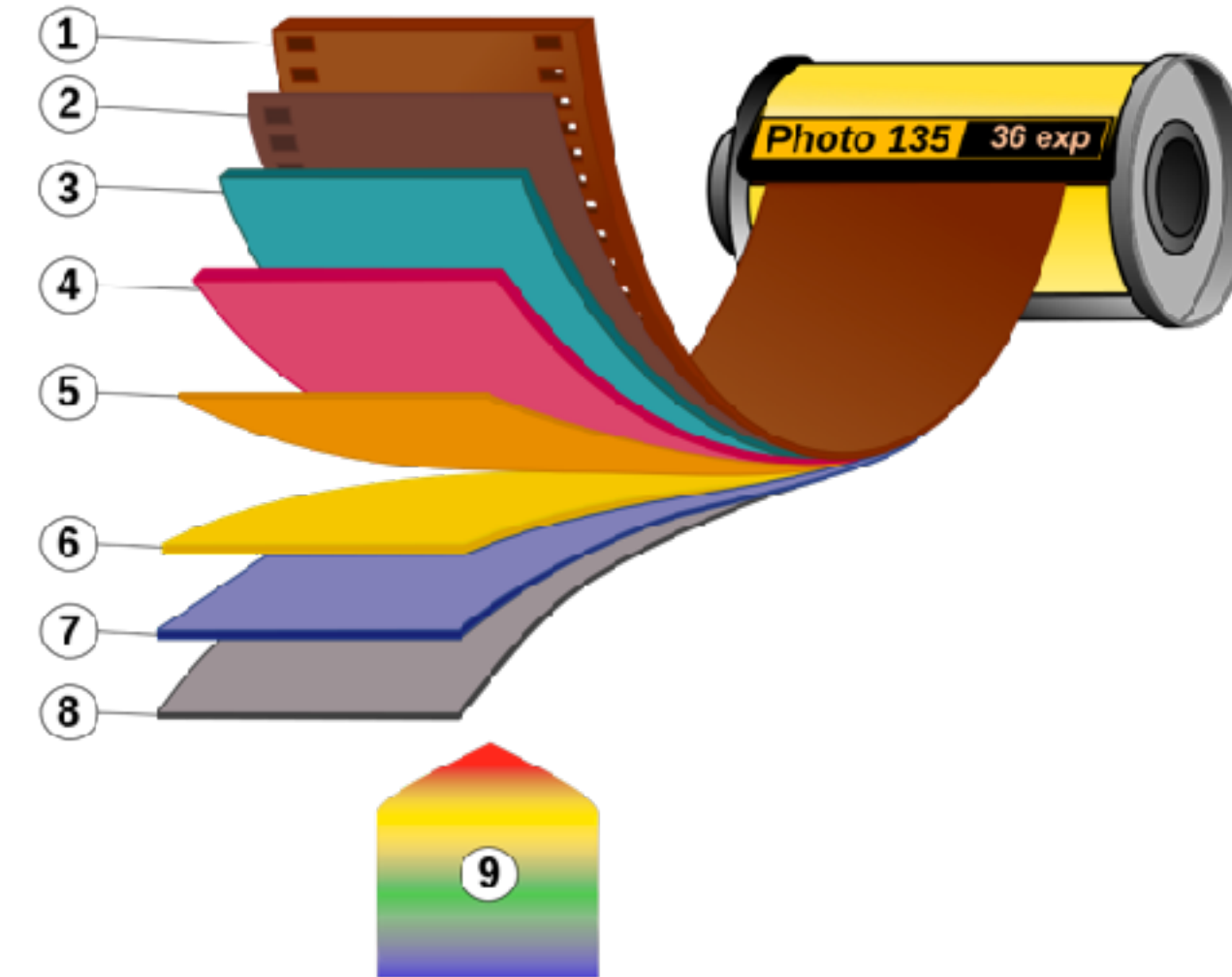




# Measuring light: color films

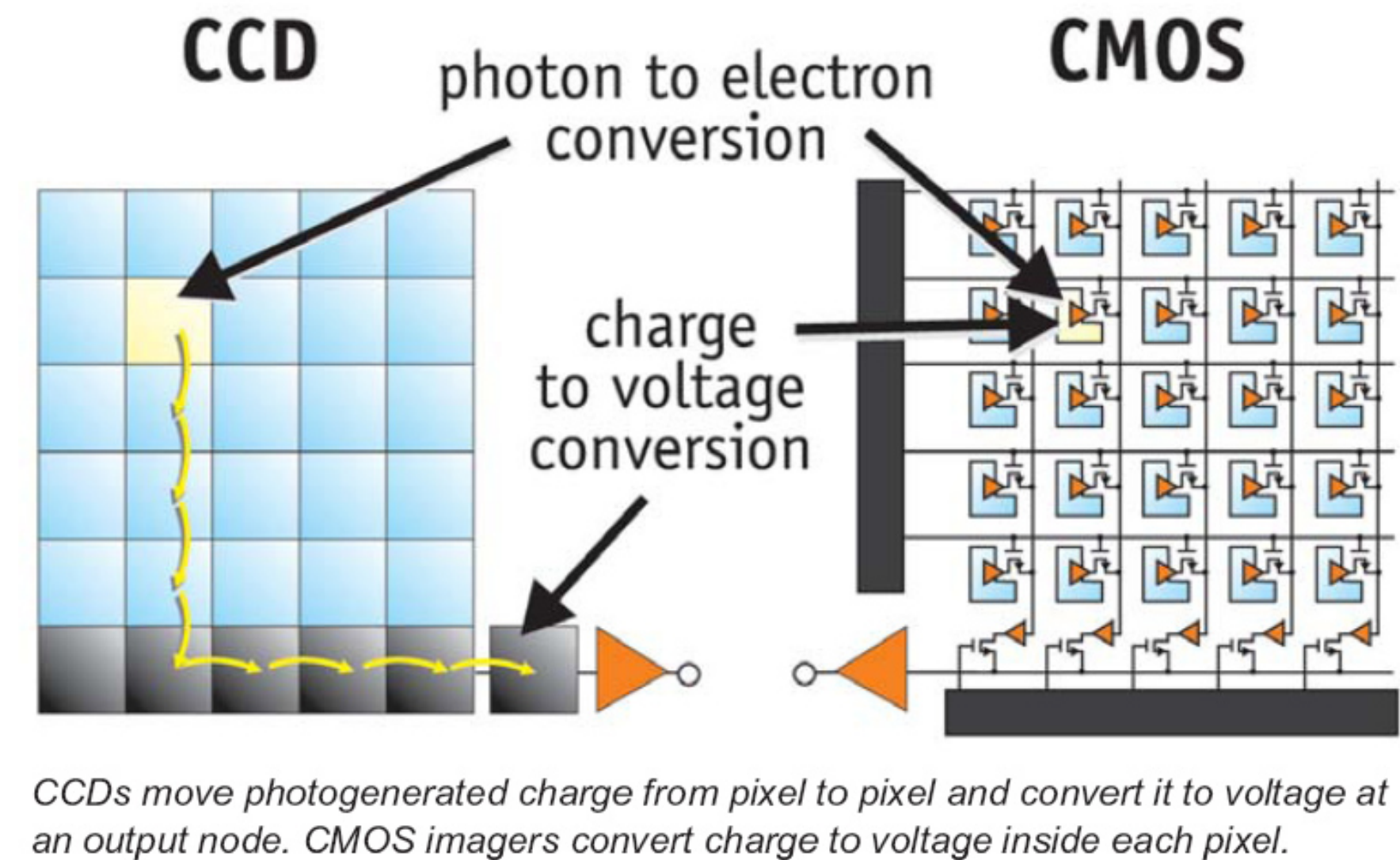
Color photographic film — many layers of dyes and light sensitive materials to capture light of different frequencies simultaneously

- Solves the alignment problem!
- But needs complex film design and development process
- Kodak pioneered color films for making paper prints





# Digital camera



A digital camera replaces the film with a sensor array

- Each cell in the array is a light-sensitive diode that converts photons to electrons
- Two common types of sensor arrays
  - Charge Coupled Device (CCD)
  - Complementary Metal Oxide Semiconductor (CMOS)

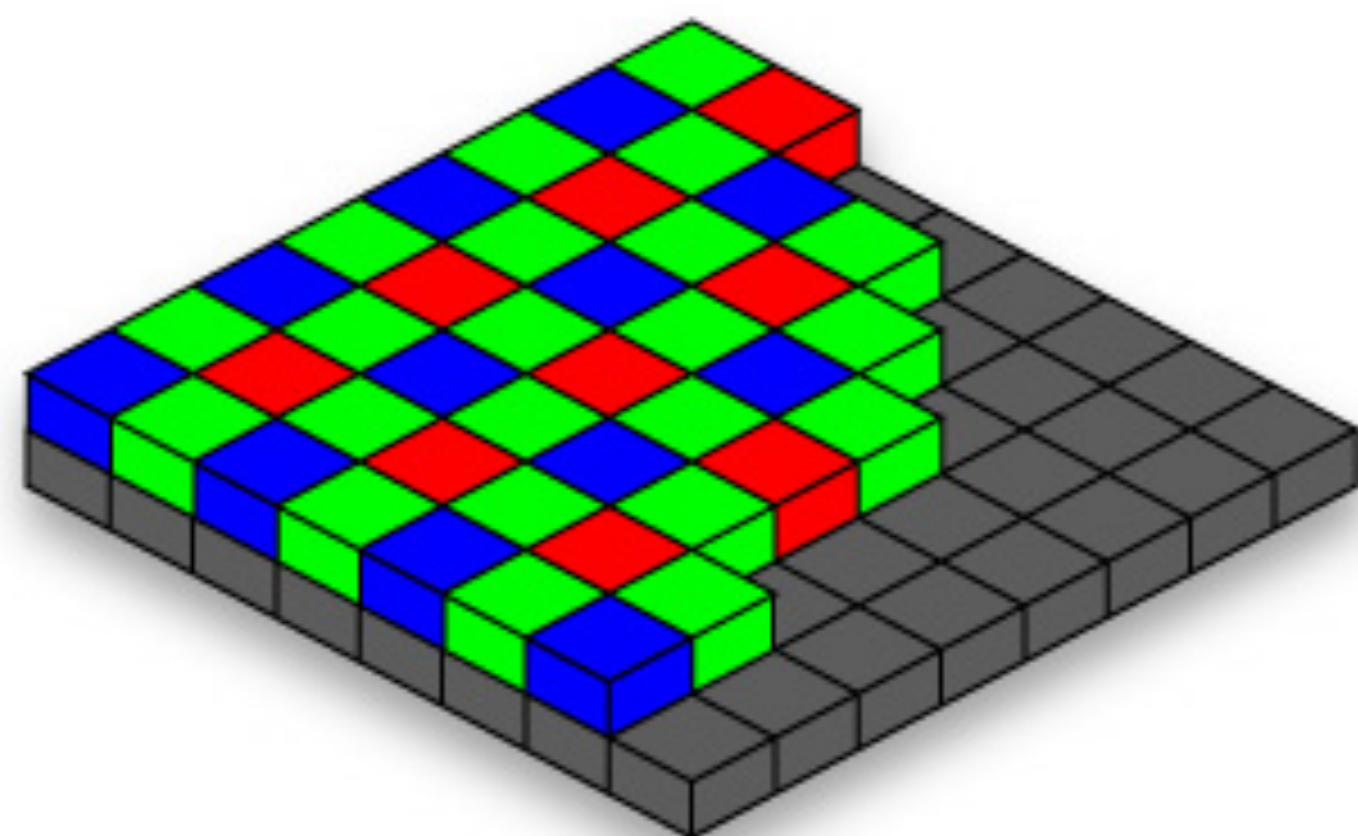
<http://electronics.howstuffworks.com/digital-camera.htm>



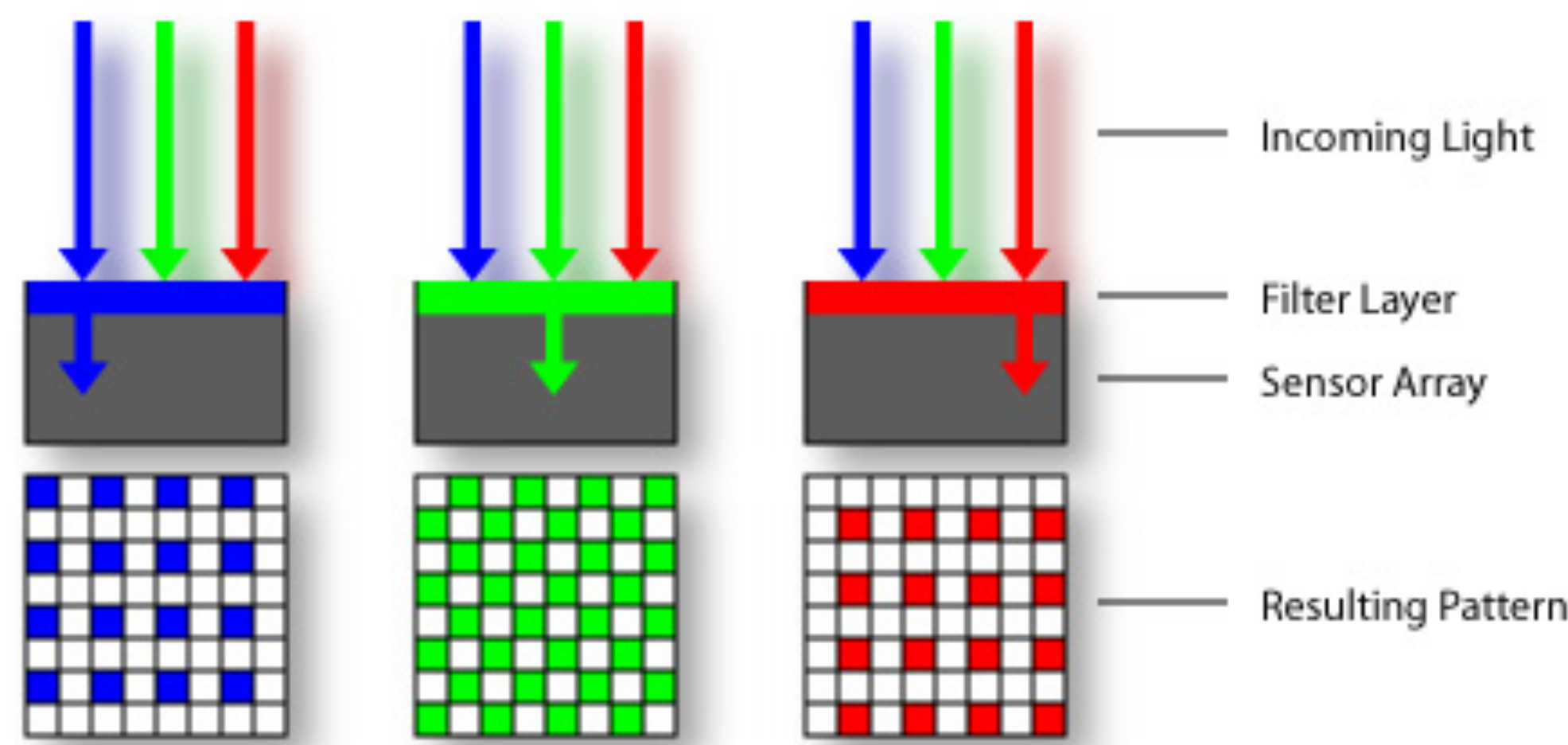
# Color sensing in the camera

Color filter array

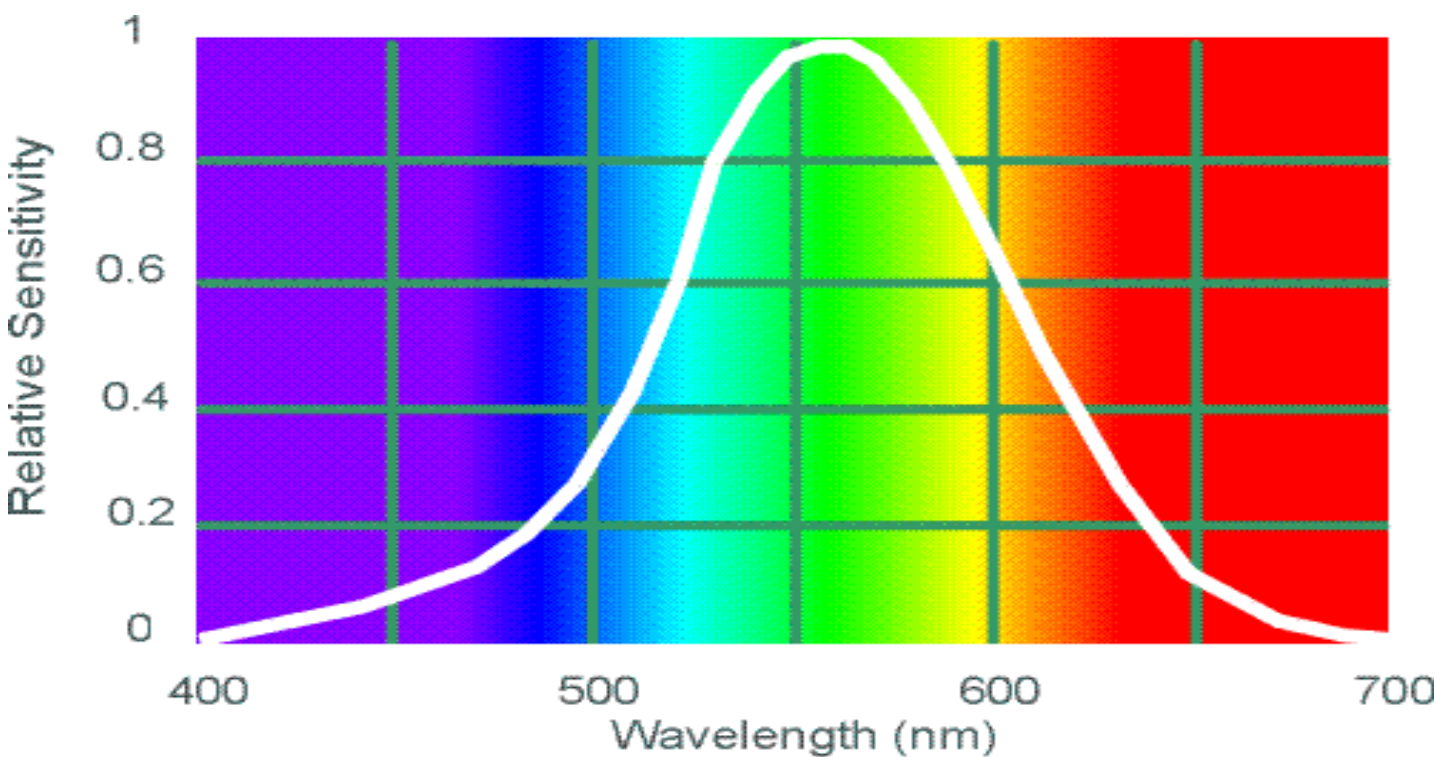
Bayer grid



Estimate missing components from neighboring values  
(**demosaicing**)



Why more green?



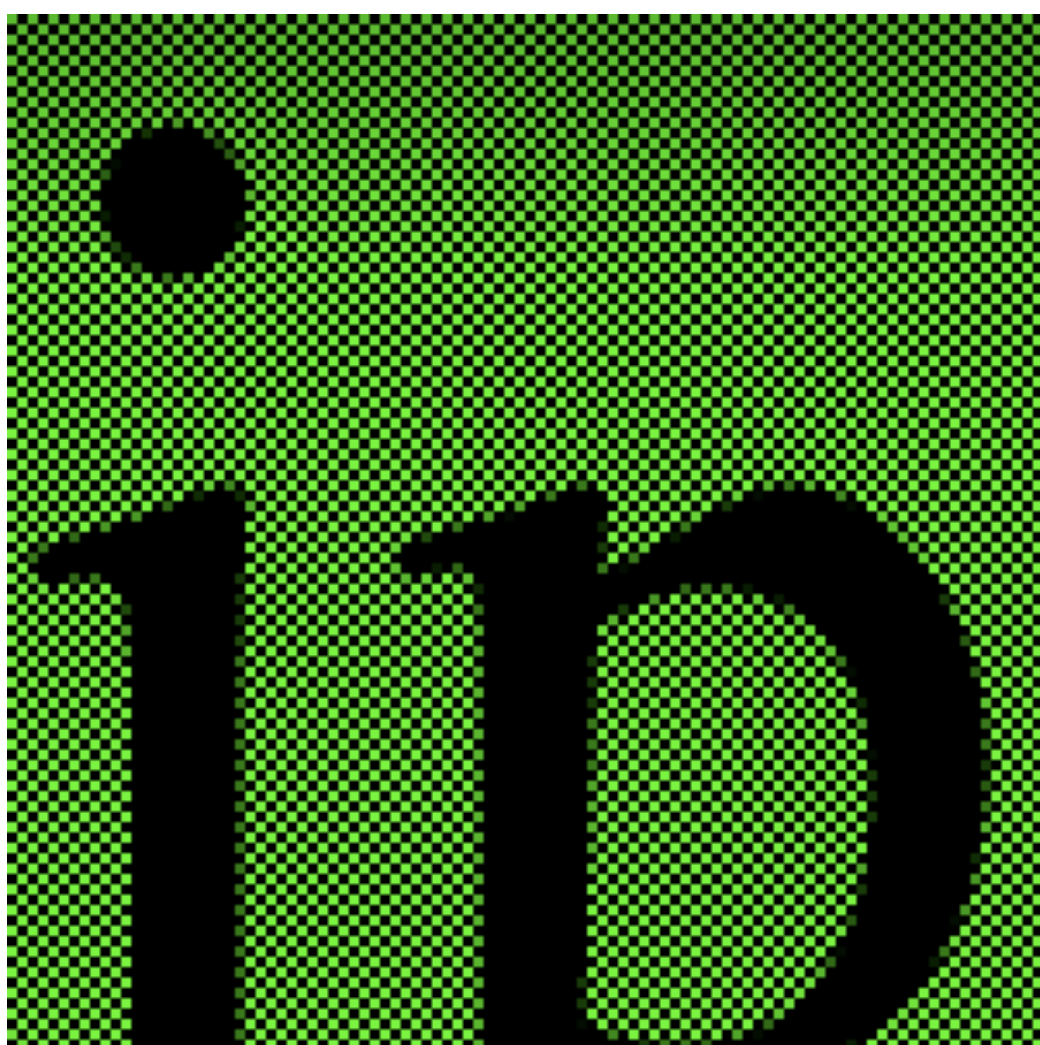
Human luminance sensitivity function



# What is captured? — a moscaiced image



Red



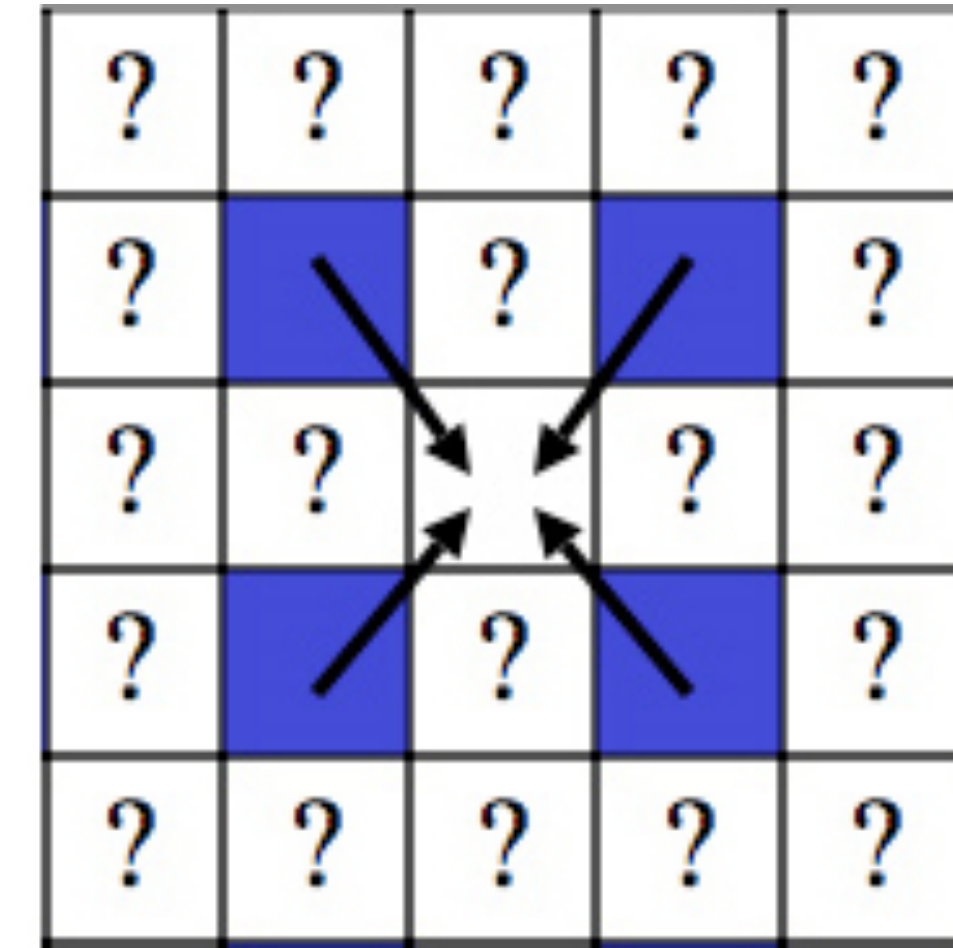
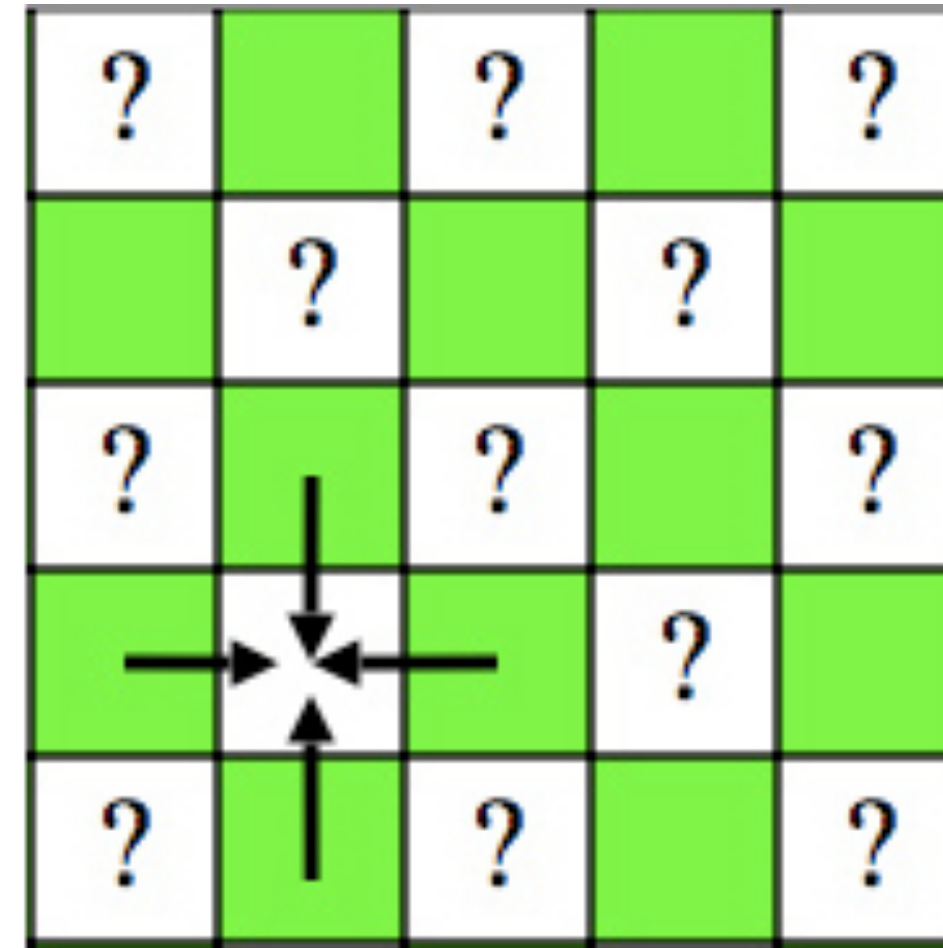
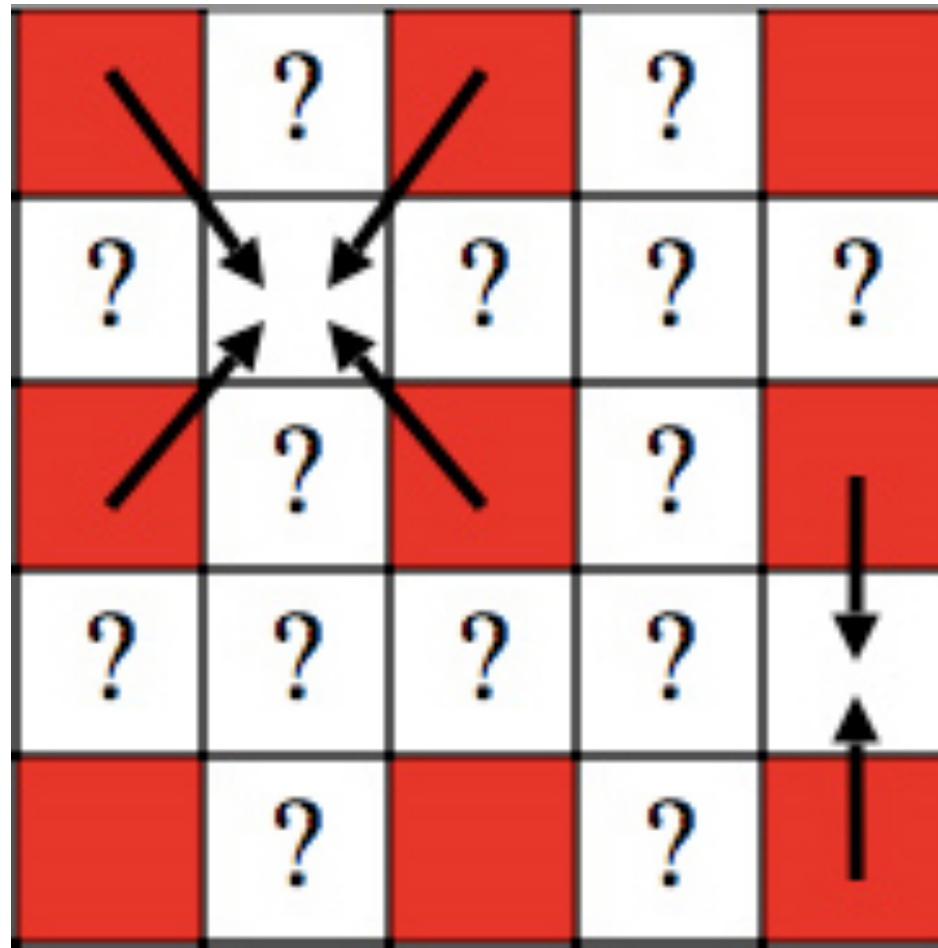
Green



Blue



# Demosaicing — interpolating the missing values



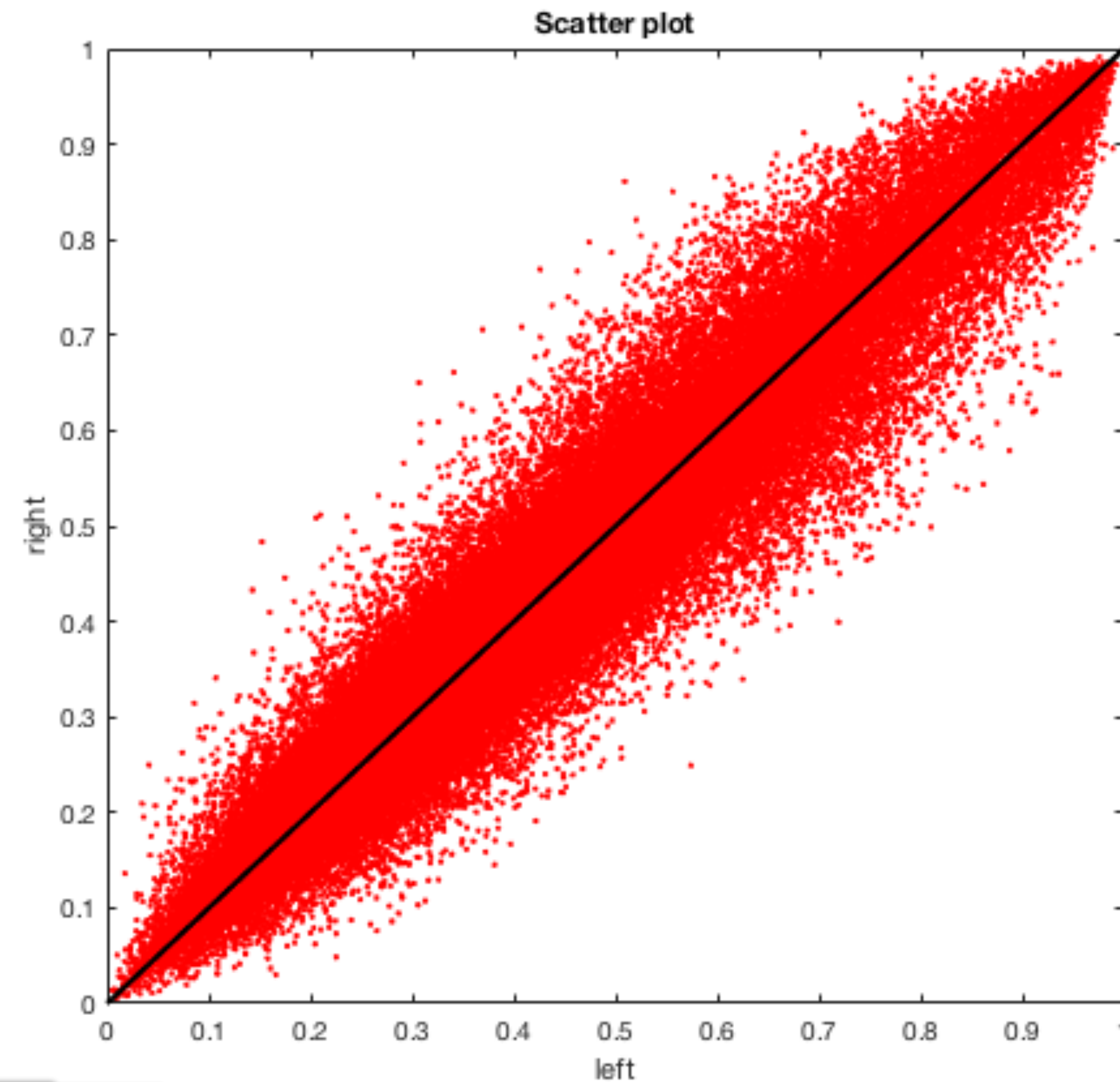
**Problem:** guess the values of missing pixels in each of the three channels

How?



# Why is this possible?

Adjacent pixel values are strongly correlated



left

right

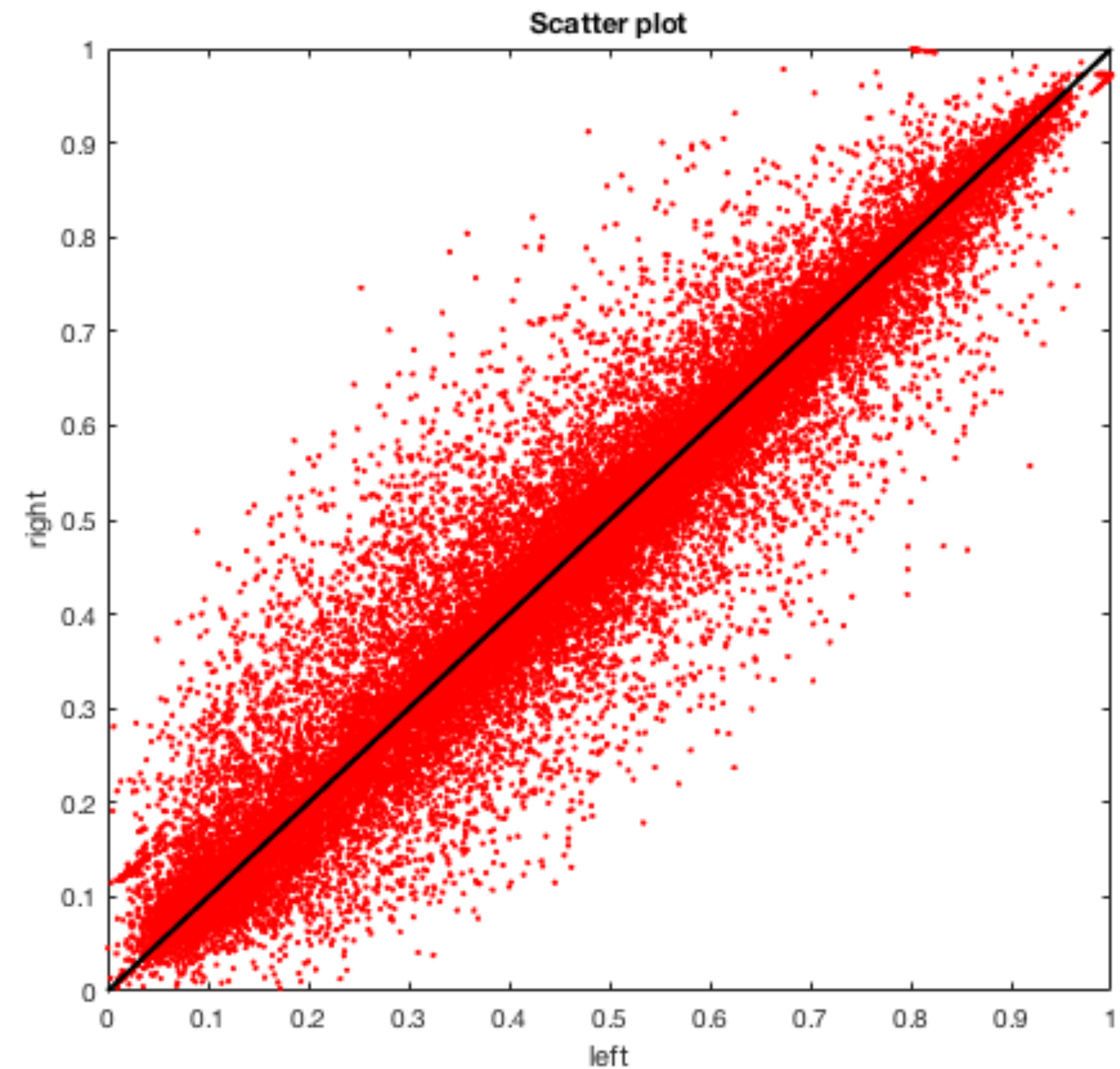


# Why is this possible?

Adjacent pixel values are strongly correlated



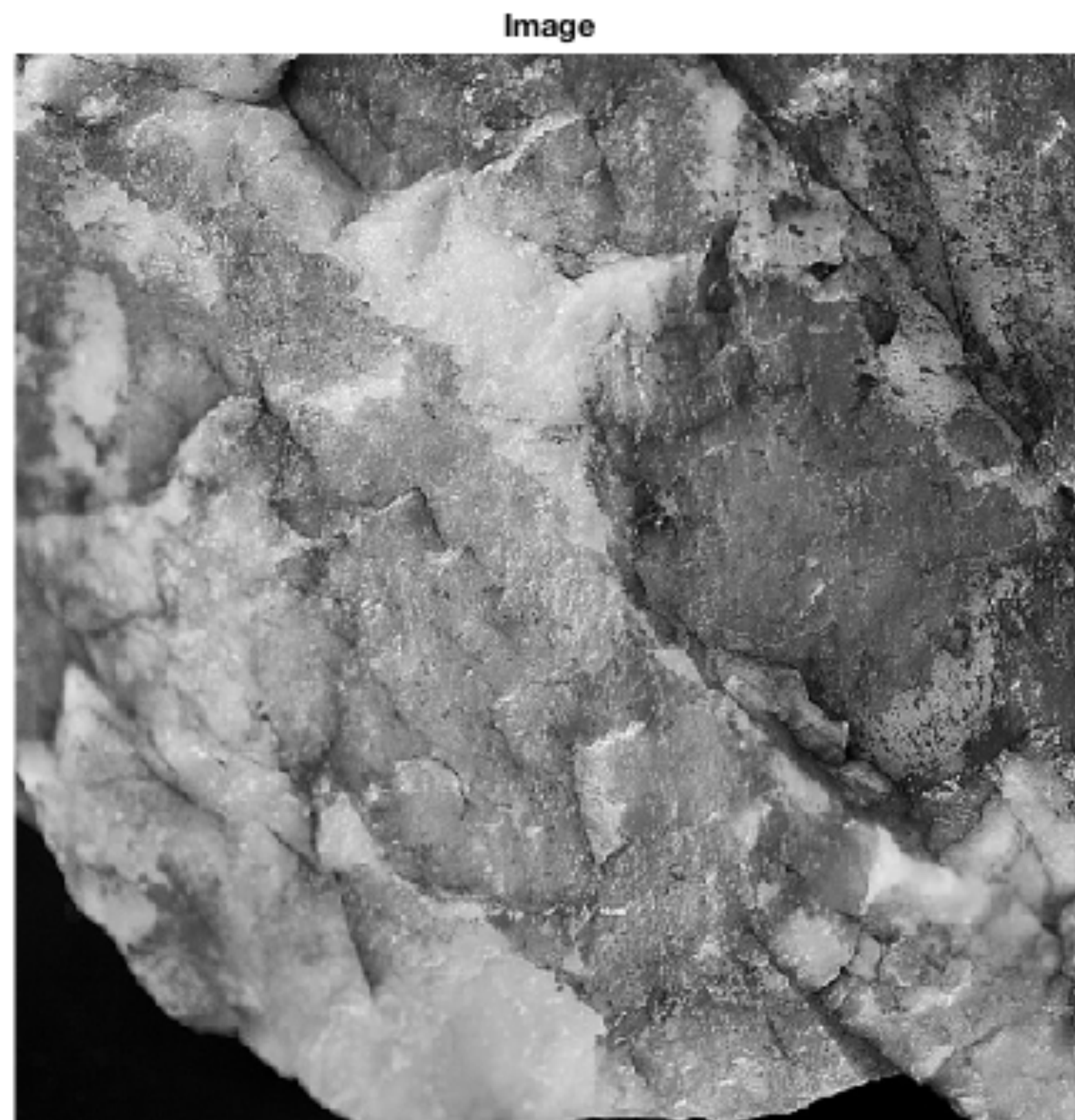
left right



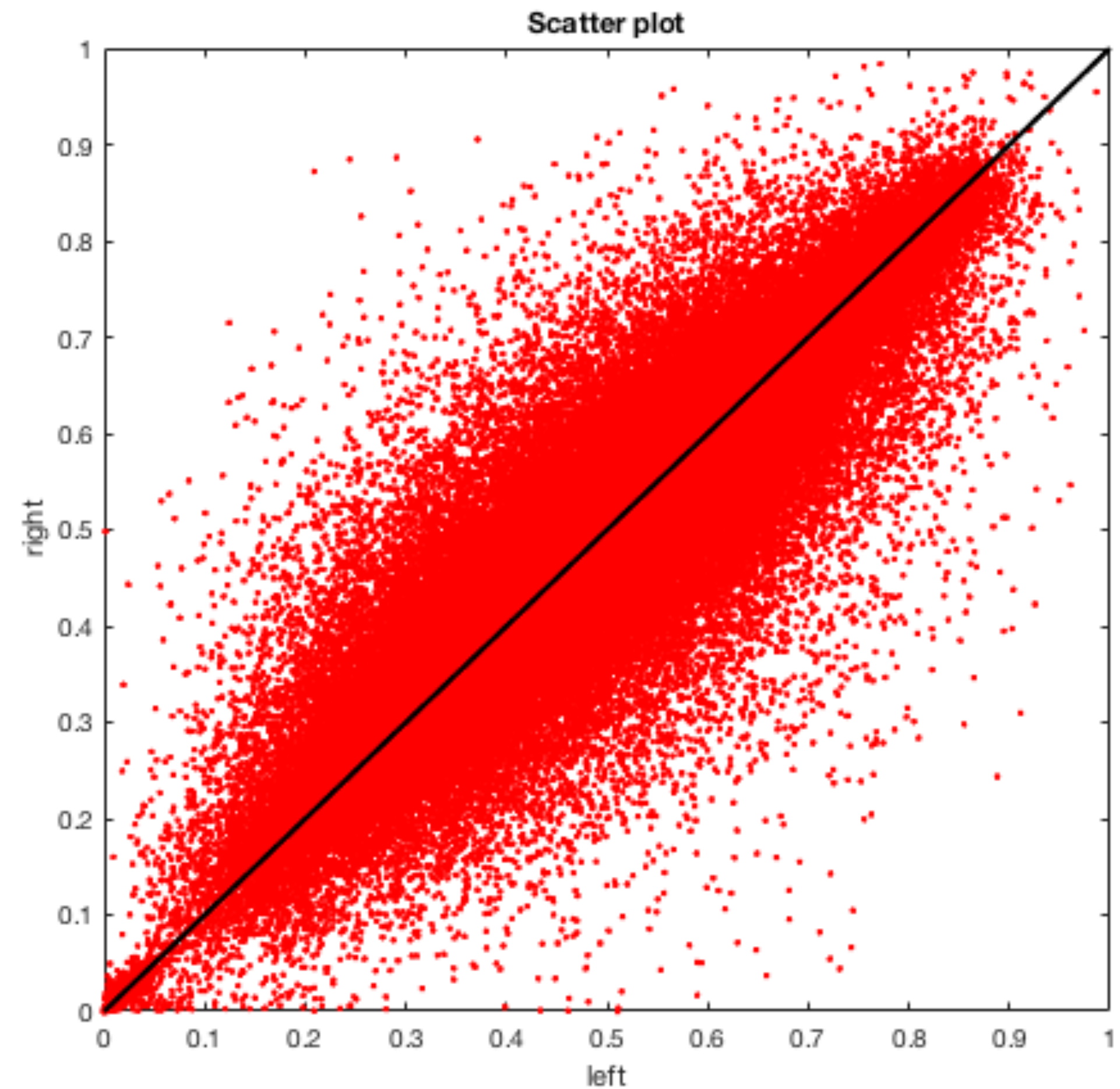


# Why is this possible?

Adjacent pixel values are strongly correlated

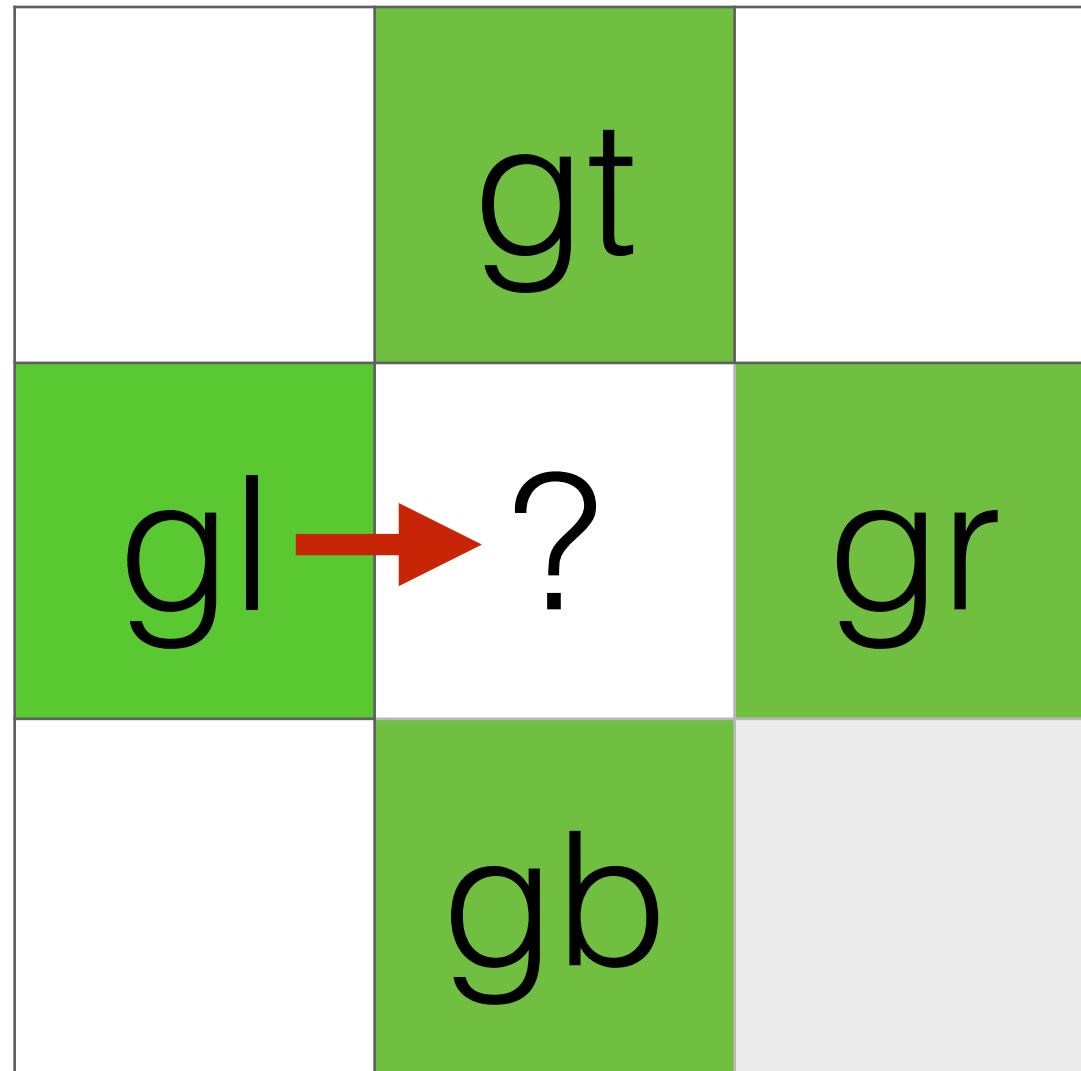


left right





# Interpolation



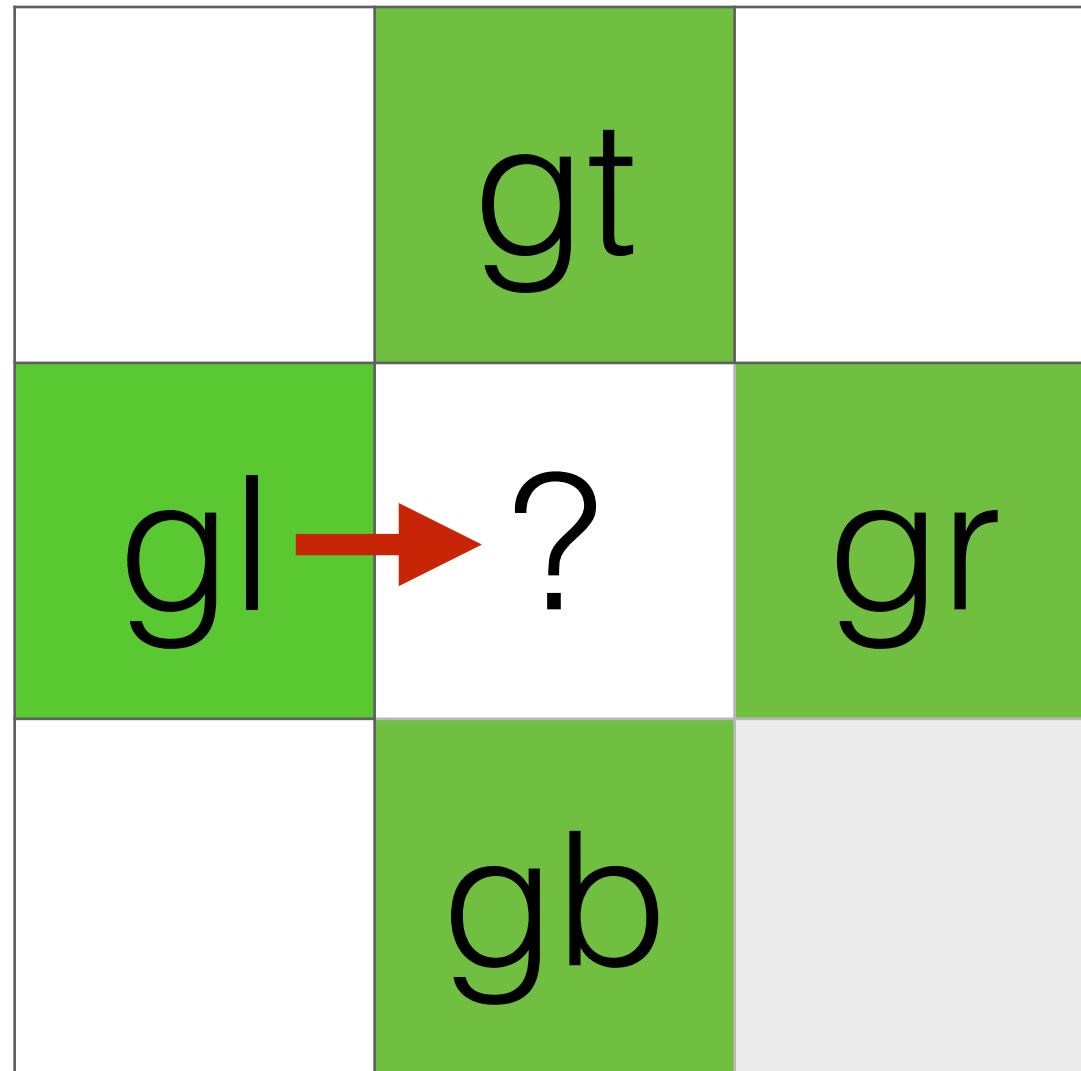
**nearest neighbor**

copy one of your  
neighbors

? ← gl



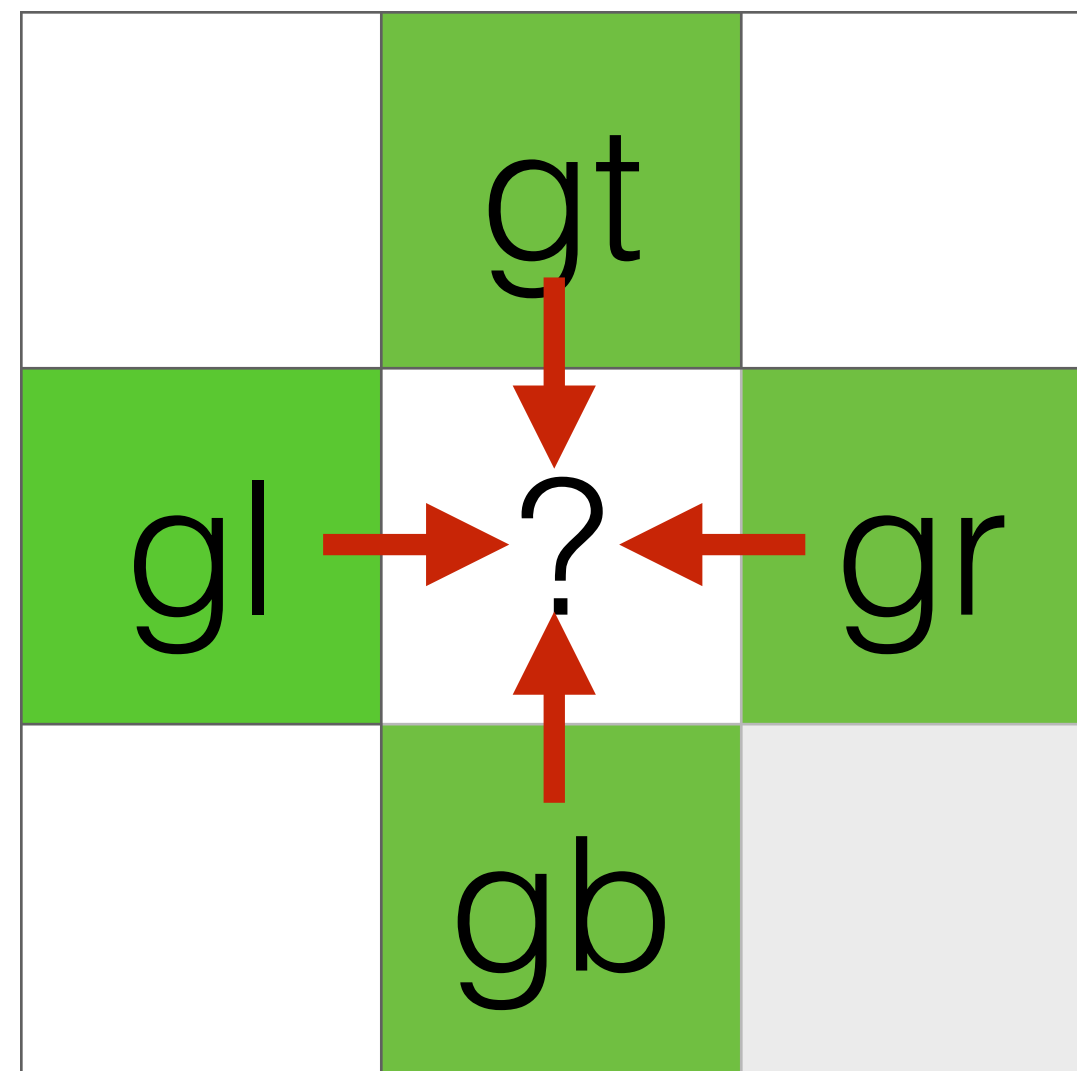
# Interpolation



## nearest neighbor

copy one of your  
neighbors

?  $\leftarrow$  gl



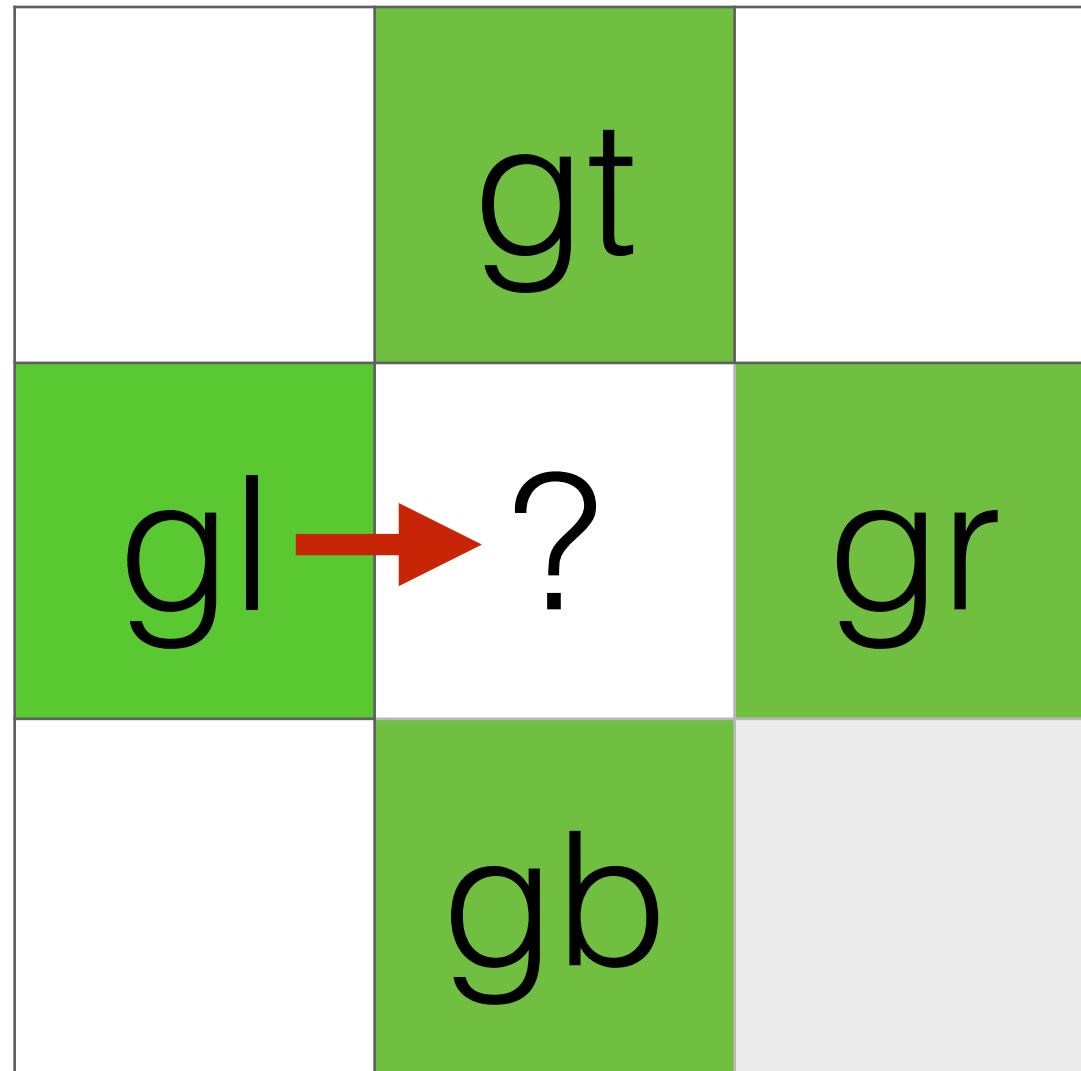
## linear interpolation

average values of  
your neighbors

?  $\leftarrow (gt+gl+gr+gb)/4$



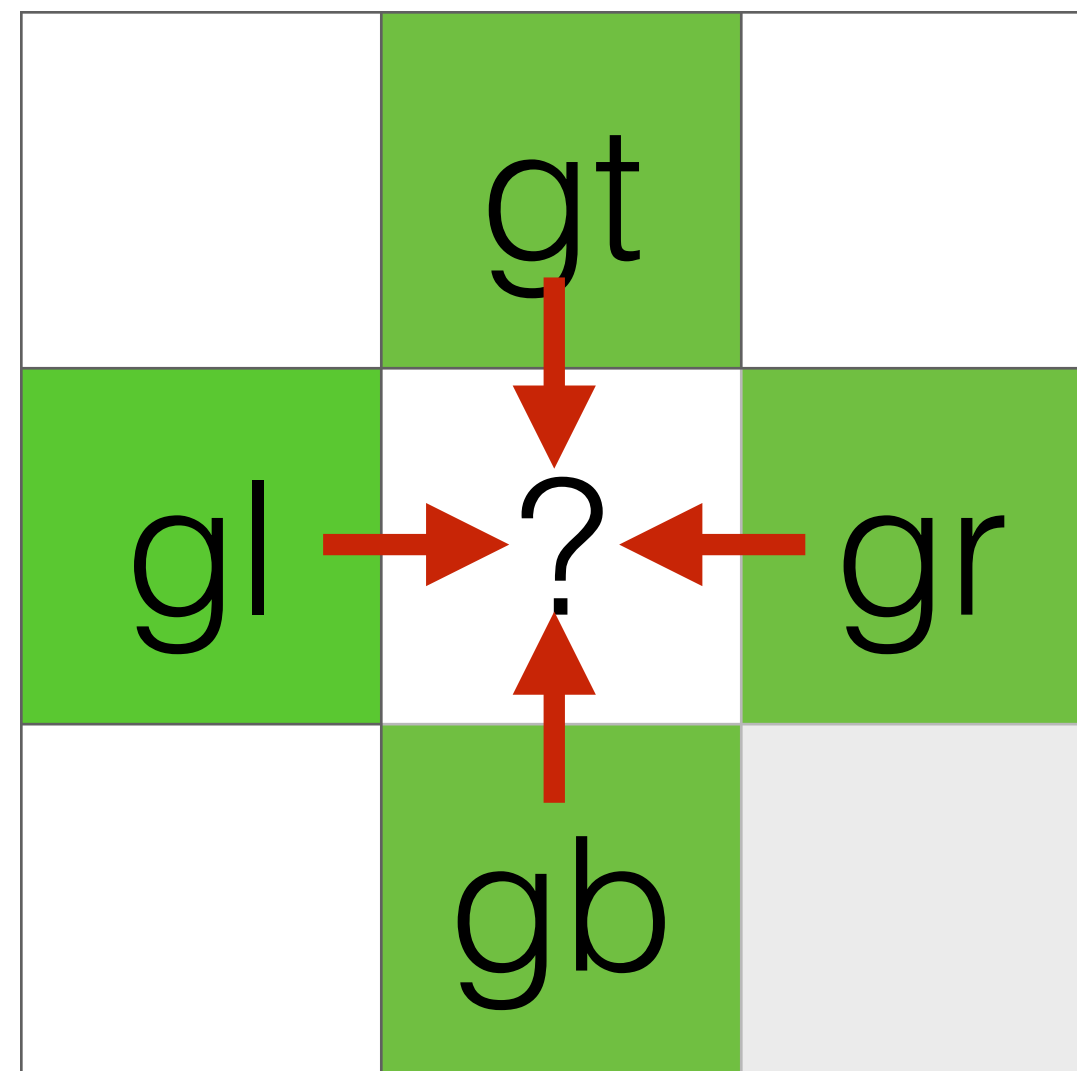
# Interpolation



## nearest neighbor

copy one of your neighbors

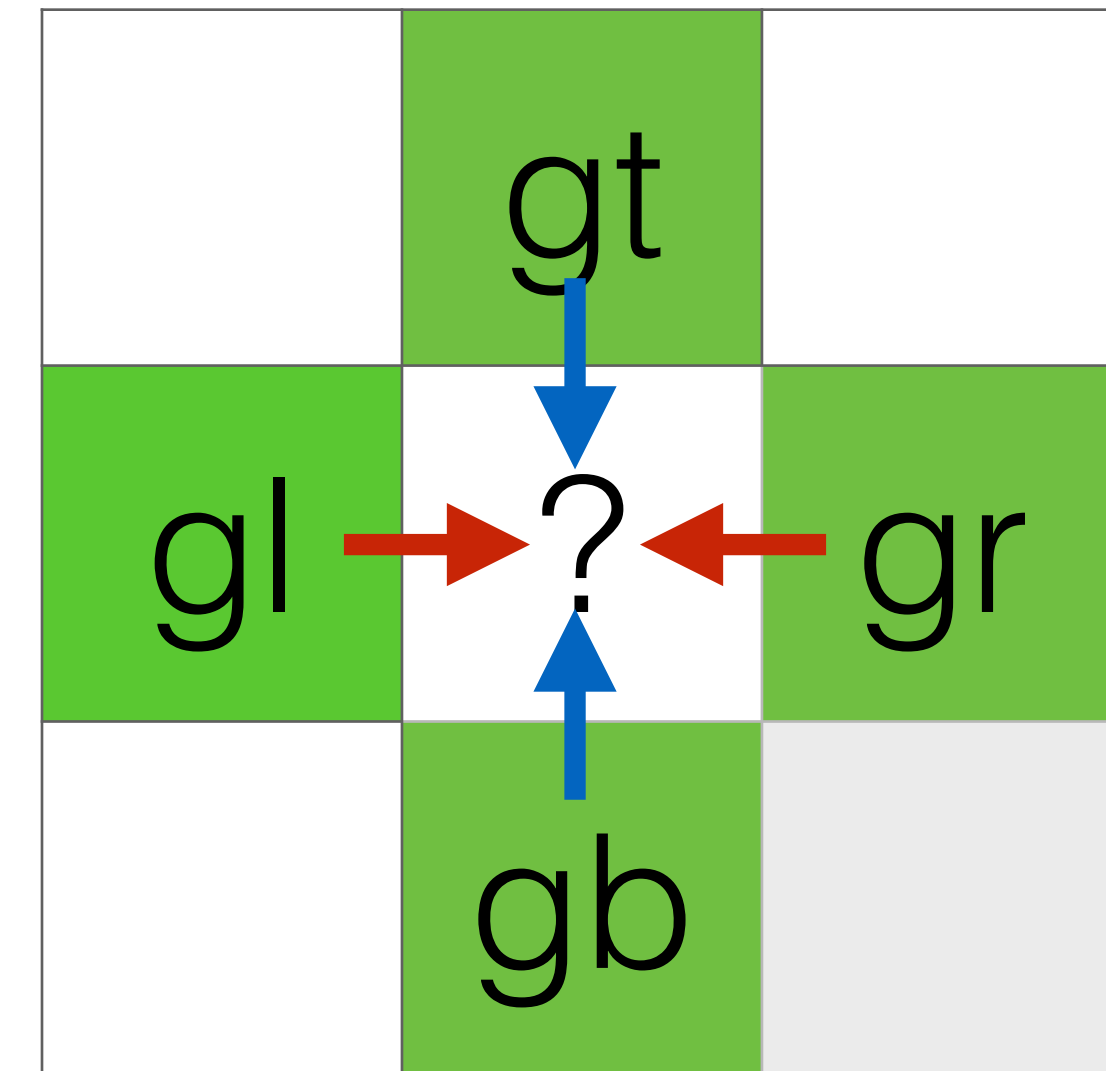
$$? \leftarrow gl$$



## linear interpolation

average values of your neighbors

$$? \leftarrow (gt+gl+gr+gb)/4$$



## adaptive gradient

average based on nbhd. structure

*if*  $|gt-gb| > |gl-gr|$

$$? \leftarrow (gl+gr)/2$$

*else*

$$? \leftarrow (gt+gb)/2$$

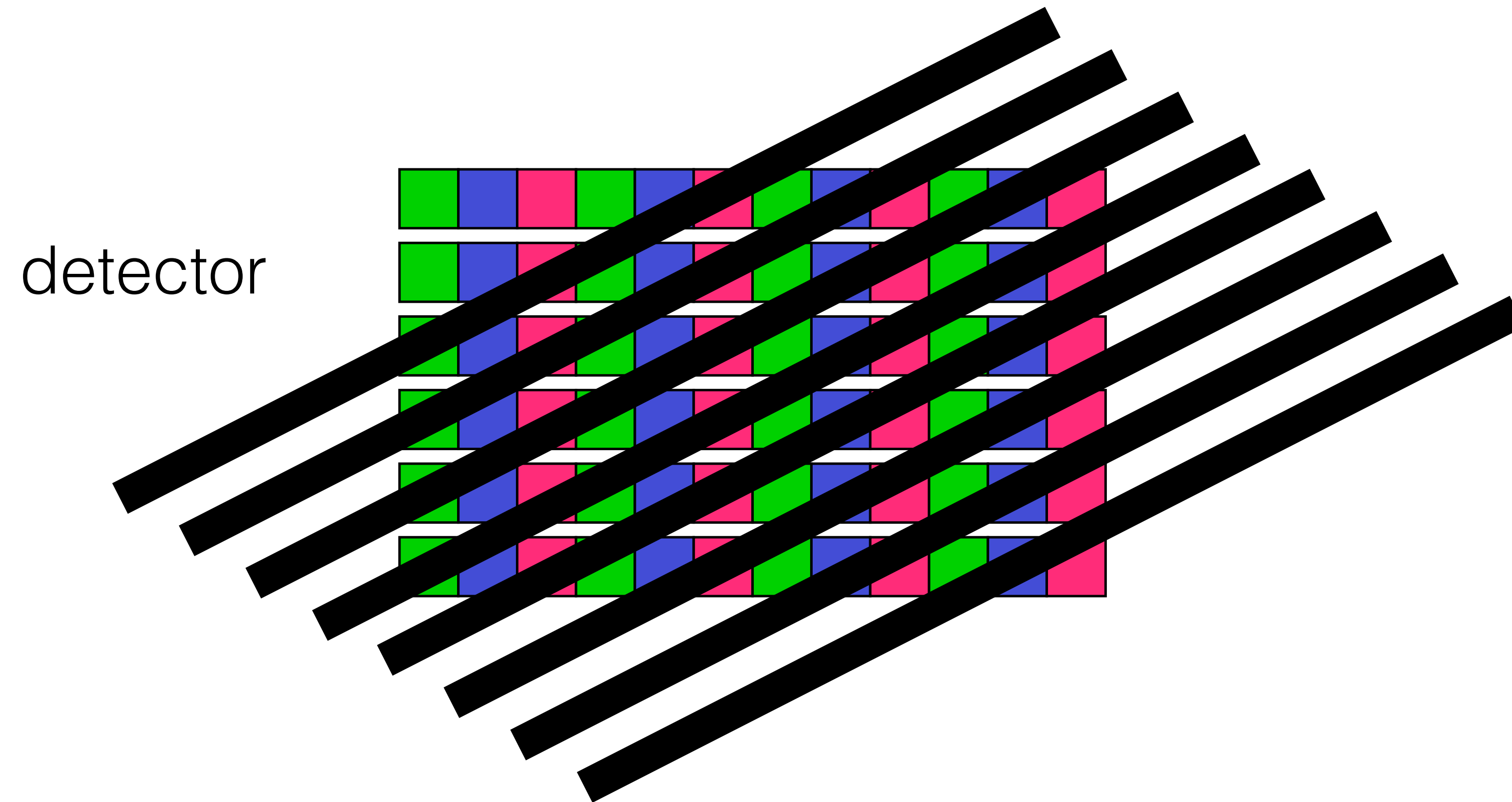


# Problem: color moiré





# The cause of color moiré



Fine black and white detail in the image scene  
is misinterpreted as color information